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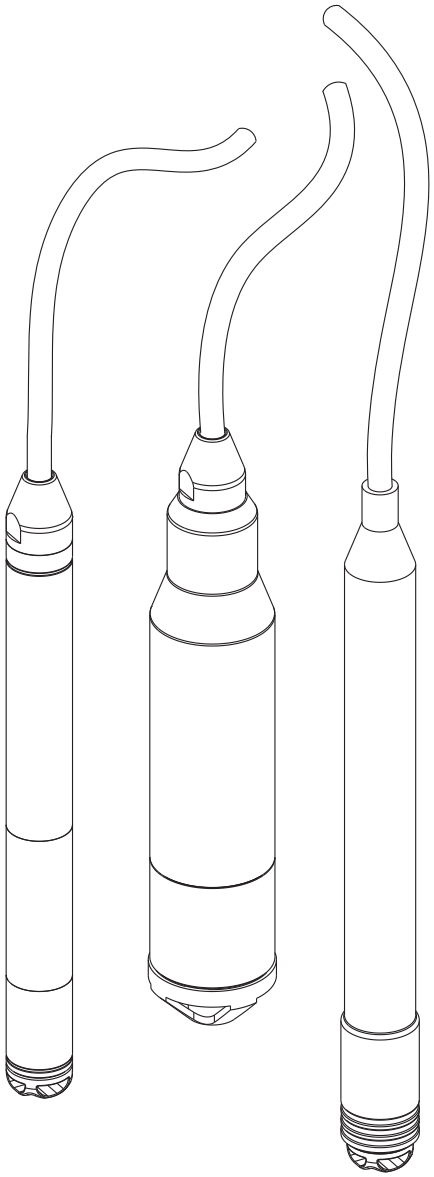
01.00.zz

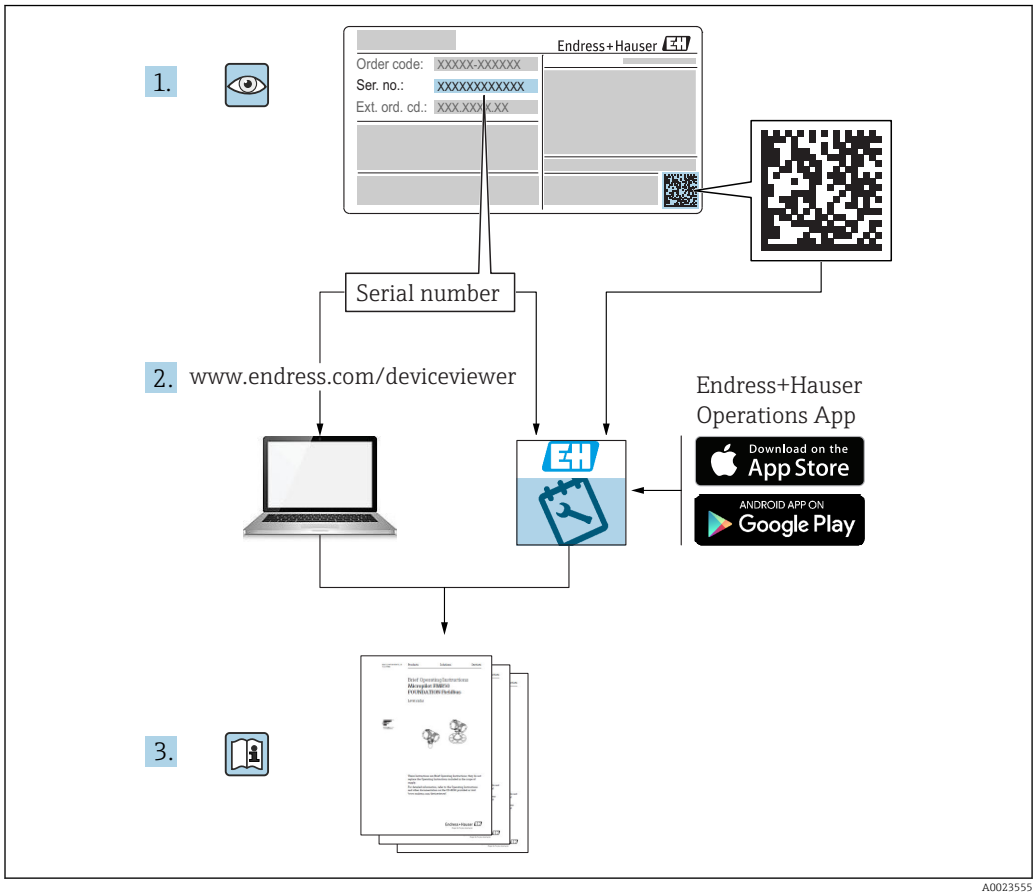
Operating Instructions
Waterpilot FMX21

Hydrostatic level measurement
4 to 20 mA HART

HART COMMUNICATION PROTOCOL



Endress+Hauser
People for Process Automation



- Make sure the document is stored in a safe place such that it is always available when working on or with the device.
- To avoid danger to individuals or the facility, read the "Basic safety instructions" section carefully, as well as all other safety instructions in the document that are specific to working procedures.
- The manufacturer reserves the right to modify technical data without prior notice. Your Endress+Hauser distributor will supply you with current information and updates to these Instructions.

Table of contents

1 About this document

1.1 Document function

These Operating Instructions contain all the information that is required in various phases of the life cycle of the device: from product identification, incoming acceptance and storage, to mounting, connection, operation and commissioning through to troubleshooting, maintenance and disposal.

1.2 Symbols used

1.2.1 Safety symbols

Symbol	Meaning
DANGER	**DANGER!** This symbol alerts you to a dangerous situation. Failure to avoid this situation will result in serious or fatal injury.
WARNING	**WARNING!** This symbol alerts you to a dangerous situation. Failure to avoid this situation can result in serious or fatal injury.
CAUTION	**CAUTION!** This symbol alerts you to a dangerous situation. Failure to avoid this situation can result in minor or medium injury.
NOTICE	**NOTE!** This symbol contains information on procedures and other facts which do not result in personal injury.

1.2.2 Electrical symbols

Symbol	Meaning	Symbol	Meaning
⎓	Direct current	~	Alternating current
⎓ ~	Direct current and alternating current	⏚	**Ground connection** A grounded terminal which, as far as the operator is concerned, is grounded via a grounding system.
⏚	**Protective ground connection** A terminal which must be connected to ground prior to establishing any other connections.	⏚	**Equipotential connection** A connection that has to be connected to the plant grounding system: This may be a potential equalization line or a star grounding system depending on national or company codes of practice.

1.2.3 Tool symbols

Symbol	Meaning
 A0011220	Flat blade screwdriver
 A0011219	Phillips screwdriver

Symbol	Meaning
 A0011221	Allen key
 A0011222	Open-ended wrench

1.2.4 Symbols for certain types of information

Symbol	Meaning
	**Permitted** Procedures, processes or actions that are permitted.
	**Preferred** Procedures, processes or actions that are preferred.
	**Forbidden** Procedures, processes or actions that are forbidden.
	**Tip** Indicates additional information.
	Reference to documentation
	Reference to page
	Reference to graphic
1. , 2. , 3. ...	Series of steps
	Result of a step
	Help in the event of a problem
	Visual inspection

1.2.5 Symbols in graphics

Symbol	Meaning
1, 2, 3 ...	Item numbers
1. , 2. , 3. ...	Series of steps
A, B, C, ...	Views
A-A, B-B, C-C, ...	Sections

1.3 Registered trademarks

1.3.1 GORE-TEX®

Trademark of W.L. Gore & Associates, Inc., USA.

1.3.2 TEFLON®

Trademark of E.I. Du Pont de Nemours & Co., Wilmington, USA.

1.3.3 HART®

Registered trademark of the FieldComm Group, Austin, USA

1.3.4 FieldCare®

Trademark of Endress+Hauser Process Solutions AG.

1.3.5 DeviceCare®

Trademark of Endress+Hauser Process Solutions AG.

1.3.6 iTEMP®

Trademark of Endress+Hauser Wetzer GmbH + Co. KG, Nesselwang, D..

1.4 Supplementary documentation

The document types listed are available:
In the Download Area of the Endress+Hauser Internet site: www.endress.com → Download

1.4.1 Technical Information (TI): planning aid for your device

Waterpilot: TI00431P

RIA15: TI01043K

The document contains all the technical data on the device and provides an overview of the accessories and other products that can be ordered for the device.

1.4.2 Brief Operating Instructions (KA): getting the 1st measured value quickly

FMX21 4 to 20 mA HART - KA01189P:

The Brief Operating Instructions contain all the essential information from incoming acceptance to initial commissioning.

1.4.3 Safety Instructions (XA)

Depending on the approval, the following Safety Instructions (XA) are supplied with the device. They are an integral part of the Operating Instructions.

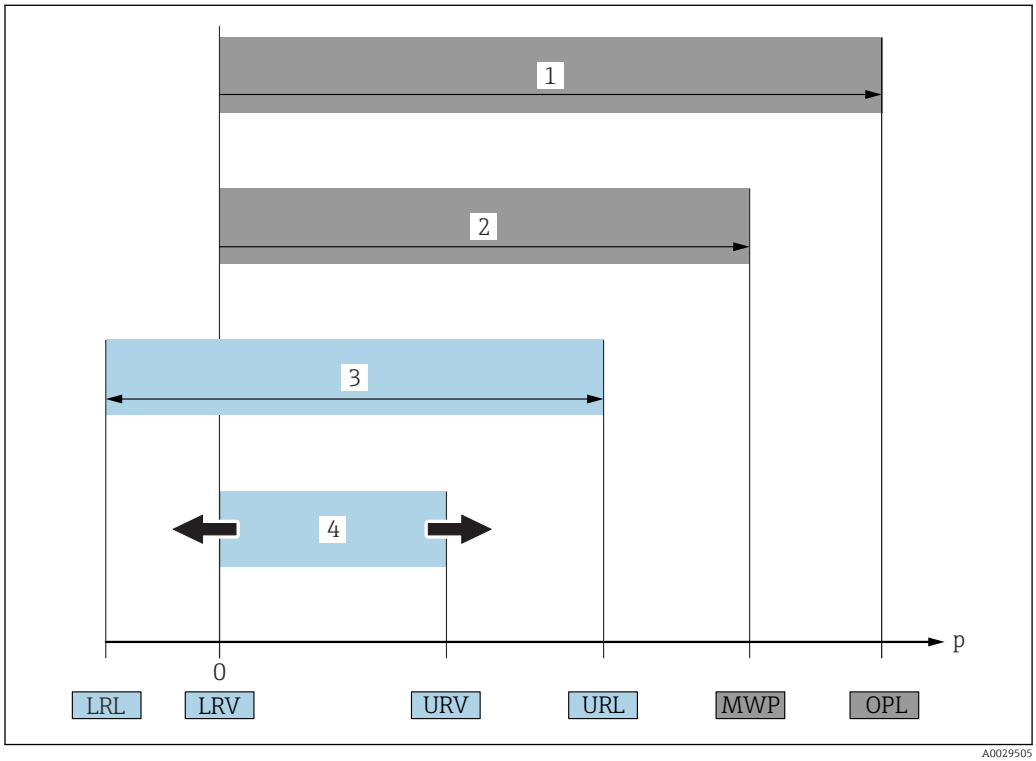
Directive	Type of protection	Category	Documentation	Option [1]
ATEX	Ex ia IIC	II 2 G	XA00454P	BD
ATEX	Ex nA IIC	II 3 G	XA00485P	BE
IECEx	Ex ia IIC	n/a	XA00455P	IC
CSA C/US	Ex ia IIC	n/a	ZD00232P (960008976)	CE
FM	AEx ia IIC	n/a	ZD00231P (960008975)	FE

Directive	Type of protection	Category	Documentation	Option [1]
NEPSI	Ex ia IIC	n/a	XA00456P	NA
INMETRO	Ex ia IIC	n/a	XA01066P	MA

1) Product Configurator order code for "Approval"

The nameplate indicates the Safety Instructions (XA) that are relevant to the device.

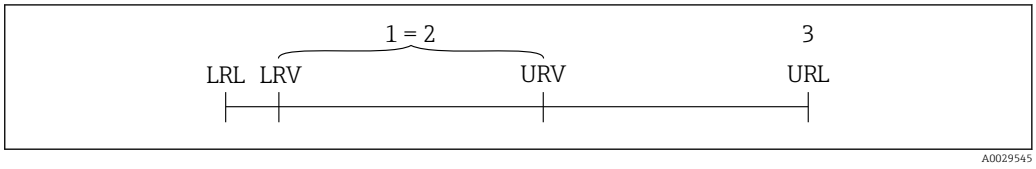
1.5 Terms and abbreviations



Item	Term/abbreviation	Explanation
1	OPL	The OPL (over pressure limit = sensor overload limit) for the measuring device depends on the lowest-rated element, with regard to pressure, of the selected components, i.e. the process connection has to be taken into consideration in addition to the measuring cell. Also observe pressure-temperature dependency. The OPL may only be applied for a limited period of time.
2	MWP	The MWP (maximum working pressure) for the sensors depends on the lowest-rated element, with regard to pressure, of the selected components, i.e. the process connection has to be taken into consideration in addition to the measuring cell. Also observe pressure-temperature dependency. The MWP may be applied at the device for an unlimited period. The MWP can also be found on the nameplate.
3	Maximum sensor measuring range	Span between LRL and URL This sensor measuring range is equivalent to the maximum calibratable/adjustable span.
4	Calibrated/adjusted span	Span between LRV and URV Factory setting: 0 to URL Other calibrated spans can be ordered as customized spans.
p	-	Pressure
-	LRL	Lower range limit
-	URL	Upper range limit
-	LRV	Lower range value

Item	Term/abbreviation	Explanation
-	URV	Upper range value
-	TD (turn down)	Turn down Example - see the following section.
-	PE	Polyethylene
-	FEP	Fluorinated ethylene propylene
-	PUR	Polyurethane

1.6 Turn down calculation



1 Calibrated/adjusted span
2 Zero point-based span
3 URL sensor

Example

- Sensor:10 bar (150 psi)
- Upper range value (URL) = 10 bar (150 psi)

Turn down (TD):

- Calibrated/adjusted span: 0 to 5 bar (0 to 75 psi)
- Lower range value (LRV) = 0 bar (0 psi)
- Upper range value (URV) = 5 bar (75 psi)

$$TD = \frac{URL}{|URV - LRV|}$$

$$TD = \frac{10\ bar\ (150\ psi)}{|5\ bar\ (75\ psi) - 0\ bar\ (0\ psi)|} = 2$$

In this example, the TD is 2:1.
This span is based on the zero point.

2 Basic safety instructions

2.1 Requirements concerning the staff

The personnel for installation, commissioning, diagnostics and maintenance must fulfill the following requirements:
- Trained, qualified specialists: must have a relevant qualification for this specific function and task
- Are authorized by the plant owner/operator
- Are familiar with federal/national regulations
- Before beginning work, the specialist staff must have read and understood the instructions in the Operating Instructions and supplementary documentation as well as in the certificates (depending on the application)
- Following instructions and basic conditions

The operating personnel must fulfill the following requirements:
- Being instructed and authorized according to the requirements of the task by the facility's owner-operator
- Following the instructions in these Operating Instructions

2.2 Designated use

2.2.1 Application and media

The Waterpilot FMX21 is a hydrostatic pressure sensor for measuring the level of fresh water, wastewater and salt water. The temperature is measured simultaneously in the case of sensor versions with a Pt100 resistance thermometer.

An optional temperature head transmitter converts the Pt100 signal to a 4 to 20 mA signal with superimposed digital communication protocol HART 6.0.

2.2.2 Incorrect use

The manufacturer is not liable for damage caused by improper or non-designated use.

Verification for borderline cases:
- For special fluids and fluids for cleaning, Endress+Hauser is glad to provide assistance in verifying the corrosion resistance of fluid-wetted materials, but does not accept any warranty or liability.

2.3 Workplace safety

For work on and with the device:
- Wear the required personal protective equipment according to federal/national regulations.
- Switch off the supply voltage before connecting the device.

2.4 Operational safety

Risk of injury!
- Operate the device in proper technical condition and fail-safe condition only.
- The operator is responsible for interference-free operation of the device.

Modifications to the device

Unauthorized modifications to the device are not permitted and can lead to unforeseeable dangers.
- If, despite this, modifications are required, consult with Endress+Hauser.

Repairs

To ensure continued operational safety and reliability,
- Carry out repairs on the device only if they are expressly permitted.
- Observe federal/national regulations pertaining to repair of an electrical device.
- Use original spare parts and accessories from Endress+Hauser only.

Hazardous area

To eliminate danger to persons or the facility when the device is used in the approval-related area (e.g. explosion protection, pressure vessel safety):
- Check the nameplate to verify if the device ordered can be put to its intended use in the approval-related area.
- Observe the specifications in the separate supplementary documentation that is an integral part of these Instructions.

2.5 Product safety

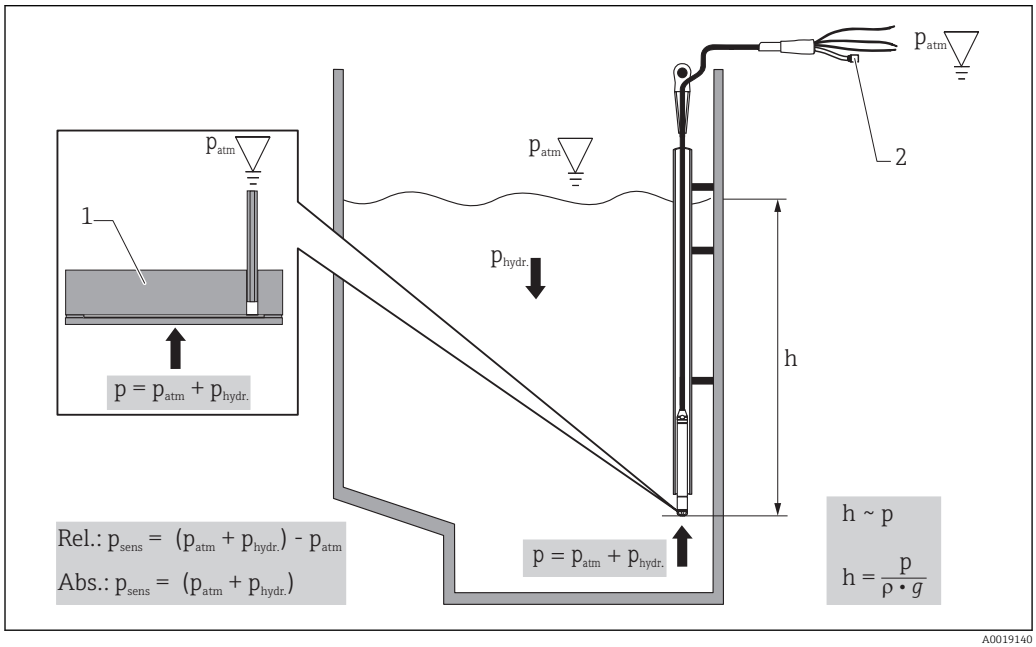
This measuring device is designed in accordance with good engineering practice to meet state-of-the-art safety requirements, has been tested, and left the factory in a condition in which it is safe to operate.

It meets general safety standards and legal requirements. It also complies with the EC directives listed in the device-specific EC Declaration of Conformity. Endress+Hauser confirms this by affixing the CE mark to the device.

3 Product description

3.1 Function

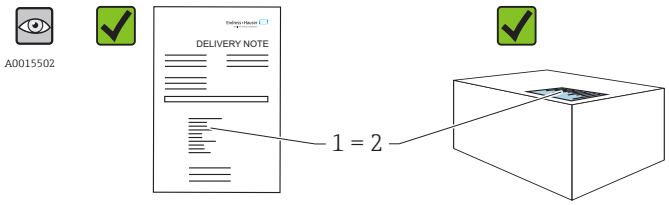
The ceramic measuring cell is a dry measuring cell i.e. the pressure acts directly on the robust, ceramic process isolating diaphragm of the Waterpilot FMX21. Changes in air pressure are guided via a pressure compensation tube through the extension cable to the rear of the ceramic process isolating diaphragm and are compensated for. A pressure-dependent change in capacitance, caused by the movement of the process isolating diaphragm, is measured at the electrodes of the ceramic carrier. The electronics unit then converts this to a signal that is proportional to the pressure and linear to the level.



1 *Ceramic measuring cell*
2 *Pressure compensation tube*
h *Height level*
p *Total pressure = atmospheric pressure + hydrostatic pressure*
ρ *Density of the medium*
g *Acceleration due to gravity*
$P_{hydr.}$ *Hydrostatic pressure*
P_{atm} *Atmospheric pressure*
P_{sens} *Pressure displayed on the sensor*

4 Incoming acceptance and product identification

4.1 Incoming acceptance



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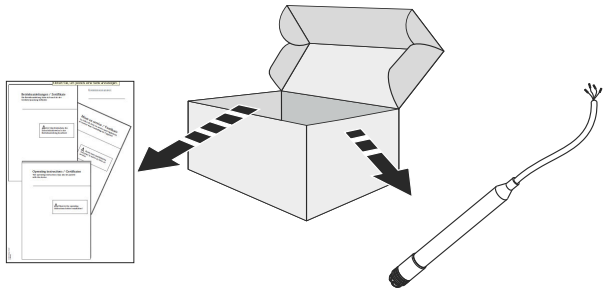
Is the order code on the delivery note (1) identical to the order code on the product sticker (2)?



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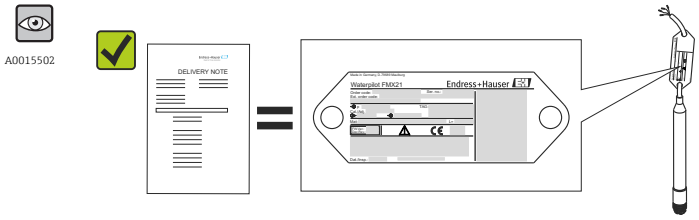
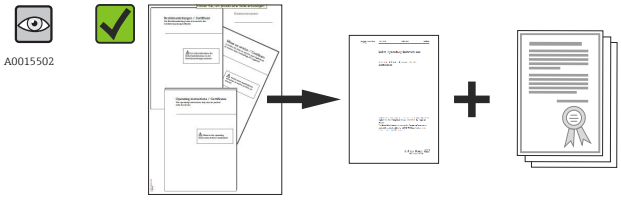
A0026536

Are the goods undamaged?



A0026537

Do the data on the nameplate correspond to the order specifications and the delivery note?



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Is the documentation available?
If required (see nameplate): Are the safety instructions (XA) present?

If one of these conditions does not apply, please contact your Endress+Hauser sales office.

4.2 Product identification

The following options are available for identification of the measuring device:
- Nameplate specifications
- Order code with breakdown of the device features on the delivery note
- Enter serial number of nameplates in *W@M Device Viewer* (www.endress.com/deviceviewer): All details on the measuring device are displayed.

For an overview of the technical documentation provided, enter the serial number from the nameplates in the *W@M Device Viewer* (www.endress.com/deviceviewer)

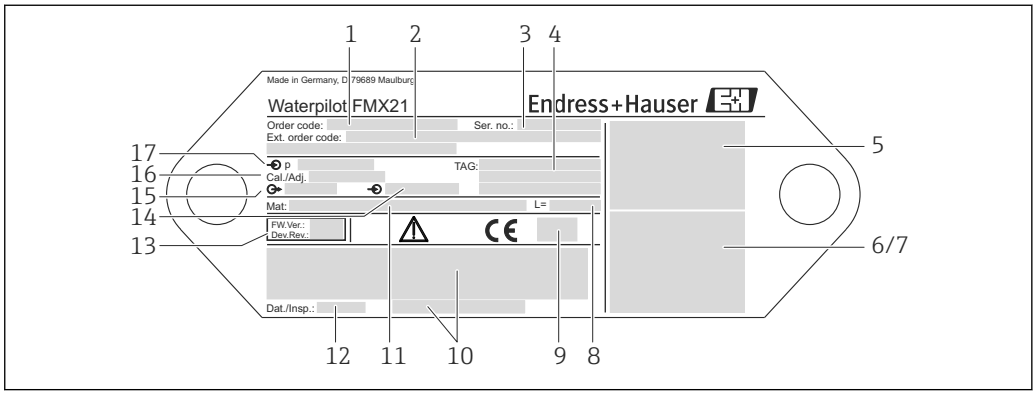
4.2.1 Manufacturer address

Endress+Hauser SE+Co. KG
Hauptstraße 1
79689 Maulburg, Germany

Address of the manufacturing plant: See nameplate.

4.3 Nameplates

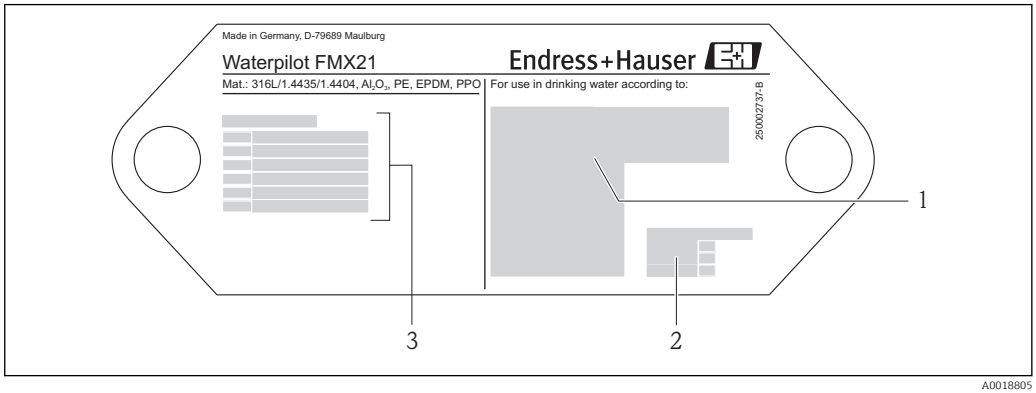
4.3.1 Nameplates on extension cable



A0018802

1 *Order code (shortened for reordering); The meaning of the individual letters and digits is explained in the order confirmation details.*
2 *Extended order number (complete)*
3 *Serial number (for clear identification)*
4 *TAG (device tag)*
5 *FMX21 connection diagram*
6 *Pt100 connection diagram (optional)*
7 *Warning (hazardous area), (optional)*
8 *Length of extension cable*
9 *Approval symbol, e.g. CSA, FM, ATEX (optional)*
10 *Text for approval (optional)*
11 *Materials in contact with process*
12 *Test date (optional)*
13 *Software version/device version*
14 *Supply voltage*
15 *Output signal*
16 *Set measuring range*
17 *Nominal measuring range*

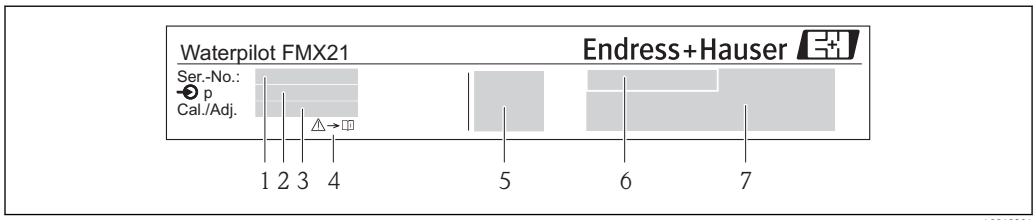
Additional nameplate for devices with approvals



A0018805

1 *Approval symbol (drinking water approval)*
2 *Reference to associated documentation*
3 *Approval number (marine approval)*

4.3.2 Additional nameplate for devices with external diameter 22 mm (0.87 in) and 42 mm (1.65 in)



1 *Serial number*
2 *Nominal measuring range*
3 *Set measuring range*
4 *CE mark or approval symbol*
5 *Certificate number (optional)*
6 *Text for approval (optional)*
7 *Reference to documentation*

4.4 Identification of sensor type

With gauge pressure or absolute pressure sensors, the "Pos. zero adjust" parameter is displayed in the operating menu. With absolute pressure sensors, the "Calib. offset" parameter is displayed in the operating menu.

4.5 Storage and transport

4.5.1 Storage conditions

Use original packaging.

Store the measuring device in clean and dry conditions and protect from damage caused by shocks (EN 837-2).

Storage temperature range

FMX21 + Pt100 (optional)

−40 to +80 °C (−40 to +176 °F)

Cable

(when mounted in a fixed position)
- With PE: −30 to +70 °C (−22 to +158 °F)
- With FEP: −30 to +80 °C (−22 to +176 °F)
- With PUR: −40 to +80 °C (−40 to +176 °F)

Terminal box

−40 to +80 °C (−40 to +176 °F)

TMT182 temperature head transmitter (optional) for FMX21 4 to 20 mA HART

−40 to +100 °C (−40 to +212 °F)

4.5.2 Transporting the product to the measuring point

⚠ WARNING

Incorrect transport!

Device or cable may become damaged, and there is a risk of injury!

- ▶ Transport measuring device in the original packaging.
- ▶ Follow the safety instructions and transport conditions for devices weighing more than 18 kg (39.6 lbs).

4.6 Scope of delivery

The scope of delivery comprises:

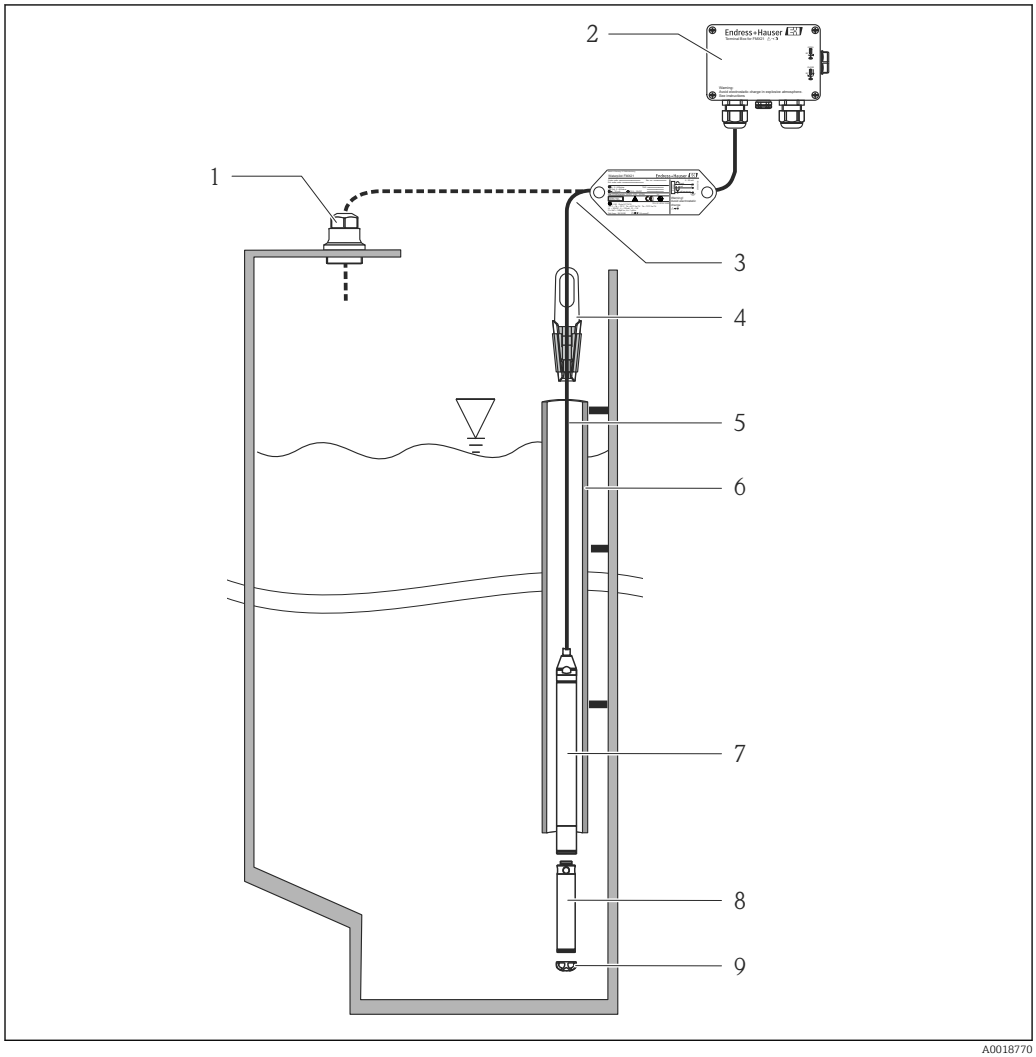
- Waterpilot FMX21, optionally with integrated Pt100 resistance thermometer
- Optional accessories

Documentation supplied:

- The Operating Instructions BA00380P are available on the internet. → see: www.de.endress.com → Downloads.
- Brief Operating Instructions KA01189P
- Final inspection report
- Drinking water approvals (optional): SD00289P, SD00319P, SD00320P
- Devices that are suitable for use in hazardous areas: Additional documentation e.g. Safety instructions (XA, ZD)

5 Installation

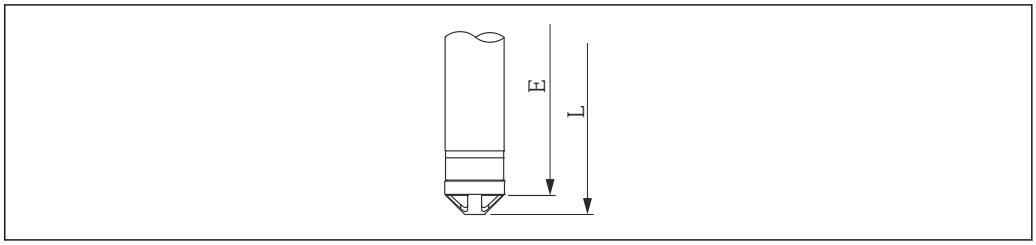
5.1 Installation conditions



1 *Cable mounting screw (can be ordered as an accessory)*
2 *Terminal box (can be ordered as an accessory)*
3 *Bending radius of extension cable > 120 mm (4.72 in)*
4 *Mounting clamp (can be ordered as an accessory)*
5 *Extension cable*
6 *Guide tube*
7 *Waterpilot FMX21*
8 *Additional weight can be ordered as an accessory for the FMX21 with external diameter of 22 mm (0.87 in) and 29 mm (1.14 in)*
9 *Protection cap*

5.2 Additional mounting instructions

- Cable length
  - Customer-specific in meters or feet.
  - Limited cable length when performing installation with freely suspended device with cable mounting screw or mounting clamp, as well as for FM/CSA approval: max. 300 m (984 ft).
- Sideways movement of the level probe can result in measuring errors. For this reason, install the probe at a point free from flow and turbulence, or use a guide tube. The internal diameter of the guide tube should be at least 1 mm (0.04 in) greater than the external diameter of the selected FMX21.
- To avoid mechanical damage to the measuring cell, the device is equipped with a protection cap.
- The cable must end in a dry room or a suitable terminal box. The terminal box from Endress+Hauser provides humidity and climatic protection and is suitable for installation outdoors → 🖹 124.
- Cable length tolerance: < 5 m (16 ft): ±17.5 mm (0.69 in); > 5 m (16 ft): ±0.2 %
- If the cable is shortened, the filter at the pressure compensation tube must be reattached. Endress+Hauser offers a cable shortening kit for this purpose → 🖹 124 (documentation SD00552P/00/A6).
- Endress+Hauser recommends using twisted, shielded cable.
- In shipbuilding applications, measures are required to restrict the spread of fire along cable looms.
- The length of the extension cable depends on the intended level zero point. The height of the protection cap must be taken into consideration when designing the layout of the measuring point. The level zero point (E) corresponds to the position of the process isolating diaphragm. Level zero point = E; tip of probe = L (see the following diagram).



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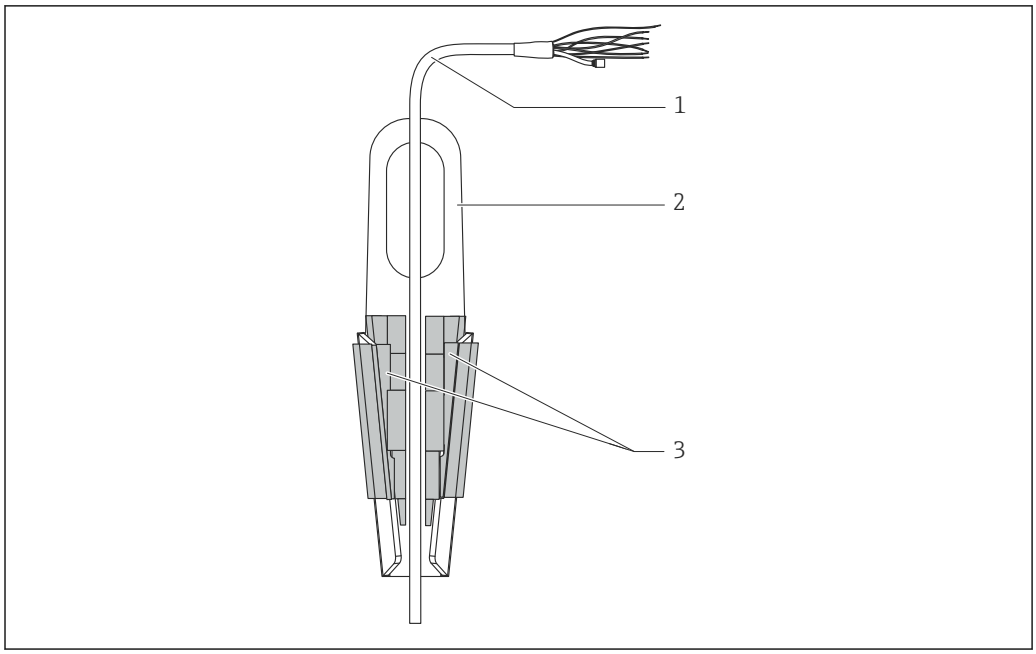
5.3 Dimensions

For dimensions, please refer to the Technical Information TI00431P/00/EN, "Mechanical construction" section (see also: www.de.endress.com → Downloads → Media Type: Documentation).

5.4 Mounting the Waterpilot with a mounting clamp

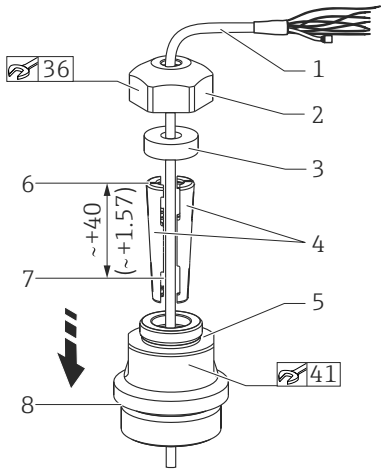


1 Extension cable
2 Suspension clamp
3 Clamping jaws

5.4.1 Mounting the suspension clamp:

1. Mount the suspension clamp (item 2). Take the weight of the extension cable (item 1) and the device into account when selecting the fastening point.
2. Push up the clamping jaws (item 3). Place the extension cable (item 1) between the clamping jaws as shown in the graphic.
3. Hold the extension cable (item 1) in position and push the clamping jaws (item 3) back down. Tap the clamping jaws gently from above to fix them in place.

5.5 Mounting the Waterpilot with a cable mounting screw



1 *Extension cable*
2 *Cover for cable mounting screw*
3 *Sealing ring*
4 *Clamping sleeves*
5 *Adapter for cable mounting screw*
6 *Top edge of clamping sleeve*
7 *Desired length of extension cable and Waterpilot probe prior to assembly*
8 *After assembly, item 7 is located next to the mounting screw with G 1½" thread: height of sealing surface of the adapter or NPT 1½" thread height of thread run-out of adapter*

Engineering unit mm (in). Illustrated with G 1½" thread.

If you want to lower the level probe to a certain depth, position the top edge of the clamping sleeve 40 mm (4.57 in) higher than the required depth. Then push the extension cable and the clamping sleeve into the adapter as described in Step 6 in the following section.

5.5.1 Mounting the cable mounting screw with a G 1½" or NPT 1½" thread:

1. Mark the desired length of extension cable on the extension cable.
2. Insert the probe through the measuring aperture and carefully lower on the extension cable. Fix the extension cable to prevent it from slipping.
3. Slide the adapter (item 5) over the extension cable and screw it tightly into the measuring aperture.
4. Slide the sealing ring (item 3) and cover (item 2) onto the cable from above. Press the sealing ring into the cover.
5. Place the clamping sleeves (item 4) around the extension cable (item 1) at the marked point as illustrated in the graphic.
6. Slide the extension cable with the clamping sleeves (item 4) into the adapter (item 5)
7. Fit the cover (item 2) with the sealing ring (item 3) onto the adapter (item 5) and securely screw together with the adapter.

To remove the cable mounting screw, perform this sequence of steps in reverse.

⚠ CAUTION

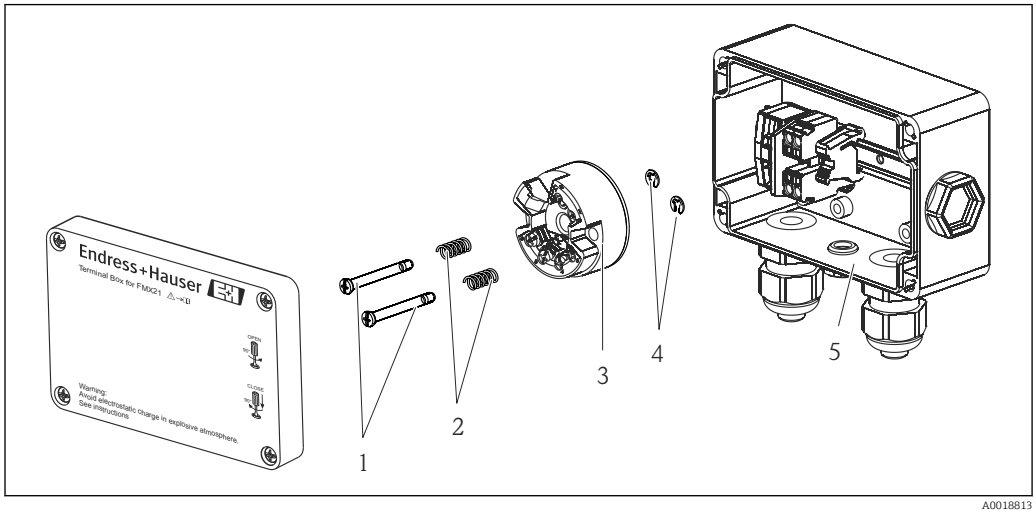
Risk of injury!

▶ Use only in unpressurized vessels.

5.6 Mounting the terminal box

The optional terminal box is mounted using four screws (M4). For the dimensions of the terminal box, please see the Technical Information TI00431P/00/ EN, "Mechanical construction" section (see also: www.de.endress.com → Downloads → Media Type: Documentation).

5.7 Mounting the TMT182 temperature head transmitter with terminal box



1 *Mounting screws*
2 *Mounting springs*
3 *TMT182 temperature head transmitter*
4 *Circlips*
5 *Terminal box*

Only open the terminal box with a screwdriver.

⚠ WARNING

Risk of explosion!

▶ The TMT182 is not designed for use in hazardous areas.

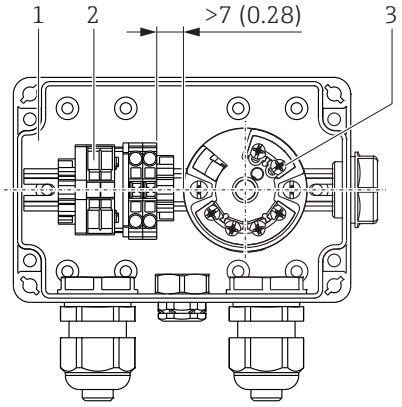
5.7.1 Mounting the temperature head transmitter:

1. Guide the mounting screws (item 1) with the mounting springs (item 2) through the bore of the temperature head transmitter (item 3)
2. Secure the mounting screws with the circlips (item 4). Circlips, mounting screws and springs are included in the scope of delivery for the temperature head transmitter.
3. Screw the temperature head transmitter into the field housing tightly. (Width of screwdriver blade max. 6 mm (0.24 in))

NOTICE

Avoid damage to the temperature head transmitter.

▶ Do not overtighten the mounting screw.



1 Terminal box
2 Terminal strip
3 TMT182 temperature head transmitter

Engineering unit mm (in)

NOTICE

Incorrect connection!

- A distance of >7 mm (> 0.28) must be maintained between the terminal strip and the TMT182 temperature head transmitter.

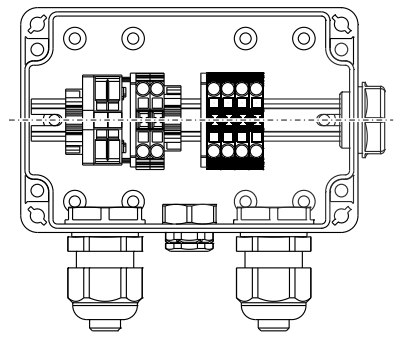
5.8 Mounting the terminal strip for the Pt100 passive (without TMT182)

If the FMX21 with optional Pt100 is supplied without the optional TMT182 temperature head transmitter, a terminal strip is provided with the terminal box for the purpose of wiring the Pt100.

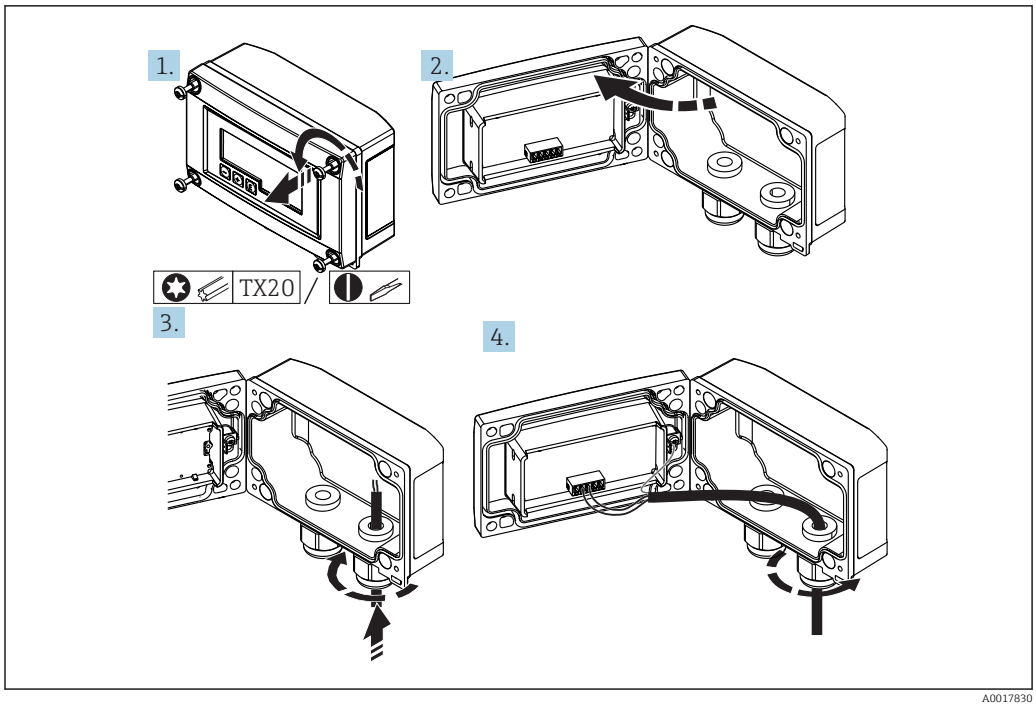
⚠ WARNING

Risk of explosion!

- The Pt100, as well as the terminal strip, are not designed for use in hazardous areas.



5.9 Inserting the cable into the RIA15 field housing



A0017830

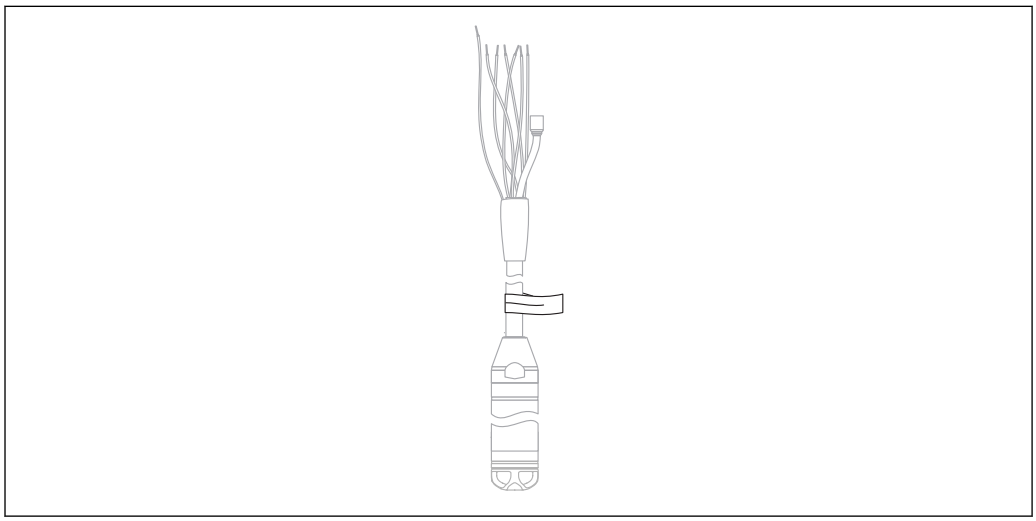
Inserting the cable, field housing, connection without transmitter power supply (example)

1. Release the housing screws
2. Open the housing
3. Open the cable gland (M16) and insert the cable
4. Connect the cable including the functional grounding and close the cable gland

Compensation of the atmospheric pressure must be ensured for the installation. A black, vented cable gland is supplied for this purpose.

If using the communication resistor module in the RIA15, the cable of the FMX21 must be inserted into the right gland when connecting the FMX21 so that the integrated pressure compensation tube is not pinched.

5.10 Cable marking



A0030955

- To make installation easier, Endress+Hauser marks the extension cable if a customer-specific length has been ordered.
  Ordering information: Product Configurator order code for "Service", option "IR" or "IS".
- Cable marking tolerance (distance to lower end of level probe):
  Cable length < 5 m (16 ft): ±17.5 mm (0.69 in)
  Cable length > 5 m (16 ft): ±0.2 %
- Material: PET, stick-on label: acrylic
- Immunity to temperature change: −30 to +100 °C (−22 to +212 °F)

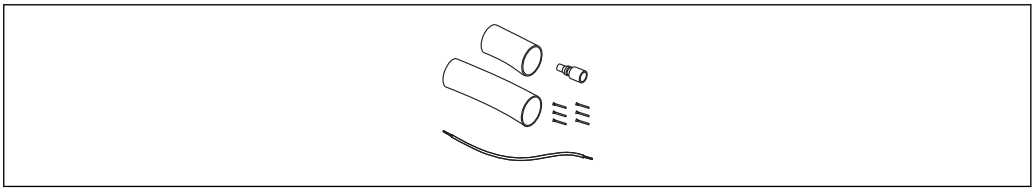
NOTICE

The marking is used exclusively for installation purposes.

▶ The mark must be thoroughly removed without trace in the case of devices with drinking water approval. The extension cable must not be damaged in the process.

Not for use of the FMX21 in hazardous areas.

5.11 Cable shortening kit



A0030948

The cable shortening kit is used to shorten a cable easily and professionally.

The cable shortening kit is not designed for the FMX21 with FM/CSA approval.

- Ordering information: Product Configurator order code for "Accessories enclosed", option "PW"
- Associated documentation SD00552P/00/A6.

5.12 Post-installation check

❑	Is the device undamaged (visual inspection)?
❑	Does the device conform to the measuring point specifications? For example: ▪ Process temperature ▪ Process pressure ▪ Ambient temperature ▪ Measuring range
❑	Are the measuring point identification and labeling correct (visual inspection)?
❑	Check that all screws are firmly seated.

6 Electrical connection

⚠ WARNING

Electrical safety is compromised by an incorrect connection!

- When using the measuring device in a hazardous area, the relevant national standards and guidelines as well as the Safety Instructions (XAs) or installation or control drawings (ZDs) must be adhered to. All data relating to explosion protection can be found in separate documentation which is available on request. This documentation is supplied with the devices as standard → 🖹 7

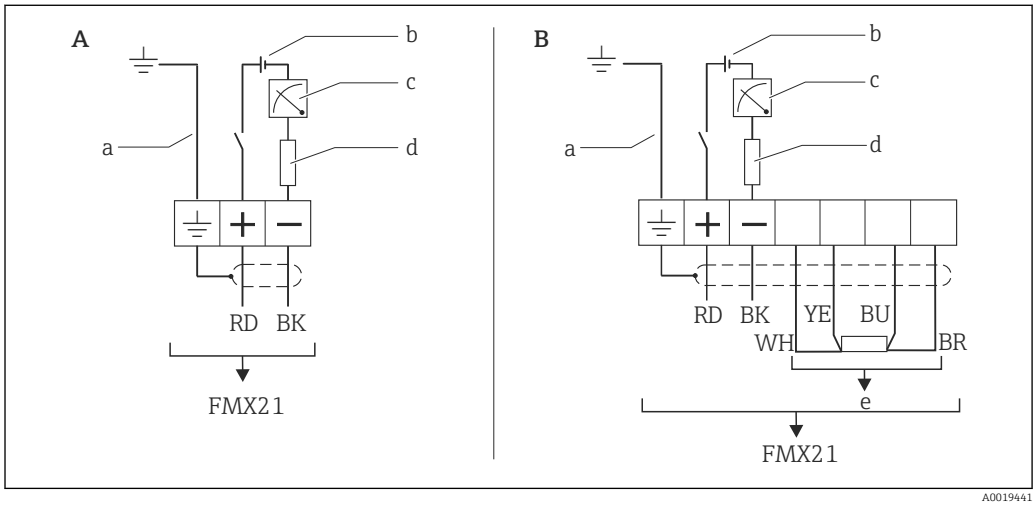
6.1 Connecting the device

⚠ WARNING

Electrical safety is compromised by an incorrect connection!

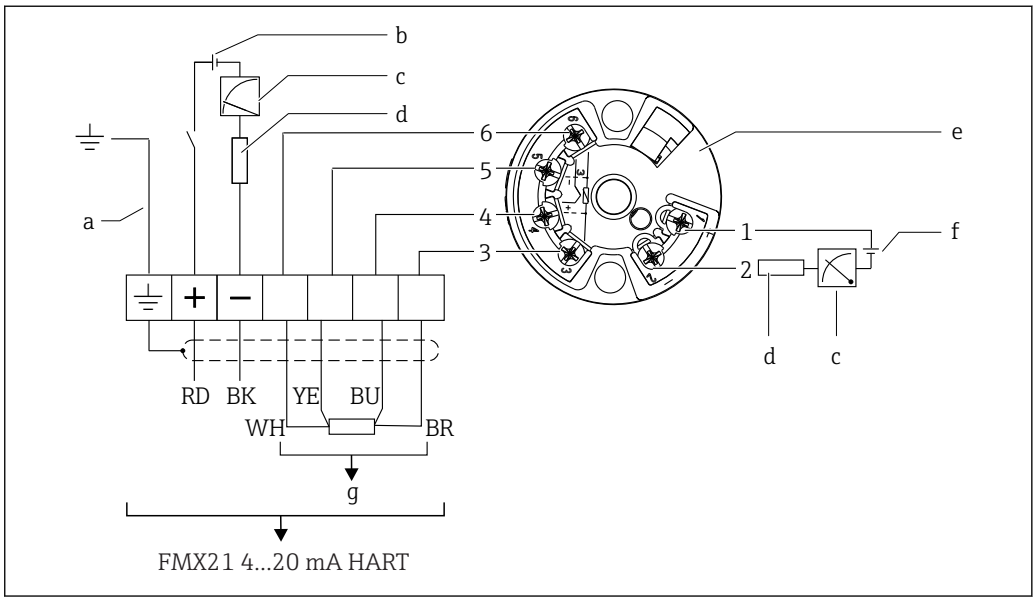
- The supply voltage must match the supply voltage specified on the nameplate → 🖹 15
- Switch off the supply voltage before connecting the device.
- The cable must end in a dry room or a suitable terminal box. The IP66/IP67 terminal box with GORE-TEX® filter from Endress+Hauser is suitable for outdoor installation.→ 🖹 22
- Connect the device in accordance with the following diagrams. Reverse polarity protection is integrated in the Waterpilot FMX21 and the temperature head transmitter. Changing the polarities will not result in the destruction of the devices.
- A suitable circuit breaker should be provided for the device in accordance with IEC/EN 61010.

6.1.1 Waterpilot with Pt100



A Waterpilot FMX21
B Waterpilot FMX21 with Pt100 (not for use in hazardous areas); option "NB", Product Configurator order code for "Accessories"
a Not for the FMX21 with external diameter of 29 mm (1.14 in)
b 10.5 to 30 V DC (hazardous area), 10.5 to 35 V DC
c 4...20 mA
d Resistance (R_L)
e Pt100

6.1.2 Waterpilot with Pt100 and TMT182 temperature head transmitter for FMX21 4 to 20 mA HART



a Not for the FMX21 with external diameter of 29 mm (1.14 in)
b 10.5 to 35 V DC
c 4...20 mA
d Resistance (R_L)
e TMT182 temperature head transmitter (4 to 20 mA) (not for use in hazardous areas)
f 11.5 to 35 V DC
g Pt100
1...6 Pin assignment

Ordering information:

Pt100: Product Configurator order code for "Accessories mounted", option "NB"

TMT182: Product Configurator order code for "Accessories enclosed", option "PT"

6.1.3 Waterpilot FMX21 with RIA15

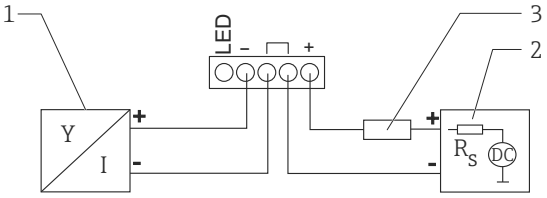
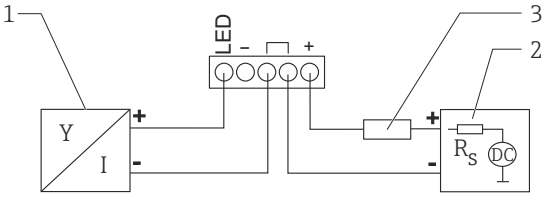
The RIA15 remote display can be ordered together with the device.

Product structure, feature 620 "Accessory enclosed":
- Option R4 "Remote display RIA15 non-hazardous area, field housing"
- Option R5 "Remote display RIA15 Ex= explosion protection approval, field housing"

Compensation of the atmospheric pressure must be ensured for the installation. A black, vented cable gland is supplied for this purpose.

The RIA15 process display unit is loop-powered and does not require any external power supply.

The voltage drop to be taken into account is:
- ≤1 V in the standard version with 4 to 20 mA communication
- ≤1.9 V with HART communication
- and an additional 2.9 V if display light is used

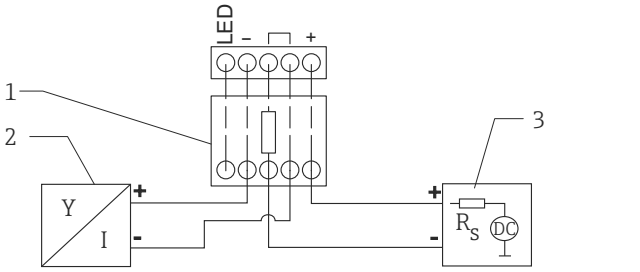
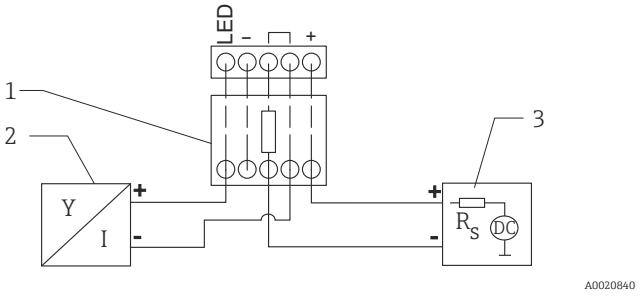
	Circuit diagram / Description
Waterpilot FMX21 connection, HART communication and RIA15 **without** backlight	 1 *Waterpilot FMX21 block diagram, HART with RIA15 process display unit without light* *1 Waterpilot FMX21* *2 Power supply* *3 HART resistance*
Waterpilot FMX21 connection, HART communication and RIA15 **with** backlight	 2 *Waterpilot FMX21 block diagram, HART with RIA15 process display unit with light* *1 Waterpilot FMX21* *2 Power supply* *3 HART resistance*

6.1.4 Waterpilot FMX21, RIA15 with installed HART communication resistor module

The HART communication module for installation in the RIA15 can be ordered together with the device.

Product structure, feature 620 "Accessory enclosed":
- Option R6 "HART communication resistor hazardous / non-hazardous area"
- The **voltage drop** to be taken into account is max. **7 V**

Compensation of the atmospheric pressure must be ensured for the installation. A black, vented cable gland is supplied for this purpose.

	Circuit diagram / Description
Waterpilot FMX21 connection and RIA15 **without** backlight	 3 *Waterpilot FMX21 block diagram, RIA15 without light, HART communication resistor module* *1 HART communication resistor module* *2 Waterpilot FMX21* *3 Power supply*
Waterpilot FMX21 connection and RIA15 **with** backlight	 4 *Waterpilot FMX21 block diagram, RIA15 with light, HART communication resistor module* *1 HART communication resistor module* *2 Waterpilot FMX21* *3 Power supply*

6.1.5 Wire colors

RD = red, BK = black, WH = white, YE = yellow, BU = blue, BR = brown

6.1.6 Connection data

Connection classification as per IEC 61010-1:
- Overvoltage category 1
- Pollution level 1

Connection data in the hazardous area

See relevant XA.

6.2 Supply voltage

⚠ WARNING

Supply voltage might be connected!
Risk of electric shock and/or explosion!

- ▶ When using the measuring device in hazardous areas, installation must comply with the corresponding national standards and regulations as well as the Safety Instructions.
- ▶ All explosion protection data are given in separate documentation which is available upon request. The Ex documentation is supplied as standard with all devices approved for use in explosion hazardous areas.

6.2.1 FMX21 + Pt100 (optional)

- 10.5 to 35 V (not hazardous areas)
- 10.5 to 30 V (hazardous areas)

6.2.2 TMT182 temperature head transmitter (optional) for FMX21 4 to 20 mA HART

11.5 to 35 V DC

6.3 Cable specifications

Endress+Hauser recommends using shielded, twisted-pair two-wire cables.

The probe cables are shielded for device versions with outer diameters of 22 mm (0.87 in) and 42 mm (1.65 in).

6.3.1 FMX21 + Pt100 (optional)

- Commercially available instrument cable
- Terminals, terminal box: 0.08 to 2.5 mm^2 (28 to 14 AWG)

6.3.2 TMT182 temperature head transmitter (optional) for FMX21 4 to 20 mA HART

- Commercially available instrument cable
- Terminals, terminal box: 0.08 to 2.5 mm^2 (28 to 14 AWG)
- Transmitter connection: max. 1.75 mm^2 (15 AWG)

6.4 Power consumption

6.4.1 FMX21 + Pt100 (optional)

- ≤ 0.805 W at 35 V DC (non-hazardous area)
- ≤ 0.690 W at 30 V DC (hazardous area)

6.4.2 TMT182 temperature head transmitter (optional) for FMX21 4 to 20 mA HART

≤ 0.805 W at 35 V DC

6.5 Current consumption

6.5.1 FMX21 + Pt100 (optional)

Max. current consumption: ≤ 23 mA
Min. current consumption: ≥ 3.6 mA

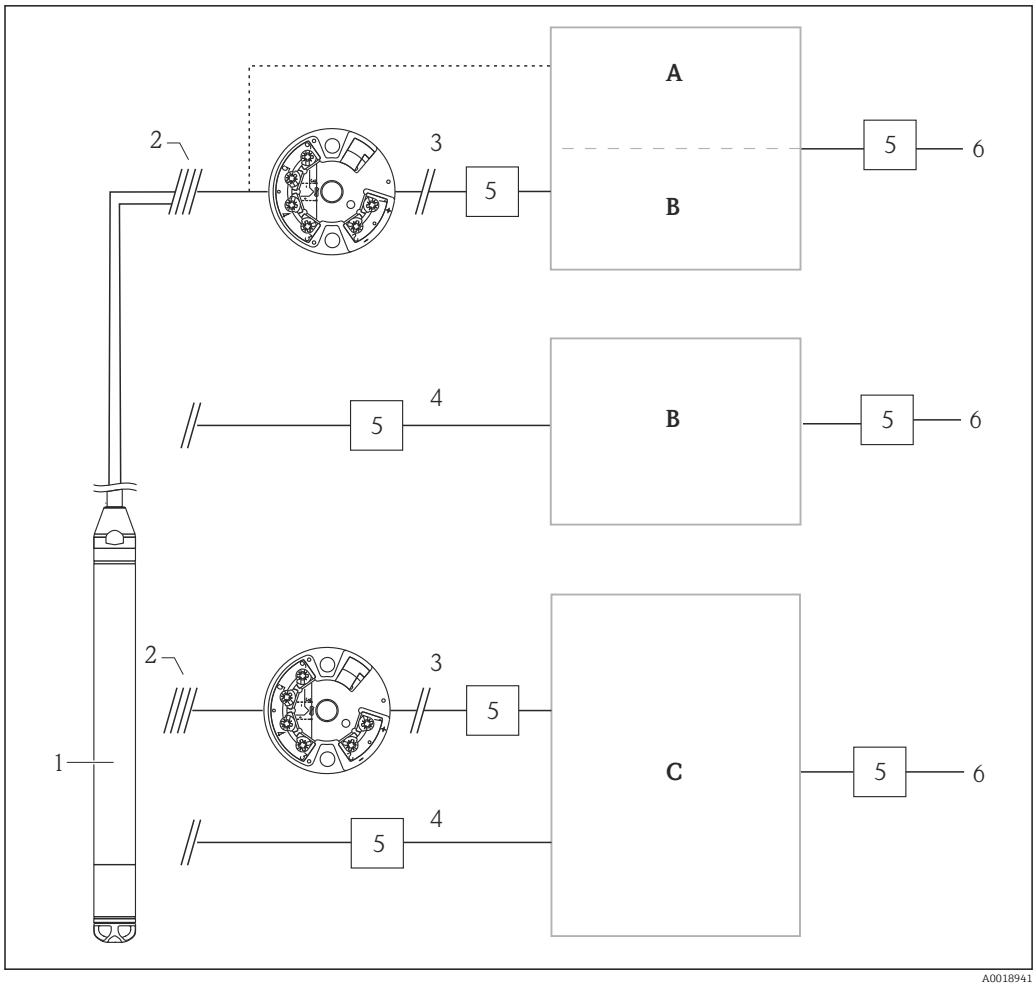
6.5.2 TMT182 temperature head transmitter (optional) for FMX21 4 to 20 mA HART

- Max. current consumption: ≤ 23 mA
- Min. current consumption: ≥ 3.5 mA

6.6 Connecting the measuring unit

6.6.1 Overvoltage protection

To protect the Waterpilot and the TMT182 temperature head transmitter from large interference voltage peaks, Endress+Hauser recommends installing overvoltage protection upstream and downstream of the display and/or evaluation unit as shown in the graphic.



A Power supply, display and evaluation unit with one input for Pt100
B Power supply, display and evaluation unit with one input for 4 to 20 mA
C Power supply, display and evaluation unit with two inputs for 4 to 20 mA
1 Waterpilot FMX21 HART
2 Connection for integrated Pt100 in the FMX21
3 4 to 20 mA HART (temperature)
4 4 to 20 mA HART (level)
5 Overvoltage protection, e.g. HAW from Endress+Hauser (not for use in hazardous areas.)
6 Power supply

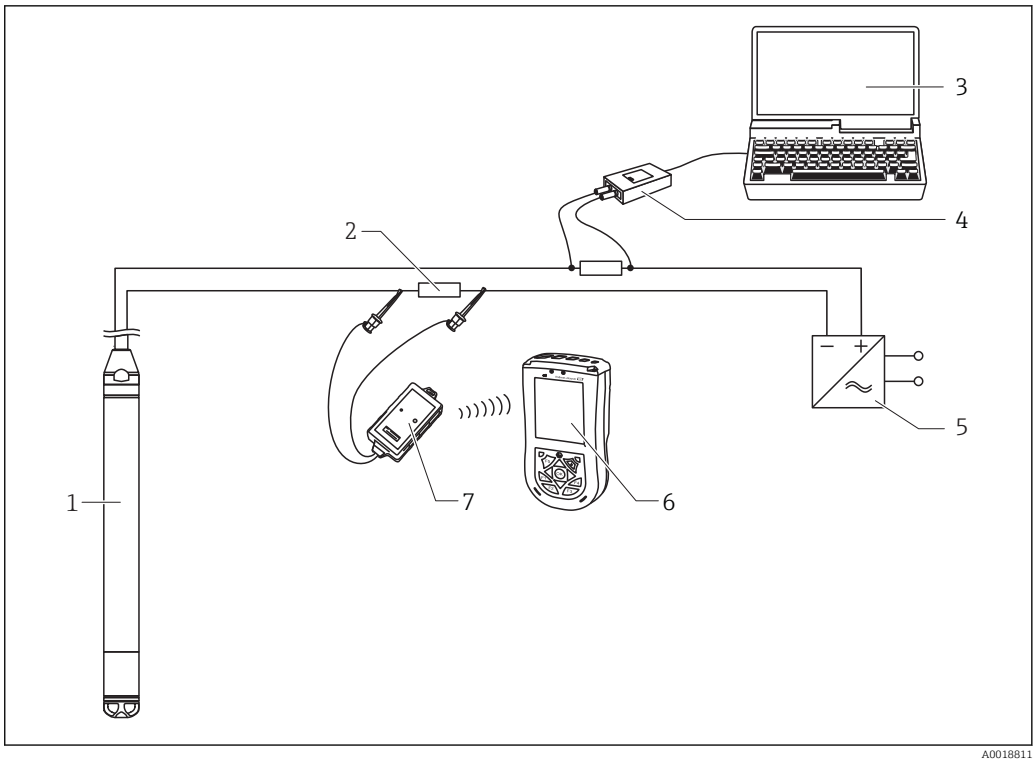
Further information on the TMT182 temperature head transmitter for HART applications from Endress+Hauser can be found in the Technical Information TI00078R/09/EN.

6.6.2 Connecting the Commubox FXA195

The Commubox FXA195 connects transmitters with the HART protocol to the USB interface of a computer. This enables remote operation of the transmitter using the Endress+Hauser operating program FieldCare/DeviceCare. Power is supplied to the Commubox via the USB port. The Commubox is also suitable for connecting to intrinsically safe circuits. For further information, see the Technical Information TI00404F/00/EN.

6.6.3 Connecting the Field Xpert SFX

Compact, flexible and robust industrial handheld terminal for remote configuration and for obtaining measured values via the HART current output (4 to 20 mA). For details, see Operating Instructions BA00060S/04/EN.



1 *Waterpilot FMX21*
2 *Required communication resistor ≥ 250 Ω*
3 *Computer with operating tool (e.g. FieldCare)*
4 *Commubox FXA195 (USB)*
5 *Transmitter power supply unit, e.g. RN221N (with communication resistor)*
6 *Field Xpert SFX*
7 *VIATOR Bluetooth modem with connecting cable*

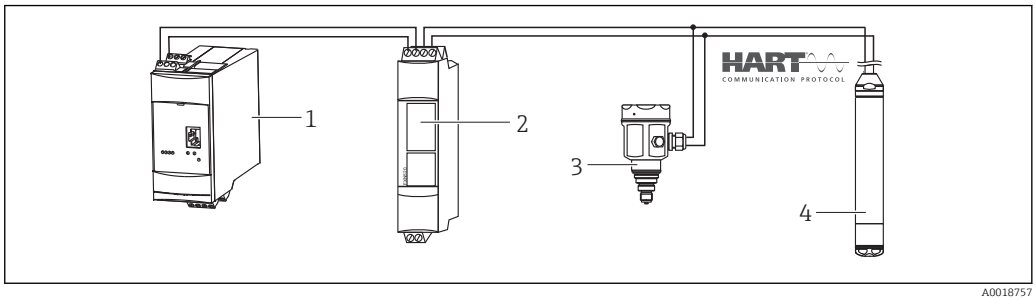
Only use certified operating devices in hazardous area!

WARNING

Risk of explosion!

- Do not change the battery of the handheld terminal in the hazardous area.
- When using the measuring device in hazardous areas, installation must comply with the corresponding national standards and regulations and the Safety Instructions (XAs) or the Installation or Control Drawings (ZDs).

6.6.4 Connecting for air pressure compensation with external measured value



1 *Fieldgate FXA520*
2 *Multidrop Connector FXN520*
3 *Cerabar*
4 *Waterpilot FMX21*

For applications in which condensation may occur, the use of an absolute pressure probe is recommended. For level measurement using an absolute pressure probe, the measured value is affected by fluctuations in the ambient air pressure. To correct the resulting measured error, you can connect an external absolute pressure sensor (e.g. Cerabar) to the HART signal line, switch the Waterpilot to burst mode and operate the Cerabar in the "Electr. Delta P" mode.

When you switch on the "Electr. Delta P" application, the external absolute pressure sensor calculates the difference between the two pressure signals and can thus determine the level precisely. Only one level measured value can be corrected in this way.

For additional information, see → 57.

If using intrinsically safe devices, the regulations which apply to interconnecting intrinsically safe circuits as outlined in IEC 60079-14 (proof of intrinsic safety) must be observed.

6.6.5 Connecting an external temperature sensor/temperature head transmitter for density compensation

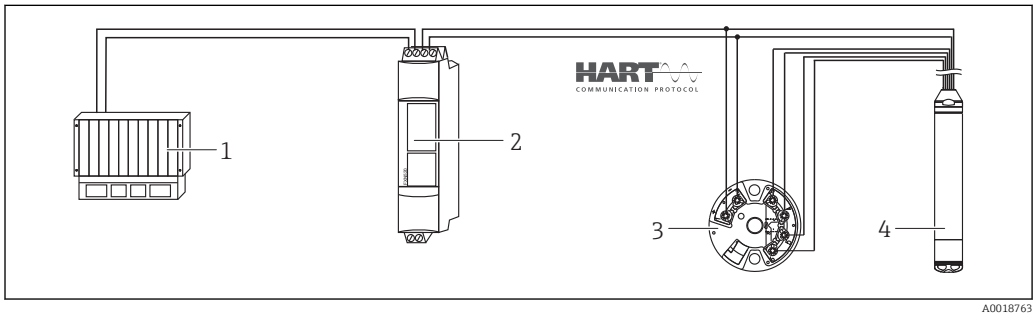
The Waterpilot FMX21 can correct measured errors that result from fluctuations in the density of the water caused by temperature. Users can choose from the following options:

Use the internally measured sensor temperature of the FMX21

The internally measured sensor temperature is calculated in the Waterpilot FMX21 for density compensation. The level signal is thus corrected according to the density characteristic line of water.

Use the optional internal Pt100 temperature sensor for density compensation in a suitable HART master (e.g. PLC)

The Waterpilot FMX21 is available with an optional Pt100 temperature sensor. Endress +Hauser additionally offers the TMT182 temperature head transmitter to convert the Pt100 signal to a 4 to 20 mA HART signal. The temperature and pressure signal is queried by a HART master (e.g. PLC), where a corrected level value can be generated using a stored linearization table or density function (of a chosen medium).



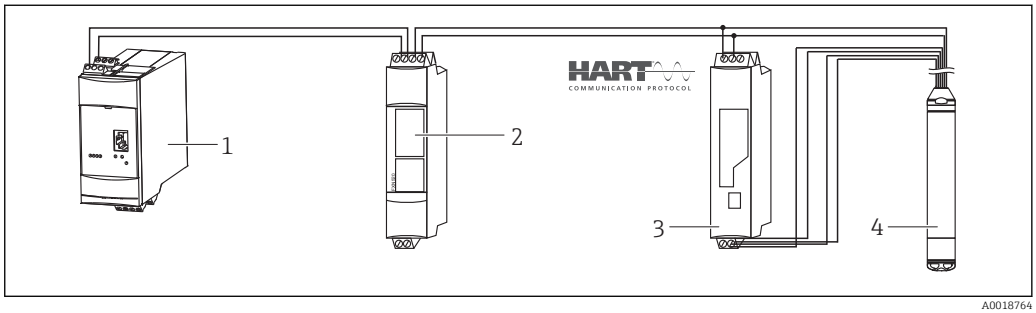
1 HART master, e.g. PLC (programmable logic controller)
2 Multidrop Connector FXN520
3 TMT182 temperature head transmitter
4 Waterpilot FMX21

Use an external temperature signal which is transmitted to the FMX21 via HART burst mode

The Waterpilot FMX21 is available with an optional Pt100 temperature sensor. With this option, the signal of the Pt100 is evaluated with a HART-compliant temperature head transmitter (min. HART 5.0) that supports the burst mode. The temperature signal can

thus be transmitted to the FMX21. The FMX21 uses this signal for density correction of the level signal.

The TMT182 temperature head transmitter is not suitable for this configuration.



1 Fieldgate FXA520
2 Multidrop Connector FXN520
3 HART-compatible temperature transmitter (e.g. TMT82)
4 Waterpilot FMX21

Without additional compensation due to the anomaly of water, errors of up to 4% may occur at a temperature of +70 °C (+158 °F), for example. With density compensation, this error can be decreased to 0.5 % in the entire temperature range from 0 to +70 °C (+32 to +158 °F).

For additional information, see → 59.

For further information on the devices, please refer to the relevant Technical Information:
- TI01010T: TMT82 temperature transmitter (4 to 20 mA HART)
- TI00369F: Fieldgate FXA520
- TI00400F: Multidrop Connector FXN520

6.7 Post-connection check

❑	Is the device or cable undamaged (visual check)?
❑	Do the cables comply with the requirements ?
❑	Do the cables have adequate strain relief?
❑	Are all cable glands installed, securely tightened and leak-tight?
❑	Does the supply voltage match the specifications on the nameplate?
❑	Is the terminal assignment correct ?

7 Operation options

Endress+Hauser offers comprehensive measuring point solutions with display and/or evaluation units for the Waterpilot FMX21 HART and TMT182 temperature head transmitter.

Your Endress+Hauser service organization would be glad to be of service if you have any other questions. Contact addresses can be found on the website at www.endress.com/worldwide

7.1 Overview of operating options

7.1.1 Operation using Endress+Hauser operating program

FieldCare

The FieldCare operating program is an Endress+Hauser asset management tool based on FDT technology. With FieldCare, you can configure all Endress+Hauser devices as well as devices from other manufacturers that support the FDT standard.

Hardware and software requirements can be found on the Internet:

www.de.endress.com → Search: FieldCare → FieldCare → Technical data.

FieldCare supports the following functions:
- Configuration of transmitters in online/offline mode
- Loading and saving device data (upload/download)
- Documentation of the measuring point

Connection options:
- HART via Commubox FXA195 and USB interface of a computer
- HART via Fieldgate FXA520

- Further information on FieldCare and software download can be found on the internet (www.de.endress.com ® Downloads ® Text Search: FieldCare).
- Connecting the Commubox FXA195
- As not all internal device dependencies can be mapped in offline operation, the consistency of the parameters must be checked once again before they are transmitted to the device.

DeviceCare

Function scope

Tool for connecting and configuring Endress+Hauser field devices.

The fastest way to configure Endress+Hauser field devices is with the dedicated "DeviceCare" tool. Together with the device type managers (DTMs) it presents a convenient, comprehensive solution.

For details, see Innovation brochure IN01047S

7.1.2 Operation via Field Xpert SFX

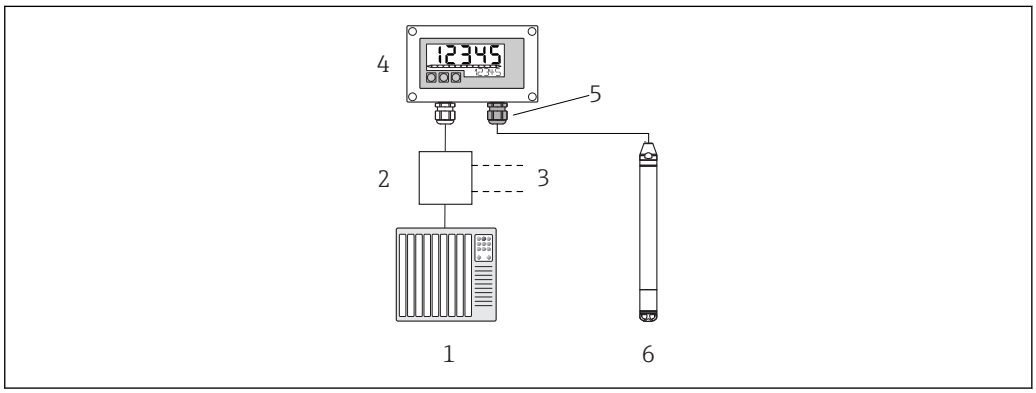
Compact, flexible and robust industrial handheld terminal for remote configuration and for obtaining measured values via the HART current output or FOUNDATION Fieldbus. For details, see the Operating Instructions BA00060S/04.

7.1.3 Operation via RIA15

The RIA15 can be used as a local display unit and for the basic configuration of the Waterpilot FMX21 hydrostatic level sensor via HART.

The following parameters can be configured on the FMX21 using the 3 operating keys on the front of the RIA15:
- Pressure engineering unit, level, temperature
- Zero adjustment (only for gauge pressure sensors)
- Empty and full pressure adjustment
- Empty and full level adjustment
- Reset to factory defaults

Further information on the operating parameters → 67



5 Remote operation of the Waterpilot FMX21 via the RIA15

1 PLC
2 Transmitter power supply, e.g. RN221N (with communication resistor)
3 Connection for Commubox FXA195 and Field Communicator 375, 475
4 RIA15 loop-powered process display unit
5 Cable gland M16 with pressure compensation membrane
6 Waterpilot FMX21

7.2 Operating concept

Operation with an operating menu is based on an operation concept with "user roles" .

User role	Meaning
Operator	Operators are responsible for the devices during normal "operation". This is usually limited to the reading of process values. If the work with the devices goes beyond reading, it concerns simple, application-specific functions that are used in operation. Should an error occur, these users simple forward the information on the errors but do not intervene themselves.
Maintenance	Service engineers usually work with the devices in the phases following device commissioning. They are primarily involved in maintenance and troubleshooting activities for which simple settings have to be made at the device. Technicians work with the devices over the entire life cycle of the product. Thus, commissioning and advanced settings and configurations are some of the tasks they have to carry out.
Expert	Experts work with the devices over the entire life cycle of the device, but, in part, have high requirements on the devices. Individual parameters/functions from the overall functionality of the devices are required for this purpose time and again. In addition to technical, process-oriented tasks, experts can also perform administrative tasks (e.g. user administration). "Experts" can avail of the entire parameter set.

7.3 Structure of the operating menu

User role	Submenu	Meaning/use
Operator	Display/ operat.	Contains parameters that are needed to configure the measured value display (selecting the values displayed, display format, etc.). With this submenu, users can change the measured value display without affecting the actual measurement.
Maintenance	setup	Contains all the parameters that are needed to commission measuring operations. This submenu has the following structure: ▪ **Standard setup parameters** A wide range of parameters, which can be used to configure a typical application, is available at the start. The measuring mode selected determines which parameters are available. After making settings for all these parameters, the measuring operation should be completely configured in the majority of cases. ▪ **"Extended setup" submenu** The "Extended setup" submenu contains additional parameters for more in-depth configuration of the measurement operation, for conversion of the measured value and for scaling the output signal. This menu is split into additional submenus depending on the measuring mode selected.
Maintenance	Diagnosis	Contains all the parameters that are needed to detect and analyze operating errors. This submenu has the following structure: ▪ **Diagnostic list** contains up to 10 currently pending error messages. ▪ **Event logbook** contains the last 10 error messages (no longer pending). ▪ **Instrument info** contains information for identifying the device. ▪ **Measured values** contains all current measured values. ▪ **Simulation** Is used to simulate pressure, level, current and alarm/warning. ▪ **Enter reset code**
Expert	Expert	Contains all the parameters of the device (including those already in one of the submenus). The "Expert" submenu is structured by the function blocks of the device. It thus contains the following submenus: ▪ **System** contains all device parameters that do not affect either measurement or integration into a distributed control system. ▪ **Measurement** contains all parameters for configuring the measurement. ▪ **Output** contains all parameters for configuring the current output. ▪ **Communication** contains all parameters for configuring the HART interface. ▪ **Diagnosis** contains all parameters required to detect and analyze operating errors.

7.4 Locking/unlocking operation

Once you have entered all the parameters, you can lock your entries against unauthorized and undesired access.

The "Operator code" parameter is used to lock/unlock the device.

Operator code

Navigation Setup → Extended setup → Operator code

Read permission Operator/Service engineers/Expert

Write permission Operator/Service engineers/Expert

Description Use this function to enter a code to lock or unlock operation.

User entry
- To lock: Enter a number ≠ the release code (value range: 1 to 65535).
- To unlock: Enter the release code.

Factory setting 0

Note The release code is "0" in the order configuration. Another release code can be defined in the "Code definition" parameter. If the user has forgotten the release code, the release code can be visible by entering the number "5864".

The release code is defined in the "Code definition" parameter.

Code definition

Navigation Setup → Extended setup → Code definition

Read permission Operator/Service engineers/Expert

Write permission Operator/Service engineers/Expert

Description Use this function to enter a release code with which the device can be unlocked.

User entry A number from 0 to 9999

Factory setting 0

Note The device setup can also be disabled on the RIA15 via a 4-digit user code.
Additional information is available in the RIA15 Operating Instructions BA01170K.

7.5 Resetting to factory settings (reset)

By entering a certain code, you can completely or partially reset the entries for the parameters to the factory settings [1]. Enter the code via the "Enter reset code" parameter (menu path: "Diagnosis" → "Enter reset code").

There are various reset codes for the device. The following table illustrates which parameters are reset by the particular reset codes. To perform a reset, operation must be unlocked (see the "Locking/unlocking operation" section).→ 38

Any customer-specific configuration carried out at the factory is not affected by a reset (customer-specific configuration remains). If you want to change the customer-specific configuration carried out at the factory, please contact Endress+Hauser Service. As there is no separate service level, the order code and serial number can be changed without a specific release code.

1) . The factory setting for the individual parameters is specified in the parameter description

Reset code [1]	Description and effect
62	**PowerUp reset (warm start)** ▪ The device is restarted. ▪ Data is read back anew from the EEPROM (process is reinitialized). ▪ Any simulation which may be running is ended.
333	**User reset** ▪ This code resets all the parameters apart from: - Device tag - Linearization table - Operating hours - Event logbook - Curr. trim 4 mA - Curr. trim 20 mA ▪ Any simulation which may be running is ended. ▪ The device is restarted.
7864	**Total reset** ▪ This code resets all the parameters apart from: - Operating hours - Event logbook ▪ Any simulation which may be running is ended. ▪ The device is restarted.

1) To be entered in "System" → "Management" → "Enter reset code"

After a "Total reset" in FieldCare you have to press the "refresh" button in order to ensure that the measuring units are also reset.

8 Integrating device via HART® protocol

Version data for the device

Firmware version	01.00.zz	▪ On the title page of the Operating instructions ▪ On nameplate → 🖹 15 ▪ **Firmware Version** parameter Diagnosis→ Instrument info → Firmware version
Manufacturer ID	17 (0x11)	**Manufacturer ID.** parameter Diagnosis → Instrument info→ Manufacturer ID
Device type code	36 (0x24)	**Device type code** parameter Diagnosis → Instrument info → Device type code
HART protocol revision	6.0	---
Device revision	1	▪ On nameplate → 🖹 15 ▪ **Device revision** parameter Diagnosis→ Instrument info → Device revision

The suitable device description file (DD) for the individual operating tools is listed in the table below, along with information on where the file can be acquired.

Operating tools

Operating tool	Reference sources for device descriptions (DD and DTM)
FieldCare	▪ www.endress.com → Downloads area ▪ CD–ROM (contact Endress+Hauser) ▪ DVD (contact Endress+Hauser)
AMS Device Manager (Emerson Process Management)	www.endress.com → Downloads area
SIMATIC PDM (Siemens)	www.endress.com → Downloads area
Field Communicator 375, 475 (Emerson Process Management)	Use update function of handheld terminal

8.1 HART process variables and measured values

The following numbers are assigned to the process variables in the factory:

Process variable	Pressure	Level	
		Linear	Table active
First process variable (Primary variable)	0 (Pressure measured)	8 (Level before linearization)	9 (Tank content)
Second process variable (Secondary variable)	2 (Corrected press.)	0 (Pressure measured)	8 (Level before linearization)

Process variable	Pressure	Level	
		Linear	Table active
Third process variable (Tertiary variable)	3 (Sensor pressure)	2 (Corrected press.)	0 (Pressure measured)
Fourth process variable (Quaternary variable)	4 (Sensor temp.)		

The assignment of the device variables to the process variable is displayed in the **Expert → Communication → HART output** menu.

The assignment of the device variables to the process variable (SV, TV, QV) can be changed using HART command 51.

An overview of the possible device variables can be found in the following section.

8.2 Device variables and measured values

The following measured values are assigned to the individual device variables:

Device variable code	Device variable	Measured value	Operating mode
0	PRESSURE_1_FINAL_VALUE	Pressure measured	All
1	PRESSURE_1_AFTER_DAMPING	Pressure af.damp	All
2	PRESSURE_1_AFTER_CALIBRATION	Corrected press.	All
3	PRESSURE_1_AFTER_SENSOR	Corrected press.	All
4	MEASURED_TEMPERATURE_1	Sensor temp.	All
8	MEASURED_LEVEL_AFTER_ SIMULATION	Level before lin.	Only level
9	MEASURED_TANK_CONTENT_AFTER_ SIMULATION	Tank content	Only level
10	CORRECTED_MEASUREMENT_ DENSITY	Process density	Only level
12	HART_INPUT_VALUE [1)]	HART input val.	-
251	None (no device variable is mapped)	-	All (but only for quaternary variable)

1) Cannot be selected as an output

The device variables can be queried from a HART® master using HART® command 9 or 33.

9 Commissioning

NOTICE

If a pressure smaller than the minimum permitted pressure or greater than the maximum permitted pressure is present at the device, the following messages are output in succession:

- "S140 Working range P" or "F140 Working range P" (depending on the setting in the "Alarm behav. P" parameter)
- "S841 Sensor range" or "F841 Sensor range" (depending on the setting in the "Alarm behav. P" parameter)
- "S971 Adjustment" (depending on setting in "Alarm behav. P" parameter

9.1 Post-installation check and function check

Before commissioning your measuring point, ensure that the post-installation and post-connection check have been performed.

- "Post-installation check" checklist→ 25
- "Post-connection check" checklist→ 35

9.2 Unlocking/locking configuration

If the device is locked to prevent configuration, it must first be unlocked.

9.2.1 Locking/unlocking software

If the device is locked via the software (device access code), the key symbol appears in the measured value display. If an attempt is made to write to a parameter, a prompt for the device access code appears. To unlock, enter the user-defined device access code.

9.3 Commissioning

Commissioning comprises the following steps:

- Function check→ 43
- Selection of the measuring mode and pressure unit → 43
- Position adjustment → 44
- Configuring measurement:
  - Pressure measurement→ 46
  - Level measurement → 48

9.4 Measuring mode selection

The device is configured for the "Pressure" measuring mode as standard. The measuring range and the unit in which the measured value is transmitted correspond to the data on the nameplate.

WARNING

Changing the measuring mode affects the span (URV)

This situation can result in product overflow.

- If the measuring mode is changed, the setting for the span (URV) must be checked in the "Setup" operating menu and readjusted if necessary.

Measuring mode

Navigation Setup → Measuring mode

Write permission Operator/Service engineers/Expert

Description Select the measuring mode.
The operating menu is structured differently depending on the measuring mode selected.

Options
- Pressure
- Level

Factory setting Level

9.5 For selecting the pressure engineering unit

Press. eng. unit

Navigation Setup → Press. eng. unit

Write permission Operator/Service engineers/Expert

Description Select the pressure engineering unit. If a new pressure engineering unit is selected, all pressure-specific parameters are converted and displayed with the new unit.

Options
- mbar, bar
- mmH2O, mH2O, inH2O
- ftH2O
- Pa, kPa, MPa
- psi
- mmHg, inHg
- kgf/cm^2

Factory setting mbar or bar depending on the nominal measuring range of the sensor module, or as per order specifications.

9.6 Position adjustment

The pressure resulting from the orientation of the device can be corrected here.

Pos. zero adjust (gauge pressure sensor)

Navigation Setup → Pos. zero adjust

Write permission Operator/Service engineers/Expert

Description Position adjustment – the pressure difference between zero (set point) and the measured pressure need not be known.

Options
- Confirm
- Cancel

Example
- Measured value = 2.2 mbar (0.033 psi)
- You correct the measured value via the "Pos. zero adjust" parameter with the "Confirm" option. This means that you are assigning the value 0.0 to the pressure present.
- Measured value (after pos. zero adjust) = 0.0 mbar
- The current value is also corrected.

Factory setting Cancel

Calib. offset

Write permission Service engineers/Expert

Description Position adjustment – the pressure difference between the set point and the measured pressure must be known.

Example
- Measured value = 982.2 mbar (14.73 psi)
- You correct the measured value with the value entered (e.g. 2.2 mbar (0.033 psi)) via the "Calib. Offset" parameter. This means that you are assigning the value 980.0 (14.7 psi) to the pressure present.
- Measured value (after pos. zero adjust) = 980.0 mbar (14.7 psi)
- The current value is also corrected.

Factory setting 0.0

9.7 Configuring the damping

The output signal follows measured value changes with the delay time. This can be configured via the operating menu.

Damping

Navigation Setup → Damping

Write permission Operator/Service engineers/Expert
(if the "Damping" DIP switch is set to "on")

Description Enter damping time (time constant τ) ("Damping" DIP switch set to "on")
Display damping time (time constant τ) ("Damping" DIP switch set to "off").
The damping affects the speed at which the measured value reacts to changes in pressure.

Input range 0.0 to 999.0 s

Factory setting 2.0 sec. or according to order specifications

9.8 Configuring pressure measurement

9.8.1 Calibration with reference pressure (wet calibration)

Example:

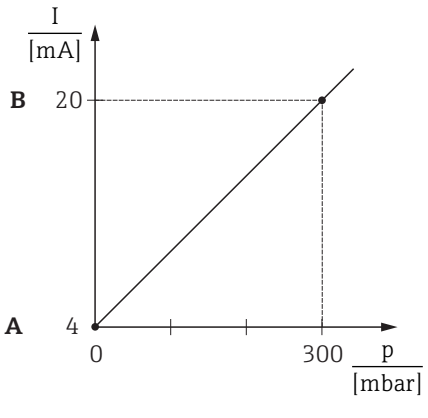
In this example, a device with a 400 mbar (6 psi) sensor module is configured for the 0 to +300 mbar (0 to 4.5 psi) measuring range, i.e. 0 mbar and 300 mbar (4.5 psi) are assigned, respectively, to the 4 mA value and the 20 mA value.

Prerequisite:

The pressure values 0 mbar and 300 mbar (4.5 psi) can be specified. For example, the device is already installed.

Due to the orientation of the device, there may be pressure shifts in the measured value, i.e. the measured value is not zero in a pressureless condition. For information on how to perform position adjustment, see → 44.

	Description
1	Select the "Pressure" measuring mode via the "Measuring Mode" parameter. Menu path: Setup → Measuring mode **WARNING** **Changing the measuring mode affects the span (URV)** This situation can result in product overflow. ► If the measuring mode is changed, the setting for the span (URV) must be checked in the "Setup" operating menu and readjusted if necessary.
2	Select a pressure unit via the "Press eng. unit" parameter, here "mbar" for example. Menu path: Setup → Press. eng. unit
3	The pressure for the LRV (4 mA value) is present at the device, here 0 mbar for example
	Select the "Get LRV" parameter. Menu path: Setup → Extended setup → Current output → Get LRV
	Confirm the present value by selecting "Apply". The present pressure value is assigned to the lower current value (4 mA).
4	The pressure for the URV (20 mA value) is present at the device, here 300 mbar (4.5 psi) for example.
	Select the "Get URV" parameter. Menu path: Setup → Extended setup → Current output → Get URV
	Confirm the present value by selecting "Apply". The present pressure value is assigned to the upper current value (20 mA).
5	Result: The measuring range is configured for 0 to +300 mbar (0 to 4.5 psi).



A See table, step 3.
B See table, step 4.

9.8.2 Calibration without reference pressure (dry calibration)

Example:

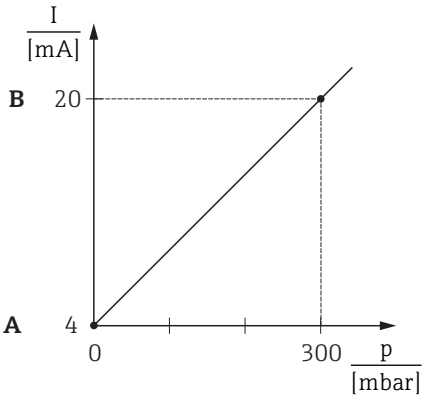
In this example, a device with a 400 mbar (6 psi) sensor module is configured for the 0 to +300 mbar (0 to 4.5 psi) measuring range, i.e. 0 mbar and 300 mbar (4.5 psi) are assigned, respectively, to the 4 mA value and the 20 mA value.

Prerequisite:

This is a theoretical calibration, i.e. the pressure values for the lower and upper range are known.

Due to the orientation of the device, there may be pressure shifts in the measured value, i.e. the measured value is not zero in a pressureless condition. For information on how to perform position adjustment, see → 44.

	Description
1	Select the "Pressure" measuring mode via the "Measuring Mode" parameter. Menu path: Setup → Measuring mode **WARNING** **Changing the measuring mode affects the span (URV)** This situation can result in product overflow. ▶ If the measuring mode is changed, the setting for the span (URV) must be checked in the "Setup" operating menu and readjusted if necessary.
2	Select a pressure unit via the "Press eng. unit" parameter, here "mbar" for example. Menu path: Setup → Press. eng. unit
3	Select the "Set LRV" parameter. Menu path: Setup → Extended setup → Current output → Set LRV
	Enter the value for the "Set LRV" parameter (here 0 mbar) and confirm. This pressure value is assigned to the lower current value (4 mA).
4	Select the "Set URV" parameter. Menu path: Setup → Extended setup → Current output → Set URV
	Enter the value for the "Set URV" parameter, here 300 mbar (4.5 psi), and confirm. This pressure value is assigned to the upper current value (20 mA).
5	Result: The measuring range is configured for 0 to +300 mbar (0 to 4.5 psi).



A *See table, step 3.*
B *See table, step 4.*

9.9 Configuring level measurement

9.9.1 Information on level measurement

You have a choice of two methods for calculating the level: "In pressure" and "In height". The table in the "Overview of level measurement" section that follows provides you with an overview of these two measuring tasks.

- The limit values are not checked, i.e. the values entered must be appropriate for the sensor module and the measuring task for the device to be able to measure correctly.
- Customer-specific units are not possible.
- The values entered for "Empty calib./Full calib.", "Empty pressure/Full pressure", "Empty height/Full height" and "Set LRV/Set URV" must be at least 1% apart. The value will be rejected, and a message displayed, if the values are too close together.

9.9.2 Overview of level measurement

Measuring task	Level selection	Measured variable options	Description	Measured value display
Calibration is performed by entering two pressure-level value pairs.	"In pressure"	Via the "Output unit" parameter: %, level, volume or mass units	▪ Calibration with reference pressure (wet calibration) → 🖹 50 ▪ Calibration without reference pressure (dry calibration)→ 🖹 48	The measured value display and the "Level before lin" parameter display the measured value.
Calibration is performed by entering the density and two height-level value pairs.	"In height"		▪ Calibration with reference pressure (wet calibration) → 🖹 54 ▪ Calibration without reference pressure (dry calibration)→ 🖹 52	

9.9.3 "In pressure" level selection Calibration without reference pressure (dry calibration)

Example:

In this example, the volume in a tank should be measured in liters. The maximum volume of 1 000 l (264 gal) corresponds to a pressure of 400 mbar (6 psi).

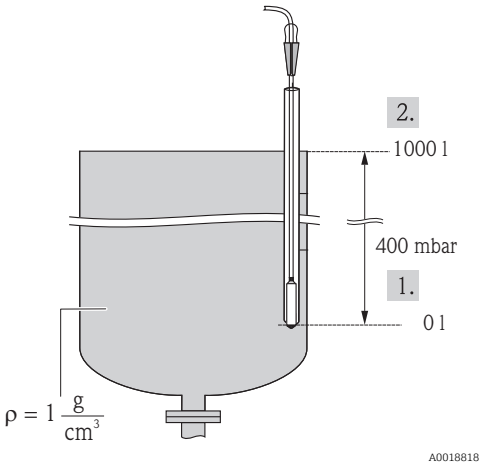
The minimum volume of 0 liters corresponds to a pressure of 0 mbar since the process isolating diaphragm of the probe is at the start of the level measuring range.

Prerequisite:

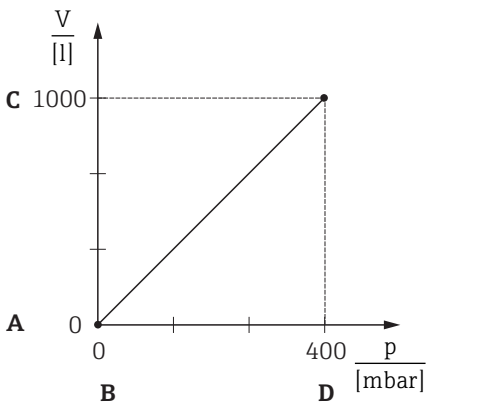
- The measured variable is in direct proportion to the pressure.
- This is a theoretical calibration i.e. the pressure and volume values for the lower and upper calibration point must be known.

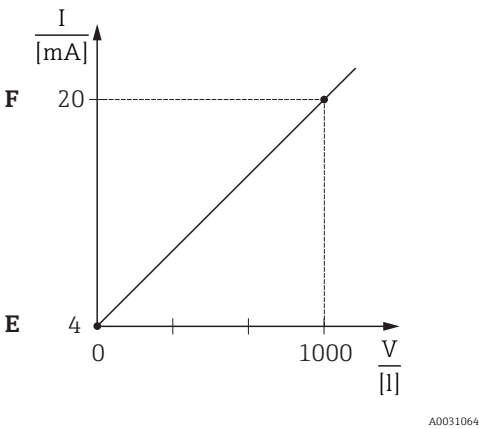
- The values entered for "Empty calib./Full calib.", "Empty pressure/Full pressure" and "Set LRV/Set URV" must be at least 1% apart. The value will be rejected, and a message displayed, if the values are too close together. Further limit values are not checked, i.e. the values entered must be appropriate for the sensor module and the measuring task for the device to be able to measure correctly.
- Due to the orientation of the device, there may be pressure shifts in the measured value, i.e. when the vessel is empty or partly filled, the measured value is not zero. For information on how to perform position adjustment, see → 🖹 44.

	Description
1	Select the "Level" measuring mode via the "Measuring mode" parameter. Menu path: Setup → Measuring mode **⚠ WARNING** **Changing the measuring mode affects the span (URV)** This situation can result in product overflow. ▶ If the measuring mode is changed, the setting for the span (URV) must be checked in the "Setup" operating menu and readjusted if necessary.
2	Select a pressure unit via the "Press eng. unit" parameter, here "mbar" for example. Menu path: Setup → Press. eng. unit
3	Select the "In pressure" level mode via the "Level selection" parameter. Menu path: Setup → Extended setup → Level → Level selection.
4	Select a volume unit via the "Output unit" parameter, here "l" (liters) for example. Menu path: Setup → Extended setup → Level → Output unit
5	Select the "Dry" option via the "Calibration mode" parameter. Menu path: Setup → Extended setup → Level → Calibration mode
6	Enter the volume value for the lower calibration point via the "Empty calib." parameter, here 0 liters for example. Menu path: Setup → Extended setup → Level → Empty calib.
7	Enter the pressure value for the lower calibration point via the "Empty pressure" parameter, here "0 mbar" for example. Menu path: Setup → Extended setup → Level → Empty pressure
8	Enter the volume value for the upper calibration point via the "Full calib." parameter, here 1 000 l (264 gal) for example. Menu path: Setup → Extended setup → Level → Full calib.
9	Enter the pressure value for the upper calibration point via the "Full pressure" parameter, here 400 mbar (6 psi) for example. Menu path: Setup → Extended setup → Level → Full pressure
10	"Adjust density" contains the factory setting 1.0 but can be changed if required. The value pairs subsequently entered must correspond to this density. Menu path: Setup → Extended setup → Level → Adjust density
11	Set the volume value for the lower current value (4 mA) via the "Set LRV" parameter (0 l). Menu path: Setup → Extended setup → Current output → Set LRV
12	Set the volume value for the upper current value (20 mA) via the "Set URV" parameter(1 000 l (264 gal)). Menu path: Setup → Extended setup → Current output → Set URV



1 See table, steps 6 and 7.
2 See table, steps 8 and 9.





A See table, step 6.
B See table, step 7.
C See table, step 8.
D See table, step 9.
E See table, step 11
F See table, step 12

	Description	
13	If the process uses a medium other than that on which the calibration was based, the new density must be specified in the "Process density" parameter. Menu path: Setup → Extended setup → Current output → Process density.	
14	If density correction is required, assign the temperature probe in the "Auto dens. corr." parameter. A density correction is only possible for water. A temperature-density curve that is saved in the device is used. For this reason, the "Adjust density" (step 10) and "Process density" (step 13) parameters are not used here. Menu path: Expert → Application → Level → Auto dens. corr.	
15	Result: The measuring range is configured for 0 to 1 000 l (0 to 264 gal).	

For this level mode, the measured variables %, level, volume and mass are available, see "Output unit" → 94.

9.9.4 "In pressure" level selection Calibration with reference pressure (wet calibration)

Example:

In this example, the level in a tank should be measured in "m". The maximum level is 3 m (9.8 ft).

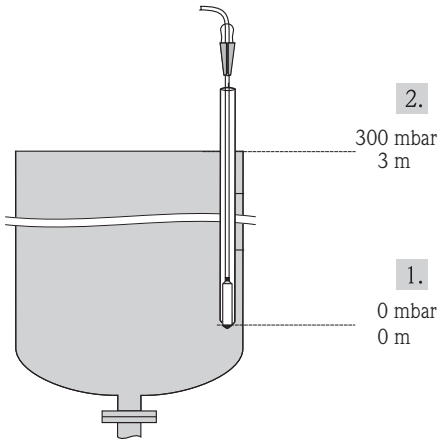
The pressure range is derived from the level and the density of the medium. In this situation, the device sets the pressure range to 0 to +300 mbar (0 to 4.5 psi).

Prerequisite:

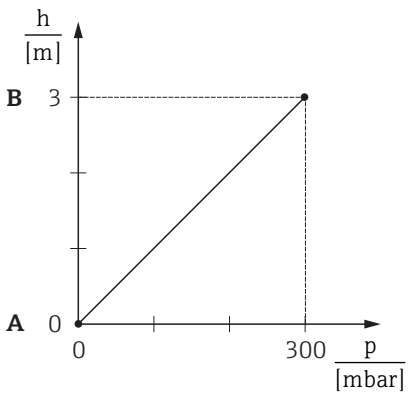
- The measured variable is in direct proportion to the pressure.
- The tank can be filled and emptied.

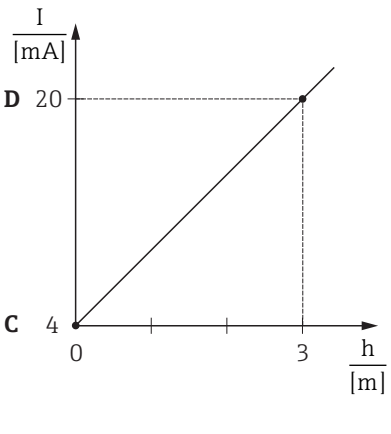
The values entered for "Empty calib./Full calib." and" Set LRV/Set URV" and the pressures present must be at least 1% apart. The value will be rejected, and a message displayed, if the values are too close together. Other limit values are not checked, i.e. the values entered must be appropriate for the sensor and the measuring task for the device to be able to measure correctly.

	Description
1	Perform "position adjustment"→ 🖹 44.
2	Select the "Level" measuring mode via the "Measuring mode" parameter. Menu path: Setup → Measuring mode **⚠ WARNING** **Changing the measuring mode affects the span (URV)** This situation can result in product overflow. ▶ If the measuring mode is changed, the setting for the span (URV) must be checked in the "Setup" operating menu and readjusted if necessary.
3	Select a pressure unit via the "Press eng. unit" parameter, here "mbar" for example. Menu path: Setup → Press. eng. unit
4	Select the "In pressure" level mode via the "Level selection" parameter. Menu path: Setup → Extended setup → Level → Level selection.
5	If density correction is required, assign the temperature probe in the "Auto dens. corr." parameter. Menu path: Expert → Application → Auto dens. corr. A density correction is only possible for water. A temperature-density curve that is saved in the device is used. For this reason, the "Adjust density" (step 8) and "Process density" (step 13) parameters are not used here.
6	Select a level unit via the "Output unit" parameter, here "m" for example. Menu path: Setup → Extended setup → Level → Output unit
7	Select the "Wet" option via the "Calibration mode" parameter. Menu path: Setup → Extended setup → Level → Calibration mode
8	If the calibration is performed with a medium other than the process medium, enter the density of the calibration medium in the "Adjust density" parameter. Menu path: Setup → Extended setup → Level → Adjust density ℹ The process density can be changed only if automatic density correction is switched off (see step 5).
9	The hydrostatic pressure for the lower calibration point is present at the device, here "0 mbar" for example.
	Select the "Empty calib." parameter. Menu path: Setup → Extended setup → Level → Empty calib.
	Enter the level value, here 0 m for example. The pressure value present is assigned to the lower level value by confirming the value.
10	The hydrostatic pressure for the upper calibration point is present at the device, here 300 mbar (4.35 psi) for example.



1 See table, step 9.
2 See table, step 10.





A See table, step 9.
B See table, step 10.
C See table, step 11.
D See table, step 12.

	Description	
	Select the "Full calib." parameter. Menu path: Setup → Extended setup → Level → Full calib.	
	Enter the level value, here 3 m (9.8 ft) for example. The pressure value present is assigned to the upper level value by confirming the value.	
11	Use the "Set LRV" parameter to set the level value for the lower current value (4 mA), here "0 m" for example. Menu path: Setup → Extended setup → Current output → Set LRV	
12	Use the "Set URV" parameter to set the upper current value (20 mA) (3 m (9.8 ft)). Menu path: Setup → Extended setup → Current output → Set URV	
12	If the process uses a medium other than that on which the calibration was based, the new density must be specified in the "Process density" parameter. Menu path: Setup → Extended setup → Level → Process density. The process density can be changed only if automatic density correction is switched off (see step 5).	
13	Result: The measuring range is configured for 0 to 3 m (0 to 9.8 ft).	

For this level mode, the measured variables %, level, volume and mass are available, see "Output unit". → 94.

9.9.5 "In height" level selection Calibration without reference pressure (dry calibration)

Example:

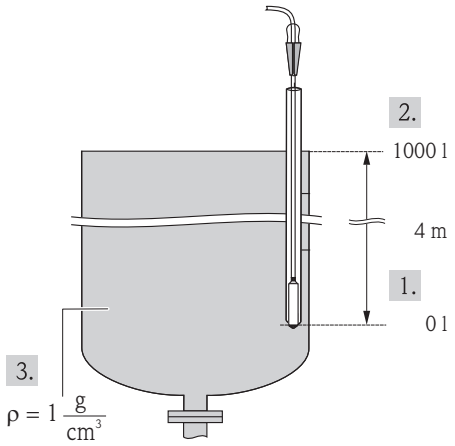
In this example, the volume in a tank should be measured in liters. The maximum volume of 1 000 l (264 gal) corresponds to a level of 4 m (13 ft). The minimum volume of 0 liter corresponds to a level of 0 m since the process isolating diaphragm of the probe is at the start of the level measuring range.

Prerequisite:

- The measured variable is in direct proportion to the pressure.
- This is a theoretical calibration i.e. the height and volume values for the lower and upper calibration point must be known.

- The values entered for "Empty calib./Full calib.", "Empty height/Full height" and" Set LRV/Set URV" must be at least 1% apart. The value will be rejected, and a message displayed, if the values are too close together. Other limit values are not checked, i.e. the values entered must be appropriate for the sensor and the measuring task for the device to be able to measure correctly.
- Due to the orientation of the device, there may be pressure shifts in the measured value, i.e. when the vessel is empty or partly filled, the measured value is not zero. For information on how to perform position adjustment, see → 44.

	Description
1	Select the "Level" measuring mode via the "Measuring mode" parameter. Menu path: Setup → Measuring mode **⚠ WARNING** **Changing the measuring mode affects the span (URV)** This situation can result in product overflow. ▶ If the measuring mode is changed, the setting for the span (URV) must be checked in the "Setup" operating menu and readjusted if necessary.
2	Select a pressure unit via the "Press eng. unit" parameter, here "mbar" for example. Menu path: Setup → Press. eng. unit
3	Select the "In height" level mode via the "Level selection" parameter. Menu path: Setup → Extended setup → Level → Level selection.
4	If density correction is required, assign the temperature probe in the "Auto dens. corr." parameter. Menu path: Setup → Extended setup → Level → Level selection.
4	Select a volume unit via the "Output unit" parameter, here "l" (liters) for example. Menu path: Setup → Extended setup → Level → Output unit A density correction is only possible for water. A temperature-density curve that is saved in the device is used. For this reason, the "Adjust density" (step 12) and "Process density" (step 15) parameters are not used here.
5	Select a volume unit via the "Output unit" parameter, here "l" (liters) for example. Menu path: Setup → Extended setup → Level → Output unit
6	Select a level unit via the "Height unit" parameter, here "m" for example. Menu path: Setup → Extended setup → Level → Height unit
7	Select the "Dry" option via the "Calibration mode" parameter. Menu path: Setup → Extended setup → Level → Calibration mode
8	Enter the volume value for the lower calibration point via the "Empty calib." parameter, here 0 liters for example. Menu path: Setup → Extended setup → Level → Empty calib.
9	Enter the height value for the lower calibration point via the "Empty height" parameter, here 0 m for example. Menu path: Setup → Extended setup → Level → Empty height
10	Enter the volume value for the upper calibration point via the "Full calib." parameter, here 1 000 l (264 gal) for example. Menu path: Setup → Extended setup → Level → Full calib.



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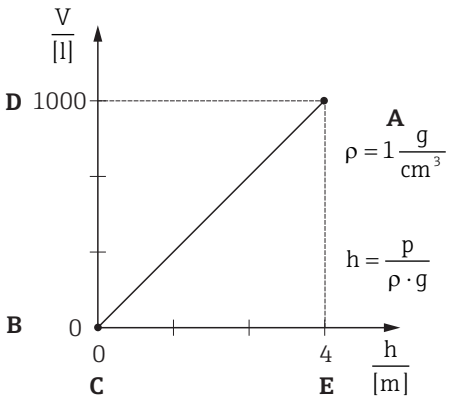
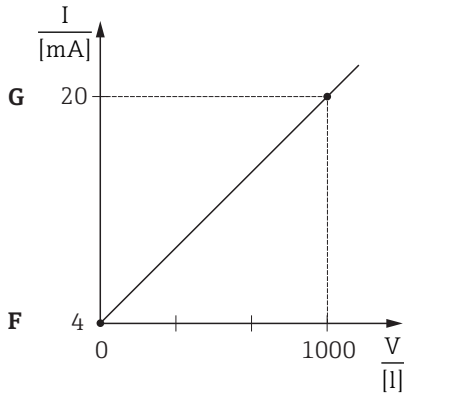
1 See table, steps 10 and 11.
2 See table, steps 13 and 14.
3 See table, step 12



A0017666



A0031067

A See table, step 12.
B See table, step 8.
C See table, step 9.
D See table, step 10.
E See table, step 11.
F See table, step 13.
G See table, step 14.

	Description	
11	Enter the height value for the upper calibration point via the "Full height" parameter, here 4 m (13 ft) for example. Menu path: Setup → Extended setup → Level → Full height	
12	Enter the density of the medium via the "Adjust density" parameter, here "1 g/cm³" (1 SGU) for example. Menu path: Setup → Extended setup → Level → Adjust density	
13	Set the volume value for the lower current value (4 mA) via the "Set LRV" parameter (0 l). Menu path: Setup → Extended setup → Current output → Set LRV	
14	Set the volume value for the upper current value (20 mA) via the "Set URV" parameter (1 000 l (264 gal)). Menu path: Setup → Extended setup → Current output → Set URV	
15	If the process uses a medium other than that on which the calibration was based, the new density must be specified in the "Process density" parameter. Menu path: Setup → Extended setup → Current output → Process density. The process density can only be changed if automatic density correction is switched off (see Step 4).	
16	Result: The measuring range is configured for 0 to 1 000 l (0 to 264 gal).	

For this level mode, the measured variables %, level, volume and mass are available, see "Output unit". → 94.

9.9.6 "In height" level selection Calibration with reference pressure (wet calibration)

Example:

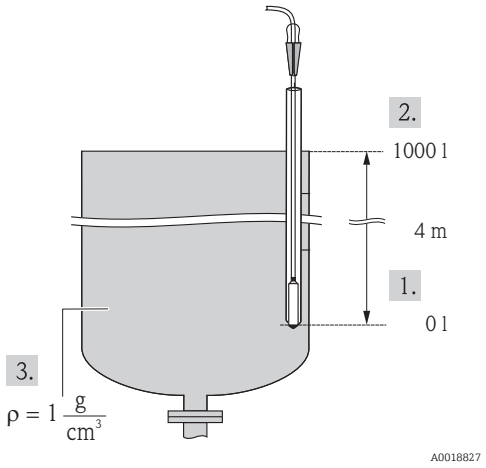
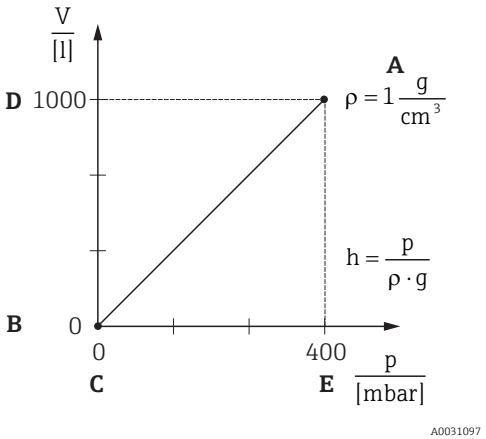
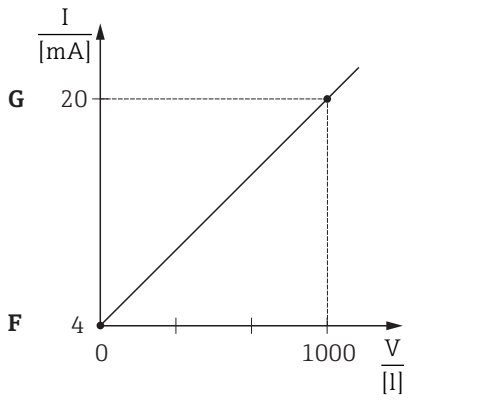
In this example, the volume in a tank should be measured in liters. The maximum volume of 1 000 l (264 gal) corresponds to a level of 4 m (13 ft).

The minimum volume of 0 liter corresponds to a level of 0 m since the process isolating diaphragm of the probe is at the start of the level measuring range. The density of the fluid is 1 g/cm³ (1 SGU).

Prerequisite:

- The measured variable is in direct proportion to the pressure.
- The tank can be filled and emptied.

The values entered for "Empty calib./Full calib." and" Set LRV/Set URV" and the pressures present must be at least 1% apart. The value will be rejected, and a message displayed, if the values are too close together. Other limit values are not checked, i.e. the values entered must be appropriate for the sensor and the measuring task for the device to be able to measure correctly.

	Description	
1	Perform "position adjustment"→ 🖹 44.	 A0018827 *1 See table, step 9.* *2 See table, step 10.* *3 See table, step 11.*
2	Select the "Level" measuring mode via the "Measuring mode" parameter. Menu path: Setup → Measuring mode **⚠ WARNING** **Changing the measuring mode affects the span (URV)** This situation can result in product overflow. ▶ If the measuring mode is changed, the setting for the span (URV) must be checked in the "Setup" operating menu and readjusted if necessary.	
3	Select the "In height" level mode via the "Level selection" parameter. Menu path: Setup → Extended setup → Level → Level selection.	
4	If density correction is required, assign the temperature probe in the "Auto dens. corr." parameter. Menu path: Expert → Application → Auto dens. corr. A density correction is only possible for water. A temperature-density curve that is saved in the device is used. For this reason, the "Adjust density" (step 11) and "Process density" (step 14) parameters are not used here.	
5	Select a pressure unit via the "Press eng. unit" parameter, here "mbar" for example. Menu path: Setup → Press. eng. unit	 A0031097
6	Select a volume unit via the "Output unit" parameter, here "l" (liters) for example Menu path: Setup → Extended setup → Level → Output unit	
7	Select a height unit via the "Height unit" parameter, here "m" for example. Menu path: Setup → Extended setup → Level → Height unit	
8	Select the "Wet" option via the "Calibration mode" parameter. Menu path: Setup → Extended setup → Level → Calibration mode	
9	The hydrostatic pressure for the lower calibration point is present at the device, here "0 mbar" for example.	 A0031067 *A See table, step 11.* *B See table, step 9.* *C See table, step 9.* *D See table, step 10.*
	Enter the volume value for the lower calibration point via the "Empty calib." parameter, here "0 liters" for example. Menu path: Setup → Extended setup → Level → Empty calib.	
10	The hydrostatic pressure for the upper calibration point is present at the device, here "400 mbar (6 psi)" for example.	
	Enter the volume value for the upper calibration point via the "Full calib." parameter, here 1 000 l (264 gal) for example. Menu path: Setup → Extended setup → Level → Full calib.	

	Description	
11	If the calibration is performed with a medium other than the process medium, enter the density of the calibration medium in the "Adjust density" parameter, here 1 g/cm³ (1 SGU) for example. Menu path: Setup → Extended setup → Level → Adjust density The process density can only be changed if automatic density correction is switched off (see Step 4).	*E See table, step 10.* *F See table, step 12.* *G See table, step 13.*
12	Set the volume value for the lower current value (4 mA) via the "Set LRV" parameter (0 l). Menu path: Setup → Extended setup → Current output → Set LRV	
13	Set the volume value for the upper current value (20 mA) via the "Set URV" parameter(1 000 l (264 gal)). Menu path: Setup → Extended setup → Current output → Set URV	
14	If the process uses a medium other than that on which the calibration was based, the new density must be specified in the "Process density" parameter. Menu path: Setup → Extended setup → Level → Process density. The process density can only be changed if automatic density correction is switched off (see Step 4).	
15	Result: The measuring range is configured for 0 to 1 000 l (0 to 264 gal).	

For this level mode, the measured variables %, level, volume and mass are available, see "Output unit". → 94.

9.9.7 Calibration with partially filled vessel (wet calibration)

Example:

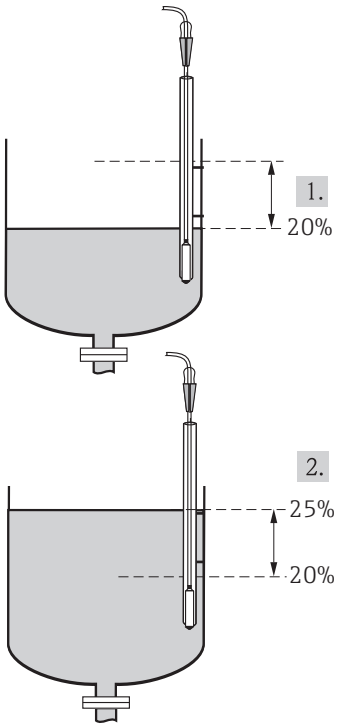
This example explains a wet calibration for cases in which it is not possible to empty the vessel and then fill it to 100%.

During this wet calibration, a level of 20% is used as the calibration point for "Empty" and a level of "25%" is used as the calibration point for "Full".

The calibration is then extended to 0% to 100% and lower range-value (LRV)/upper range-value (URV) are adapted accordingly.

Prerequisite:

- The default value in level mode for the calibration mode is "Wet".
- This value can be adjusted: Menu path: Setup → Extended setup → Level → Calibration mode

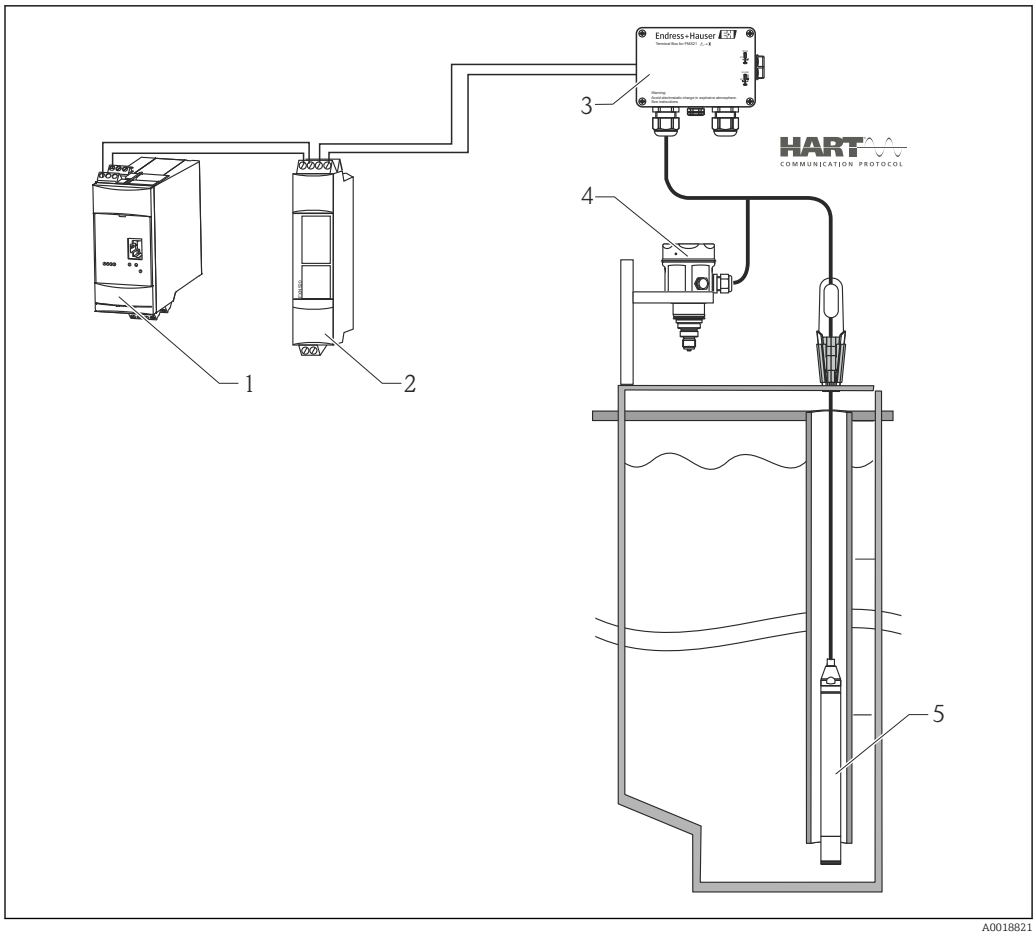
	Description	
1	Select the "Level" measuring mode via the "Measuring mode" parameter. Menu path: Setup → Measuring mode **⚠ WARNING** **Changing the measuring mode affects the span (URV)** This situation can result in product overflow. ▶ If the measuring mode is changed, the setting for the span (URV) must be checked in the "Setup" operating menu and readjusted if necessary.	 *1 See table, step 2* *2 See table, step 3*
2	Set the value for "Empty calib." with the acting pressure for the level, e.g. 20% Menu path: Setup → Extended setup → Level → Empty calib.	
3	Set the value for "Full calib." with the acting pressure for the level, e.g. 25%. Menu path: Setup → Extended setup → Level → Full calib.	
4	The values for the pressure when the vessel is full or empty are measured automatically during adjustment. The transmitter automatically sets the pressure values that are most suitable for "Empty calib." and "Full calib." as the minimum and maximum pressure which generates the output current. For this reason, the correct upper-range value (URV) and the correct lower-range value (LRV) must be set.	

If the process uses a medium other than that on which the calibration was based, the new density must be specified in the "Process density" parameter. In this case, you have to enter the various densities via the following menu path:
- Setup → Extended setup → Level→ Adjust Density (034) (e.g. 1.0 kg/l for water)
- Setup → Extended setup → Level → Process Density (035) (e.g. 0.8 kg/l for oil)

9.9.8 Level measurement with absolute pressure probe and external pressure signal (electrical differential pressure)

Example:

In this example, a Waterpilot FMX21 and a Cerabar M (each with an absolute pressure measuring cell) are connected via the common communication bus. The level can thus be measured in a deep well, with simultaneous compensation for the effect of atmospheric pressure.



1 *Fieldgate FXA520*
2 *Multidrop Connector FXN520*
3 *Terminal box (can be ordered as an accessory)*
4 *Cerabar M absolute pressure (level)*
5 *Waterpilot absolute pressure (pressure)*

	Sensor level adjustment (Waterpilot)
1	Select the "Pressure" measuring mode via the "Measuring Mode" parameter. Menu path: Setup → Measuring mode **⚠ WARNING** **Changing the measuring mode affects the span (URV)** This situation can result in product overflow. ► If the measuring mode is changed, the setting for the span (URV) must be checked in the "Setup" operating menu and readjusted if necessary.
2	Select a pressure unit via the "Press eng. unit" parameter, here "mbar" for example. Menu path: Setup → Press. eng. unit
3	The sensor is unpressurized, perform a position adjustment → 📄 44
4	Switch on burst mode via the "Burst mode" parameter. Menu path: Expert → Communication → HART config
5	Set the output current to "Fixed" 4.0 mA via the "Current Mode" parameter. Menu path: Expert → Communication → HART config
6	Configure an address ≠0 using the "Bus address" parameter, e.g. bus address = 1. (HART 5.0 master: Range 0 to 15, where address = 0 calls up the "Signaling" setting; HART 6.0 master: Range 0 to 63) Menu path: Expert → Communication → HART config

	Sensor level adjustment (Cerabar)
1	Select the "Level" measuring mode via the "Measuring mode" parameter. Menu path: Setup → Measuring mode **⚠ WARNING** **Changing the measuring mode affects the span (URV)** This situation can result in product overflow. ▶ If the measuring mode is changed, the setting for the span (URV) must be checked in the "Setup" operating menu and readjusted if necessary.
2	Select a pressure unit via the "Press eng. unit" parameter, here "mbar" for example. Menu path: Setup → Press. eng. unit
3	The sensor is unpressurized, perform a position adjustment → 📄 44
4	Set the output current to "Fixed" 4.0 mA via the "Current Mode" parameter. Menu path: Expert → Communication → HART config
5	Configure an address ≠0 using the "Bus address" parameter, e.g. bus address = 2. (HART 5.0 master: Range 0 to 15, where address = 0 calls up the "Signaling" setting; HART 6.0 master: Range 0 to 63) Menu path: Expert → Communication → HART config
6	Activate the reading of a value sent externally in burst mode via the "Electr. Delta P" parameter. Menu path: Expert → Application
7	Perform level adjustment (wet or dry)
8	Result: The measured value output by the atmospheric pressure sensor equals the level in the deep well (differential signal) and can be read out by means of a HART request for the address of the atmospheric pressure sensor.

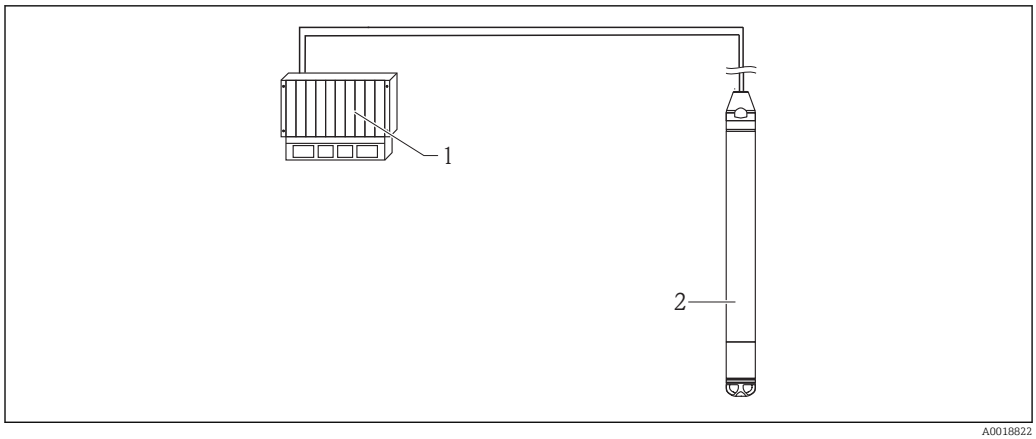
- It is not permissible to reverse the assignment of the measuring points to the direction of communication.
- The measured value of the transmitting device (via burst) must always be greater than the measured value of the receiving device (via "Electr. Delta P" mode).
- Adjustments that involve an offset in the pressure values (e.g. position adjustment, trim) must always suit the individual sensor and the sensor's orientation irrespective of the "Electr. Delta P" application.
- Other settings result in non-permitted use of the "Electr. Delta P" mode and can lead to incorrect measured values.

9.10 Automatic density compensation

9.10.1 Automatic density compensation with the internally measured sensor temperature

Example:

In this example, a Waterpilot FMX21 is used for level measurement in water. The change in the water density caused by changing temperatures is automatically factored into the level signal by activating the automatic density compensation.



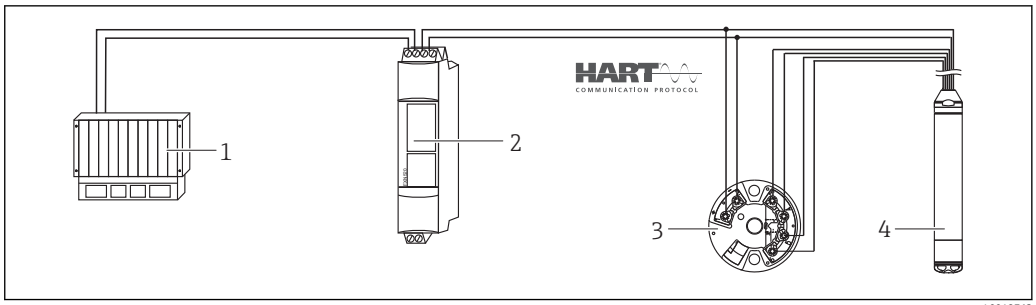
1 HART master, e.g. PLC (programmable logic controller)
2 Waterpilot FMX21

	Waterpilot adjustment for level measurement
1	Select the "Level" measuring mode via the "Measuring mode" parameter. Menu path: Setup → Measuring mode **⚠ WARNING** **Changing the measuring mode affects the span (URV)** This situation can result in product overflow. ▶ If the measuring mode is changed, the setting for the span (URV) must be checked in the "Setup" operating menu and readjusted if necessary.
2	Select a pressure unit via the "Press eng. unit" parameter, here "mbar" for example. Menu path: Setup → Press. eng. unit
3	The sensor is unpressurized, perform a position adjustment → 🖹 44
4	Set the "Auto dens. corr." parameter to Sensor temperature. Menu path: Expert → Application
5	Perform level adjustment (wet or dry)
6	Result: The measured value output by the Waterpilot corresponds to the level in the deep well corrected by means of the density characteristic line of water.

9.10.2 Automatic density compensation using an integrated Pt100 for calculation in a suitable HART master (e.g. PLC)

Example:

In this example, the FMX21 with an integrated Pt100 is connected via the common communication bus to any temperature head transmitter with HART communication (e.g. TMT182). The temperature and pressure signal is transmitted to the HART master (e.g. PLC), where a corrected level value can be generated using a stored linearization table or density function (of a chosen medium). A pressure signal and a temperature signal can thus be generated with a chosen density function to compensate for a level.



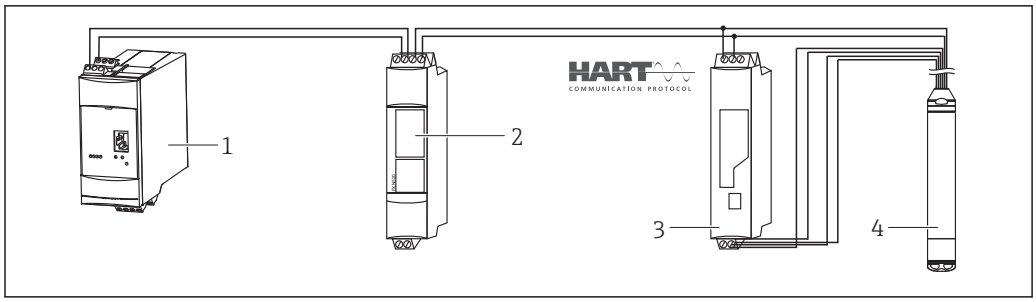
1 *HART master, PLC (programmable logic controller)*
2 *Multidrop Connector FXN520*
3 *TMT182 temperature head transmitter*
4 *Waterpilot FMX21*

	Waterpilot adjustment for level measurement
1	Select the "Level" measuring mode via the "Measuring mode" parameter. Menu path: Setup → Measuring mode **⚠ WARNING** **Changing the measuring mode affects the span (URV)** This situation can result in product overflow. ▶ If the measuring mode is changed, the setting for the span (URV) must be checked in the "Setup" operating menu and readjusted if necessary.
2	Select a pressure unit via the "Press eng. unit" parameter, here "mbar" for example. Menu path: Setup → Press. eng. unit
3	The sensor is unpressurized, perform a position adjustment → 🖹 44
4	Set the output current to "Fixed" 4.0 mA via the "Current Mode" parameter. Menu path: Expert → Communication → HART config
5	Perform level adjustment (wet or dry)
6	Configure an address ≠0 using the "Bus address" parameter, e.g. bus address = 1. (HART 5.0 master: Range 0 to 15, where address = 0 calls up the "Signaling" setting; HART 6.0 master: Range 0 to 63) Menu path: Expert → Communication → HART config ℹ The output current of the temperature head transmitter used must also be set to "Fixed" and have a HART address other than zero (e.g. address = 2).
7	Switch on burst mode via the "Burst mode" parameter. Menu path: Expert → Communication → HART config
8	Result: by balancing the pressure signal and temperature signal in a suitable HART master (e.g. PLC), a corrected level value can be determined for any medium by using a suitable density function.

9.10.3 Automatic density compensation using an external temperature signal for calculation in the FMX21

Example:

In this example, the FMX21 with an integrated Pt100 is connected to a HART-compliant temperature transmitter via the common communication bus. With this option, the signal of the Pt100 is evaluated with a HART-compliant temperature head transmitter (min. HART 5.0) that supports the burst mode. The change in the water density caused by changing temperatures is automatically factored into the level signal by activating the automatic density compensation.



A0018764

1 *Fieldgate FXA520*
2 *Multidrop Connector FXN520*
3 *HART-compatible temperature transmitter (e.g. TMT82)*
4 *Waterpilot FMX21*

	Configuring the HART-compliant temperature head transmitter (min. HART 5.0) with burst function
	The output current of the temperature transmitter used should be set to "Fixed" and a HART address other than zero (e.g. address = 1) must be set. The burst function must then be switched on with HART command 1. This step should be performed before the procedure described below in order to avoid a HART input error of the FMX21 being output during commissioning.
1	Select the "Level" measuring mode via the "Measuring mode" parameter. Menu path: Setup → Measuring mode **⚠ WARNING** **Changing the measuring mode affects the span (URV)** This situation can result in product overflow. ► If the measuring mode is changed, the setting for the span (URV) must be checked in the "Setup" operating menu and readjusted if necessary.
2	Select a pressure unit via the "Press eng. unit" parameter, here "mbar" for example. Menu path: Setup → Press. eng. unit
3	The sensor is unpressurized, perform a position adjustment → 🖹 44
4	Set the "Auto dens. corr." parameter to "External value". Menu path: Expert → Application
5	Perform level adjustment (wet or dry)
	Result: The measured value output by the Waterpilot corresponds to the level in the deep well corrected by means of the density characteristic line of water.

The TMT182 temperature head transmitter is not suitable for this configuration.

9.11 Linearization

9.11.1 Semi-automatic entry of a linearization table

Example:

In this example, the volume in a tank with a conical outlet should be measured in m^3.

Prerequisite:

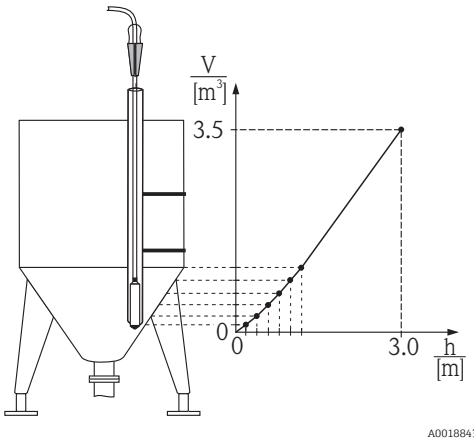
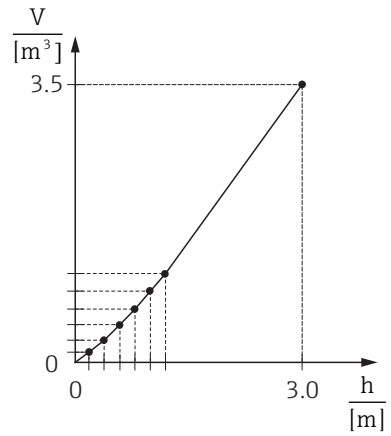
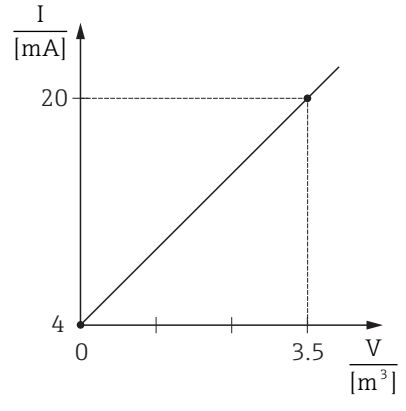
- The tank can be filled or emptied. The linearization characteristic must rise or fall continuously.
- The "Level" measuring mode has been selected.
- A level calibration has been performed.
- For a description of the parameters mentioned, see the "Description of device parameters" section→ 86.

WARNING

Changing the measuring mode affects the span (URV)

This situation can result in product overflow.

- ▶ If the measuring mode is changed, the setting for the span (URV) must be checked in the "Setup" operating menu and readjusted if necessary.

	Description	
1	Select the "Semiautom. entry" option via the "Lin. mode" parameter. Menu path: Setup → Extended setup → Linearization → Lin. mode	 A0018843
2	Select using the "Unit before lin." e.g. m^3. Menu path: Setup → Extended setup → Linearization → Unit after lin.	
3	Fill the tank to the height of the 1st point.	
4	Enter the number of the point in the table using the "Line-numb" parameter e.g. 1. Menu path: Setup → Extended setup → Linearization → Line numb	 A0031098
	The current level is displayed via the "X-value" parameter. Menu path: Setup → Extended setup → Linearization → X-val	
	Using the "Y-val." parameter, enter the corresponding volume value, here 0 m^3 for example, and confirm the value. Menu path: Setup → Extended setup → Linearization → Y-val	
5	To enter another point in the table, continue filling the tank and select the "Next point" option via the "Edit table" parameter. Enter the next point as explained in Step 4. Menu path: Setup → Extended setup → Linearization → Edit table	 A0031031

	Description	
6	Once all the points have been entered in the table, select the "Activate table" option via the "Lin. mode" parameter. Menu path: Setup → Extended setup → Linearization → Lin. mode	
7	Result: Result: The measured value after linearization is displayed.	

- Error message F510 "Linearization" and alarm current as long as the table is being entered and until the table is activated.
- The lower-range value (= 4mA) is defined by the smallest point in the table. The upper-range value (= 20mA) is defined by the largest point in the table.
- Using the parameters "Set LRV" and "Set URV", you can change the allocation of the volume/mass values to the current values.

9.11.2 Manual entry of a linearization table

Example:

In this example, the volume in a tank with a conical outlet should be measured in m^3.

Prerequisite:

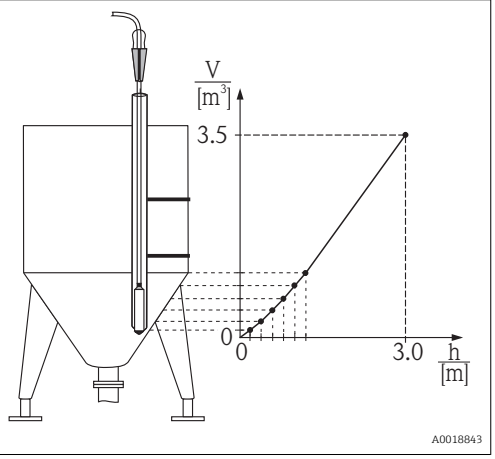
- This is a theoretical calibration, i.e. the points for the linearization table are known.
- The "Level" measuring mode has been selected.
- A level calibration has been performed.
- The linearization characteristic must rise or fall continuously.
- For a description of the parameters mentioned, see the "Description of device parameters" section→ 86.

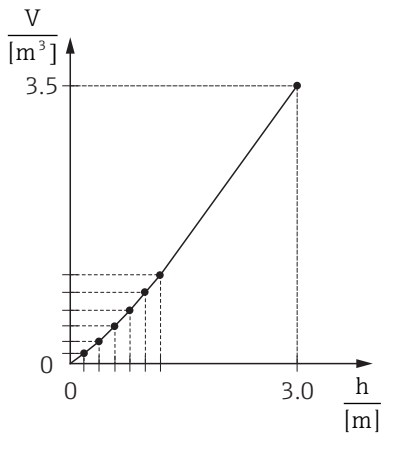
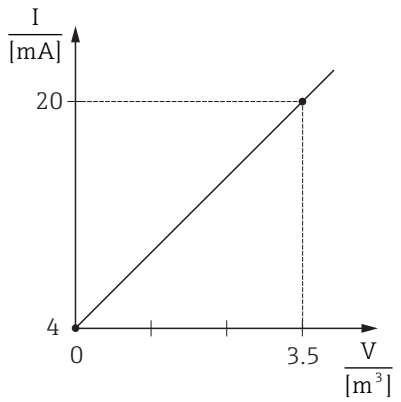
WARNING

Changing the measuring mode affects the span (URV)

This situation can result in product overflow.

▶ If the measuring mode is changed, the setting for the span (URV) must be checked in the "Setup" operating menu and readjusted if necessary.

	Description	
1	Select the "Manual entry" option via the "Lin. mode" parameter. Menu path: Setup → Extended setup → Linearization → Lin. mode	
2	Select using the "Unit after lin." e.g. m^3. Menu path: Setup → Extended setup → Linearization → Unit after lin.	

	Description	
3	Enter the number of the point in the table using the "Line-numb" parameter e.g. 1. Menu path: Setup → Extended setup → Linearization → Line numb	 A0031098  A0031031
	The level is entered via the "X-value" parameter, here 0 m for example. Confirm your entry. Menu path: Setup → Extended setup → Linearization → X-val	
	Using the "Y-val." parameter, enter the corresponding volume value, here 0 m^3 for example, and confirm the value. Menu path: Setup → Extended setup → Linearization → Y-val	
4	To enter another point in the table, select the "Next point" option via the "Edit table" parameter. Enter the next point as explained in Step 3. Menu path: Setup → Extended setup → Linearization → Edit table	
5	Once all the points have been entered in the table, select the "Activate table" option via the "Lin. mode" parameter. Menu path: Setup → Extended setup → Linearization → Lin. mode	
6	Result: Result: The measured value after linearization is displayed.	

- Error message F510 "Linearization" and alarm current as long as the table is being entered and until the table is activated.
- Error message F511/F512 "Linearization" and alarm current as long as the linearization table consists of fewer than 2 points.
- The lower-range value (= 4mA) is defined by the smallest point in the table. The upper-range value (= 20mA) is defined by the largest point in the table.
- Using the parameters "Set LRV" and "Set URV", you can change the allocation of the volume/mass values to the current values.

9.12 Manual entry of a linearization table via operating tool

Using an operating tool based on FDT technology (e.g. FieldCare), you can enter linearization using a module specially designed for this purpose. This provides you with an overview of the selected linearization, even during entry. In addition, it is possible to configure different tank shapes in FieldCare ("Device operation" → "Device functions" → "Additional functions" → "Linearization table" menu).

The linearization table may also be entered manually point by point in the operating tool menu (see Section → 86).

9.13 Backing up or duplicating the device data

The following options are available to you with an operating tool that is based on FDT technology (e.g. FieldCare):
- Storage/recovery of configuration data.
- Duplication of device parameters.
- Transfer of all relevant parameters when replacing electronic inserts.

Use the following parameter for this:

Download select. (visible only in FieldCare)

Navigation Expert → System → Management → Download select.

Write permission Operator/Service engineers/Expert

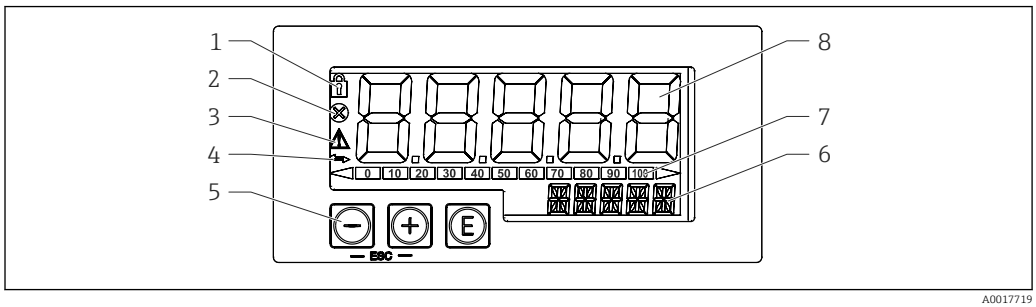
Description Selection of data packages for up/download function in Fieldcare and PDM.

Prerequisite DIP switch set to "SW" and "Damping" set to "on". If you download using the factory setting "Configuration copy", all parameters required for a measurement will be downloaded. The functionality of the "Electronics replace" setting is reserved for Endress+Hauser Service and can be accessed only if the correct device access code is entered.

Options
- Configuration copy: This option overwrites general configuration parameters with the exception of the serial number, order number, calibration, pos. zero adjust, application and day information.
- Device replacement: This option overwrites general configuration parameters with the exception of the serial number, order number, calibration and position adjustment.
- Electronics replace: This option overwrites general configuration parameters.

Factory setting Configuration copy

9.14 Operation and settings via RIA15



6 Display and operating elements of the process display unit

1 Symbol: operating menu disabled
2 Symbol: error
3 Symbol: warning
4 Symbol: HART communication active
5 Operating keys "-", "+", "E"
6 14-segment display for unit/TAG
7 Bar graph with indicators for under range and over range
8 5-digit 7-segment display for measured value, digit height 17 mm (0.67 in)

The device is operated using three operating keys on the front of the housing. The device setup can be disabled with a 4-digit user code. If the setup is disabled, a padlock symbol appears on the display when an operating parameter is selected.

 A0017716	Enter key; calling up the operating menu, confirming the option/setting parameters in the operating menu
 A0017715	Selecting and setting/changing values in the operating menu; pressing the '-' and '+' keys simultaneously takes the user back up a menu level. The configured value is not saved.
 A0017714	

9.14.1 Operating functions

The operating functions of the process display unit are divided into the following menus. The individual parameters and settings are described in the "Commissioning" section.

If the operating menu is disabled by means of a user code, the individual menus and parameters can be displayed but not changed. To change a parameter, the user code must be entered. As the display unit can only display digits in the 7-segment display and not alphanumeric characters, the procedure for number parameters is different to that for text parameters. If the operating position contains only numbers as parameters, the operating position is displayed in the 14-segment display and the configured parameter is displayed in the 7-segment display. To edit, press the 'E'-button followed by the user code. If the operating position contains text parameters, only the operating position is initially displayed in the 14-segment display. If the 'E' button is pressed again, the configured parameter is displayed in the 14-segment display. To edit, press the '+' button followed by the user code.

Setup (SETUP)	Basic device settings
Diagnostics (DIAG)	Device information, display of error messages
Expert (EXPRT)	Expert settings for device setup. The Expert menu is protected from editing by an access code (default 0000).

9.14.2 Operating modes

The process display unit can be used in two different operating modes:

- 4 to 20 mA mode:
  In this operating mode, the process display unit is incorporated into the 4 to 20 mA current loop and measures the transmitted current. The variable calculated based on the current value and range limits is displayed in digital form on the 5-digit LCD. In addition, the associated unit and a bar graph can be displayed.
- HART mode:
  The display unit is powered via the current loop.
  The FMX21 can be adjusted under the "Level" menu (see operating matrix). The measured value displayed corresponds to the measured level.
  HART communication operates according to the master/slave principle.

For additional information, see BA01170K.

9.14.3 Operating matrix

After power-up:

- Press the E key twice
  - The "Level" menu is then available

Using the following operating matrix, a display in percent can be set. To do this, select "Mode" parameter => 4-20 and "Unit" parameter =>%

Setup -> Level (LEVEL) menu					
The LEVEL menu is only visible if the RIA15 has been ordered with the "Level" option and the display unit is operated in the HART mode (MODE = HART). The basic settings for the Waterpilot FMX21 level sensor can be made via the RIA15 with this menu.					
RIA15 parameter		**Corresponds to parameter of FMX21**	**Values (default=bold)**	**Visible with**	**Description**
LEVEL [1]		Level before linearization		Level option MODE = HART FMX21 connected	This menu contains the parameters for configuring the pressure measuring device for hydrostatic level measurement, FMX21. The basic settings for the FMX21 can be made via the RIA15 with this menu. Once the LEVEL menu item is opened, the following parameters are automatically adjusted for easier operation: ▪ Measuring mode: Level ▪ Calibration mode: Dry ▪ Level selection: In pressure ▪ Lin mode: Linear It is possible to reset these parameters to the factory default settings by performing a reset.
	PUNIT	Press. eng. unit	**mbar** [2] **bar** [2] kPa PSI		Use this function to select the unit for pressure
	LUNIT	Output unit	**%** m inch feet		Use this function to select the unit for level
	TUNIT	Temperature unit	**°C** °F K		Use this function to select the unit for temperature
	ZERO	Pos. zero adjust	**NO** YES	Gauge pressure sensor	For performing a position adjustment (gauge pressure sensor). The value 0.0 is assigned to the pressure value present. The current value is also corrected.
	P_LRV	Empty pressure	-1999.9 to 9999.9 Default: Gauge pressure sensor: Sensor LRL Absolute pressure sensor: 0		Pressure empty calibration using keys -,+,E More in-depth description / valid value range: any value in the range indicated [1] [3] Number of decimal places depends on the configured pressure unit.
	P_URV	Full pressure	-1999.9 ... 9999.9 Default: Sensor URL		Pressure full calibration using keys -,+,E More in-depth description / valid value range: any value in the range indicated [1] [3] Number of decimal places depends on the configured pressure unit.
	EMPTY	Empty calib.	-1999.9 to 9999.9 Default: 0		Level empty calibration using keys -,+, E More in-depth description / valid value range: any value in the range indicated [1] [3] Number of decimal places depends on the configured level unit.
	FULL	Full calib.	-1999.9 ... 9999.9 Default: 100		Level full calibration using keys -,+, E More in-depth description / valid value range: any value in the range indicated [1] [3] Number of decimal places depends on the configured level unit.

Setup -> Level (LEVEL) menu					
The LEVEL menu is only visible if the RIA15 has been ordered with the "Level" option and the display unit is operated in the HART mode (MODE = HART). The basic settings for the Waterpilot FMX21 level sensor can be made via the RIA15 with this menu.					
RIA15 parameter		**Corresponds to parameter of FMX21**	**Values (default=bold)**	**Visible with**	**Description**
	LEVEL	Level before linearization	Measured value		Displays the measured level Number of decimal places depends on the configured level unit.
	RESET	Enter reset code	**NO** YES		Reset the FMX21 to factory defaults

1) If the measured value that is read out is too large, it is displayed as "9999.9", for example. To display a valid measured value, the pressure unit (PUNIT) (or level unit (LUNIT)) must be set to suit the measuring range.
2) Default: depends on the sensor nominal range or as per order specifications
3) The values entered for "Empty calib./Full calib.", "Empty pressure/Full pressure" and "Set LRV/Set URV" must be at least 1% apart. The value will be rejected, and a message displayed, if the values are too close together. Further limit values are not checked, i.e. the values entered must be appropriate for the sensor module and the measuring task for the device to be able to measure correctly.

Any additional settings such as linearizations must be made using FieldCare or DeviceCare.

Additional information is available in the RIA15 Operating Instructions BA01170K.

10 Diagnostics and troubleshooting

10.1 Troubleshooting

General errors

Error	Possible cause	Solution
Device is not responding.	Supply voltage does not match the specification on the nameplate.	Apply correct voltage.
	Supply voltage has incorrect polarity.	Reverse polarity of supply voltage.
	Connecting cables are not in contact with the terminals.	Check the connection of the cables and correct if necessary.
Output current < 3.6 mA	Signal line is not wired correctly. Electronics unit is defective.	Check wiring.
Device measures incorrectly.	Configuration error.	Check and correct parameter configuration (see below).
HART communication is not working.	Communication resistor missing or incorrectly installed.	Install the communication resistor (250 Ω) correctly.
	Commubox is connected incorrectly.	Connect Commubox correctly.
	Commubox is not set to "HART".	Set Commubox selector switch to "HART".
RIA15 no display	The polarity of the supply voltage is wrong	Correct the polarity
RIA15 no display	The cables do not contact the terminals properly	Ensure electrical contact between the cable and the terminal
RIA15 no display	RIA15 defective	Replace RIA15
RIA15 start sequence keeps running through	Supply voltage too low	▪ Increase supply voltage ▪ Switch off backlight

10.2 Diagnostic events in the operating tool

10.2.1 Diagnostic message

Faults detected by the self-monitoring system of the measuring device are displayed as a diagnostic message in alternation with the measured value display.

Status signals

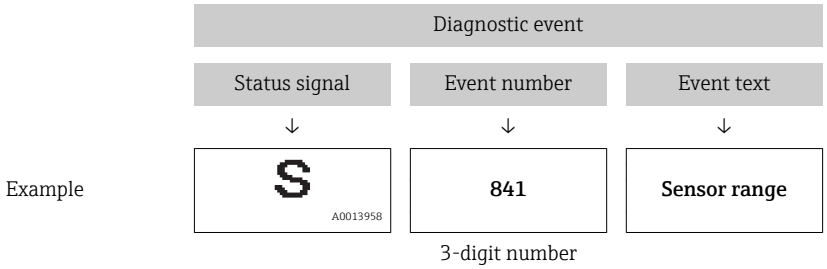
The table → 📄 71 lists the messages that may occur. The ALARM STATUS parameter shows the message with the highest priority. The device has four different status information codes according to NE107:

F A0013956	**"Failure"** A device error has occurred. The measured value is no longer valid.
M A0013957	**"Maintenance required"** Maintenance is required. The measured value remains valid.
C A0013959	**"Function check"** The device is in service mode (e.g. during a simulation).
S A0013958	**"Out of specification"** The device is being operated: ▪ Outside its technical specifications (e.g. during warm-up or cleaning). ▪ Outside of the configuration carried out by the user (e.g. level outside configured span)

Diagnostic event and event text

The fault can be identified by means of the diagnostic event.

The event text helps you by providing information on the fault.



If two or more diagnostic events are pending simultaneously, only the diagnostic message with the highest priority is shown.

Other diagnostic messages that are pending can be viewed in the **Diagnostic list** submenu → 120.

Past diagnostic messages that are no longer pending are shown in the **Event logbook** submenu→ 121.

10.2.2 Diagnostic event in the RIA15

A diagnostic event of the Waterpilot FMX21 is not directly shown in the RIA15. The fault F911 only appears directly on the RIA15 in the event of an Waterpilot FMX21 alarm.

Displaying a FMX21 diagnostic event in the RIA15

1. Navigate to: DIAG/TERR
2. Press E
3. Press ⊕
4. Press E
5. Press ⊕ 3 times
6. Press E
   ↳ The diagnostic event from the Waterpilot FMX21 is shown on the RIA15 display.

10.2.3 List of diagnostic events

General messages

Diagnostic event		Reason	Corrective measure
Code	Description		
0	No error	-	-

"F" messages

Diagnostic event		Reason	Corrective measure
Code	Description		
F002	Sensor unknown	Sensor does not suit the device (electronic sensor nameplate).	Contact Endress+Hauser Service
F062	Sensor conn.	▪ Faulty sensor. ▪ Electromagnetic effects are greater than specifications in the technical data. This message appears for a short time only.	▪ Check the sensor module cable ▪ Contact Endress+Hauser Service
F081	Initialization	▪ Faulty sensor. ▪ Electromagnetic effects are greater than specifications in the technical data. This message appears for a short time only.	▪ Check sensor cable ▪ Contact Endress+Hauser Service
F083	Memory content	▪ Faulty sensor. ▪ Electromagnetic effects outside the permitted range. This message appears for a short time only.	▪ Restart the device ▪ Contact Endress+Hauser Service
F140	Working range P	▪ Overpressure and low pressure present. ▪ Electromagnetic effects outside the permitted range. ▪ Faulty sensor.	▪ Check the process pressure ▪ Check sensor range
F261	Electronic module	▪ Main electronics defective. ▪ Fault in the main electronics.	Restart the device
F282	Memory	▪ Fault in the main electronics. ▪ Main electronics defective.	Restart the device
F283	Memory content	▪ Main electronics defective. ▪ Electromagnetic effects are greater than specifications in the technical data. ▪ The supply voltage is disconnected when writing. ▪ An error occurred when writing.	Perform a reset
F411	Up-/download	▪ File is defective. ▪ During the download, the data are not correctly transmitted to the processor, e.g. because of open cable connections, spikes (ripple) on the supply voltage or electromagnetic effects.	▪ Repeat download ▪ Use other file ▪ Perform a reset
F510	Linearization	The linearization table is being edited.	▪ Conclude entries ▪ Select "linear"
F511	Linearization	The linearization table consists of less than 2 points.	▪ Table too small ▪ Correct table ▪ Activate table
F512	Linearization	The linearization table is not monotonic increasing or decreasing.	▪ Table not monotonic ▪ Correct table ▪ Activate table
F841	Sensor range	▪ Overpressure or low pressure present. ▪ Faulty sensor.	▪ Check the pressure value ▪ Contact Endress+Hauser Service
F882	Input signal	External measured value is not received or displays a failure status.	▪ Check the bus ▪ Check source device ▪ Check the setting

"M" messages

Diagnostic event		Reason	Corrective measure
Code	Description		
M002	Sens. unknown	Sensor does not suit the device (electronic sensor nameplate). Device continues measuring.	Contact Endress+Hauser Service
M283	Memory content	▪ Cause as indicated for F283. ▪ Correct measurement can continue as long as you do not need the peakhold indicator function.	Perform a reset
M431	Adjustment	The calibration performed would cause the sensor nominal range to be exceeded or undershot.	▪ Check the measuring range ▪ Check position adjustment ▪ Check the setting
M434	Scaling	▪ Values for calibration (e.g. lower range value and upper range value) are too close together. ▪ Lower-range value and/or upper-range value exceed or fall below the range limits of the sensor. ▪ The sensor was replaced and the customer-specific configuration does not suit the sensor module. ▪ Unsuitable download carried out.	▪ Check the measuring range ▪ Check the setting ▪ Contact Endress+Hauser Service
M438	Data set	▪ The supply voltage is disconnected when writing. ▪ An error occurred when writing.	▪ Check the setting ▪ Restart the device
M882	Input signal	External measured value displays a warning status.	▪ Check the bus ▪ Check the source device ▪ Check the setting

"C" messages

Diagnostic event		Reason	Corrective measure
Code	Description		
C412	Backup in prog.	Downloading.	Wait for download to complete.
C482	Simul. output	Simulation of the current output is switched on, i.e. the device is not measuring at present.	End the simulation
C484	Error simul.	Fault state simulation is switched on, i.e. the device is not measuring at present.	End the simulation
C485	Measure simul.	Simulation is switched on, i.e. the device is not measuring at present.	End the simulation
C824	Process pressure	▪ Overpressure or low pressure present. ▪ Electromagnetic effects outside the permitted range. This message appears for a short time only.	▪ Check the pressure value ▪ Restart the device ▪ Perform a reset

"S" messages

Diagnostic event		Reason	Corrective measure
Code	Description		
S110	Operational range T	▪ High temperature or low temperature present. ▪ Electromagnetic effects outside the permitted range. ▪ Faulty sensor.	▪ Check process temperature ▪ Check the temperature range
S140	Working range P LP/HP	▪ Overpressure or low pressure present. ▪ Electromagnetic effects outside the permitted range. ▪ Faulty sensor.	▪ Check the process pressure ▪ Check sensor range

Diagnostic event		Reason	Corrective measure
Code	Description		
S822	Process temp. LP/HP	▪ The temperature measured in the sensor is higher than the upper nominal temperature of the sensor. ▪ The temperature measured in the sensor is lower than the lower nominal temperature of the sensor.	▪ Check temperature ▪ Check the setting
S841	Sensor range	▪ Overpressure or low pressure present. ▪ Faulty sensor.	▪ Check the pressure value ▪ Contact Endress+Hauser Service
S971	Adjustment	▪ The current is outside the permitted range from 3.8 to 20.5 mA. ▪ The present pressure value is outside the configured measuring range (but within the sensor module range, if applicable). ▪ The calibration performed would cause the sensor nominal range to be exceeded or undershot.	▪ Check the pressure value ▪ Check the measuring range ▪ Check the setting

10.3 Troubleshooting specific to Waterpilot FMX21 with optional Pt100

Error description	Reason	Corrective action
No measuring signal	4 to 20 mA cable not connected correctly	Connect device as per → 🖹 26.
	No power supplied via the 4 to 20 mA cable	Check current loop.
	Supply voltage too low (min. 10.5 V DC)	▪ Check supply voltage. ▪ Overall resistance greater than max. load resistance
	Waterpilot is defective	Replace the Waterpilot.
Temperature measured value is inaccurate/incorrect (only for Waterpilot FMX21 with Pt100)	Pt100 connected in 2-wire circuit, cable resistance was not compensated for	▪ Compensate the cable resistance. ▪ Connect Pt100 as 3-wire or 4-wire circuit.

10.4 Troubleshooting specific to TMT182 temperature head transmitter

Error description	Reason	Corrective action
No measuring signal	4 to 20 mA cable not connected correctly	Connect device as per → 🖹 26.
	No power supplied via the 4 to 20 mA cable	Check current loop.
	Supply voltage too low (min. 10.5 V DC)	▪ Check supply voltage. ▪ Overall resistance greater than max. load resistance
Failure current ≤ 3.6 mA or ≥ 21 mA	Pt100 not connected correctly	Connect device as per → 🖹 26.
	4 to 20 mA cable not connected correctly	Connect device as per → 🖹 26.
	Pt100 resistance thermometer defective	Replace the Waterpilot.

Error description	Reason	Corrective action
	Temperature head transmitter defective	Replace the temperature head transmitter.
Measured value is inaccurate/ incorrect	Pt100 connected in 2-wire circuit, cable resistance was not compensated for (for more information see BA00139R)	▪ Compensate the cable resistance. ▪ Connect Pt100 as 3-wire or 4-wire circuit.

10.5 Response of output to errors

The behavior of the current output in case of fault is defined by the following parameters:

- "Alarm behav. P (050)"
- "Output fail mode (190)"
- "Max. alarm curr. (052)"

10.6 Firmware history

Date	Firmware version	Modifications	Documentation
05.2009	01.00.zz	Original firmware. Compatible with: ▪ FieldCare version 2.02.00 and higher ▪ Field Communicator DXR375 with Device Rev.: 1, DD Rev.: 1	BA00380P/00/EN/03.09
			BA00380P/00/EN/07.09
			BA00380P/00/EN/08.09
			BA00380P/00/EN/13.11
			BA00380P/00/EN/14.13
			BA00380P/00/EN/15.15
			BA00380P/00/EN/16.16
			BA00380P/00/EN/17.16
			BA00380P/00/EN/18.18

11 Maintenance

- Terminal box: Keep the GORE-TEX® filter free from contamination
- FMX21 extension cable: Keep the Teflon filter in the pressure compensation tube free from contamination
- Check the process isolating diaphragm for buildup at suitable intervals.

11.1 Exterior cleaning

Please note the following points when cleaning the device:

- The cleaning agents used should not corrode the surface and the seals.
- Mechanical damage to the process isolating diaphragm, e.g. due to sharp objects, must be avoided.
- Only clean the terminal box with water or with a cloth dampened with very diluted ethanol.

12 Repairs

12.1 General notes

12.1.1 Repair concept

Repairs are not possible.

12.1.2 Replacing a device

Once a complete device has been replaced, the parameters can be transferred back into the device using FieldCare:

Prerequisite: The configuration of the old device was saved previously to the computer using FieldCare.

You can continue to measure without performing a new calibration.

12.2 Spare parts

All the spare parts for the measuring device along with the order code are listed In the *W@M Device Viewer* (www.endress.com/deviceviewer) and can be ordered. If available, users can also download the associated Installation Instructions.

Measuring device serial number:
- Is located on the nameplate of the device.
- Can be read out via the "Serial number" parameter in the "Instrument info" submenu.

12.3 Return

The measuring device must be returned in the event of a factory calibration, or if the wrong device has been ordered or delivered.

As an ISO-certified company and also due to legal regulations, Endress+Hauser is obliged to follow certain procedures when handling any returned products that have been in contact with medium. To ensure swift, safe and professional device returns, please read the return procedures and conditions on the Endress+Hauser website at www.services.endress.com/return-material

▶ Select country.
  ↳ The web site of the responsible sales office opens with all of the relevant information relating to returns.

1. If the desired country is not listed:
   Click on the "Choose your location" link.
   ↳ An overview of Endress+Hauser sales offices and representatives opens.
2. Contact your Endress+Hauser sales office or representative.

12.4 Disposal

When disposing, separate and recycle the device components based on the materials.

13 Overview of the operating menu

Depending on the parameter configuration, not all submenus and parameters are available. Information on this can be found in the parameter description under "Prerequisite".

Setup	Description
Operating mode	→ 89
Press. eng. unit	→ 91
Corrected press.	→ 93
Pos. zero adjust (relative pressure sensor)	→ 90
Calib. offset (absolute pressure sensor)	→ 90
Empty calib. ("Level" measuring mode and "Calibration mode" = wet)	→ 95
Full calib. ("Level" measuring mode and "Calibration mode" = wet")	→ 96
Set LRV ("Pressure" measuring mode)	→ 92
Set URV ("Pressure" measuring mode)	→ 92
Damping	→ 90
Level before Lin ("Level" measuring mode)	→ 98
Pressure af.damp	→ 93

Setup →	Extended setup	Description
	Code definition	→ 86
	Device tag	→ 87
	Operator code	→ 86

Setup →	Extended setup →	Level ("Level" measuring mode)	Description
		Level selection	→ 94
		Output unit	→ 94
		Height unit	→ 94
		Calibration mode	→ 95
		Empty calib.	→ 95
		Empty pressure	→ 95
		Empty height	→ 96
		Full calib.	→ 96
		Full pressure	→ 96
		Full height	→ 97
		Adjust density	→ 97
		Process density	→ 98
		Level before lin	→ 98

Setup →	Extended setup →	Linearization	Description
		Lin. mode	→ 99
		Unit after lin.	→ 99
		Line-numb:	→ 99

Setup →	Extended setup →	Linearization	Description
		X-val	→ 100
		Y-val	→ 100
		Edit table	→ 100
		Tank description	→ 101
		Tank content	→ 101

Setup →	Extended setup →	Current output	Description
		Alarm behav. P	→ 104
		Output fail mode	→ 104
		Max. alarm curr.	→ 104
		Set min. current	→ 105
		Output current	→ 104
		Get LRV (only "Pressure")	→ 105
		Set LRV	→ 105
		Get URV (only "Pressure")	→ 105
		Set URV	→ 106

Diagnosis	Description
Diagnostic code	→ 118
Last diag. code	→ 118
Min. meas. press.	→ 118
Max. meas. press.	→ 118

Diagnosis →	Diagnostics List	Description
	Diagnostic 1	→ 120
	Diagnostic 2	→ 120
	Diagnostic 3	→ 120
	Diagnostics 4	→ 120
	Diagnostics 5	→ 120
	Diagnostics 6	→ 120
	Diagnostics 7	→ 120
	Diagnostics 8	→ 120
	Diagnostics 9	→ 120
	Diagnostics 10	→ 120

Diagnosis →	Event logbook	Description
	Last diag. 1	→ 121
	Last diag. 2	→ 121
	Last diag. 3	→ 121
	Last diag. 4	→ 121
	Last diag. 5	→ 121
	Last diag. 6	→ 121

Diagnosis →	Event logbook	Description
	Last diag. 7	→ 121
	Last diag. 8	→ 121
	Last diag. 9	→ 121
	Last diag. 10	→ 121

Diagnosis →	Instrument Info	Description
	Firmware Version	→ 87
	Serial number	→ 87
	Ext. order code	→ 87
	Order Identifier	→ 88
	Cust. tag number	→ 87
	Device tag	→ 87
	ENP version	→ 88
	Config. counter	→ 119
	LRL sensor	→ 102
	URL sensor	→ 102
	Manufacturer ID	→ 110
	Device type code	→ 110
	Device revision	→ 110

Diagnosis →	Measured values	Description
	Level before lin	→ 98
	Tank content	→ 101
	Pressure measured	→ 92
	Sensor pressure	→ 92
	Corrected press.	→ 93
	Pressure af.damp	→ 93
	Sensor temp.	→ 91

Diagnosis →	Simulation	Description
	Simulation mode	→ 122
	Sim. pressure	→ 122
	Sim. level	→ 122
	Sim. tank cont.	→ 123
	Sim. current	→ 123
	Sim. alarm/warning	→ 123

Diagnosis →	Enter reset code	Description
	Enter reset code	→ 89

13.1 Overview of parameters in the "Expert" menu

The following table lists all of the parameters that can be included in the "Expert" menu. The page reference indicates where a description of the parameter can be found in the manual.

Depending on the device version and the parameter configuration, not all submenus and parameters are available in every device. Information on this can be found in the parameter description under "Prerequisite".

Expert →	System	Description
	Code definition	→ 86
	Operator code	→ 86

Expert →	System→	Instrument Info	Description
		Cust. tag number	→ 87
		Device tag	→ 87
		Serial number	→ 87
		Firmware Version	→ 87
		Ext. order code	→ 87
		Order Identifier	→ 88
		ENP version	→ 88
		Electr.Serial No	→ 88
		Sensor serial no.	→ 88

Expert →	System→	Administration	Description
		Enter reset code	→ 89

Expert →	Measurement	Description
	Operating mode	→ 89

Expert →	Measurement→	Basic Setup	Description
		Pos. zero adjust	→ 90
		Calib. Offset	→ 90
		Damping	→ 90
		Press. eng. unit	→ 91
		Temp. Eng. Unit	→ 91
		Sensor temp.	→ 91

Expert →	Measurement→	Pressure	Description
		Set LRV	→ 92
		Set URV	→ 92
		Pressure measured	→ 92
		Sensor pressure	→ 92
		Corrected press.	→ 93
		Pressure af.damp	→ 93

Expert →	Measurement→	Level	Description
		Level selection	→ 94
		Output unit	→ 94
		Height unit	→ 94
		Calibration mode	→ 95
		Empty calib.	→ 95
		Empty pressure	→ 95
		Empty height	→ 96
		Full calib.	→ 96
		Full pressure	→ 96
		Full height	→ 97
		Density unit	→ 97
		Adjust density	→ 97
		Process density	→ 98
		Level before lin.	→ 98

Expert →	Measurement→	Linearization	Description
		Lin. mode	→ 99
		Unit after lin.	→ 99
		Line-numb:	→ 99
		X-val	→ 100
		Y-val	→ 100
		Edit table	→ 100
		Tank description	→ 101
		Tank content	→ 101

Expert →	Measurement→	Sensor limits	Description
		Lower range limit	→ 102
		URL sensor	→ 102

Expert →	Measurement→	Sensor trim	Description
		Lo trim measured	→ 103
		Hi trim measured	→ 103
		Lo Trim Sensor	→ 103
		Hi Trim Sensor	→ 103

Expert →	Output→	Current output	Description
		Output current	→ 104
		Alarm behav. P	→ 104
		Output fail mode	→ 104
		Max. alarm curr.	→ 104
		Set min. current	→ 105

Expert →	Output→	Current output	Description
		Get LRV ("Pressure" only)	→ 105
		Set LRV	→ 105
		Get URV ("Pressure" only)	→ 105
		Set URV	→ 106
		Startcurrent	→ 106
		Curr. Trim 4 mA	→ 106
		Curr. Trim 20 mA	→ 107
		Offset Trim 4 mA	→ 107
		Offset Trim 20 mA	→ 107

Expert →	Communication→	HART Config	Description
		Burst Mode	→ 108
		Burst Option	→ 108
		Current Mode	→ 108
		Bus Address	→ 108
		Preamble Number	→ 109

Expert →	Communication→	HART Info	Description
		Device type code	→ 110
		Device revision	→ 110
		Manufacturer ID	→ 110
		HART version	→ 110
		Descriptor	→ 110
		HART Message	→ 110
		HART Date	→ 111

Expert →	Communication→	HART Output	Description
		Primary value is	→ 112
		Primary value	→ 112
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14 Description of device parameters

14.1 Expert → System

Operator code

Write permission Operators/Service engineers/Expert

Description Use this function to enter a code to lock or unlock operation.

User entry
- To lock: Enter a number ≠ the release code (value range: 1 to 9999).
- To unlock: Enter the release code.

Note The release code is "0" in the order configuration. Another release code can be defined in the "Code definition" parameter. If the user has forgotten the release code, the release code can be visible by entering the number "5864".

Factory setting 0

Code definition

Write permission Operators/Service engineers/Expert

Description Use this function to enter a release code with which the device can be unlocked.

Options A number from 0 to 9999

Factory setting 0

14.2 Expert → System → Instrument info

Cust. tag number

Write permission Operators/Service engineers/Expert

Description Enter the device tag, e.g. TAG number (max. 8 alphanumeric characters).

Factory setting No entry or according to order specifications

Device tag

Write permission Operators/Service engineers/Expert

Description Enter the device tag, e.g. TAG number (max. 32 alphanumeric characters).

Factory setting No entry or according to order specifications

Serial number

Write permission Parameter is read only. Only Endress+Hauser Service has write permission.

Description Displays the serial number of the device (11 alphanumeric characters).

Firmware Version

Write permission No write permissions. Parameter is read only.

Description Displays the firmware version.

Ext. order code

Write permission Parameter is read only. Only Endress+Hauser Service has write permission.

Description Displays extended order number.

Factory setting According to order specifications

Order identifier

Write permission Parameter is read only. Only Endress+Hauser Service has write permission.

Description Displays the order identifier.

Factory setting According to order specifications

ENP version

Write permission No write permissions. Parameter is read only.

Description Displays the ENP version
(ENP = electronic nameplate)

Electr.serial no.

Write permission No write permissions. Parameter is read only.

Description Displays the serial number of the main electronics (11 alphanumeric characters).

Sensor serial no.

Write permission No write permissions. Parameter is read only.

Description Displays the serial number of the main electronics (11 alphanumeric characters).

14.3 Expert → System → Management

Enter reset code

Write permission Operators/Service engineers/Expert

Description Reset parameters completely or partially to the factory values or order configuration by entering a reset code, see "Resetting to factory settings (reset)" section.→ 39

Factory setting 0

14.4 Expert → Measurement → Measuring mode

Measuring mode

WARNING

Changing the measuring mode affects the span (URV)
This situation can result in product overflow.
- If the measuring mode is changed, the setting for the span (URV) must be checked in the "Setup" operating menu and readjusted if necessary.

Write permission Operators/Service engineers/Expert

Description Select the measuring mode. The operating menu is structured differently depending on the measuring mode selected.

Options
- Pressure
- Level

Factory setting Pressure or according to order specifications

14.5 Expert → Measurement → Basic setup

Pos. zero adjust

Write permission Operators/Service engineers/Expert

Description Position adjustment – the pressure difference between zero (set point) and the measured pressure need not be known.

Example
- Measured value = 2.2 mbar (0.033 psi)
- You correct the measured value via the "Pos. zero adjust" parameter with the "Confirm" option. This means that you are assigning the value 0.0 to the pressure present.
- Measured value (after position adjustment) = 0.0 mbar
- The current value is also corrected.

Options
- Confirm
- Cancel

Factory setting Cancel

Calib. offset

Write permission Service engineers/Expert

Description Position adjustment – the pressure difference between the set point and the measured pressure must be known.

Example
- Measured value = 982.2 mbar (14.73 psi)
- You correct the measured value with the value entered (e.g. 2.2 mbar (0.033 psi)) via the "Calib. Offset" parameter. This means that you are assigning the value 980.0 (14.7 psi) to the pressure present.
- Measured value (after pos. zero adjust) = 980.0 mbar (14.7 psi)
- The current value is also corrected.

Factory setting 0.0

Damping

Write permission Operators/Service engineers/Expert
(if the "Damping" DIP switch is set to "on")

Description Enter damping time (time constant τ).
The damping affects the speed at which the measured value reacts to changes in pressure.

Input range 0.0 to 999.0 s

Factory setting 2.0 sec. or according to order specifications

Press. eng. unit

Write permission Operators/Service engineers/Expert

Description Select the pressure engineering unit. If a new pressure engineering unit is selected, all pressure-specific parameters are converted and displayed with the new unit.

Options
- mbar, bar
- mmH2O, mH2O, inH2O
- ftH2O
- Pa, kPa, MPa
- psi
- mmHg, inHg
- kgf/cm^2

Factory setting mbar or bar depending on the nominal measuring range of the sensor module, or as per order specifications

Temp. eng. unit

Write permission Service engineers/Expert

Description Select the unit for the temperature measured values.

Options
- °C
- °F
- K

Note The setting affects the unit for the "Sensor temp." parameter.

Factory setting °C

Sensor temp.

Write permission No write permissions. Parameter is read only.

Description Displays the temperature currently measured in the sensor module. This can deviate from the process temperature.

14.6 Expert → Measurement → Pressure

Set LRV

Write permission Operators/Service engineers/Expert

Description Set the pressure value, level or content for the lower current value (4 mA).

Factory setting
- 0.0 % in Level measuring mode
- 0.0 mbar/bar or in accordance with ordering information in Pressure measuring mode

Set URV

Write permission Operators/Service engineers/Expert

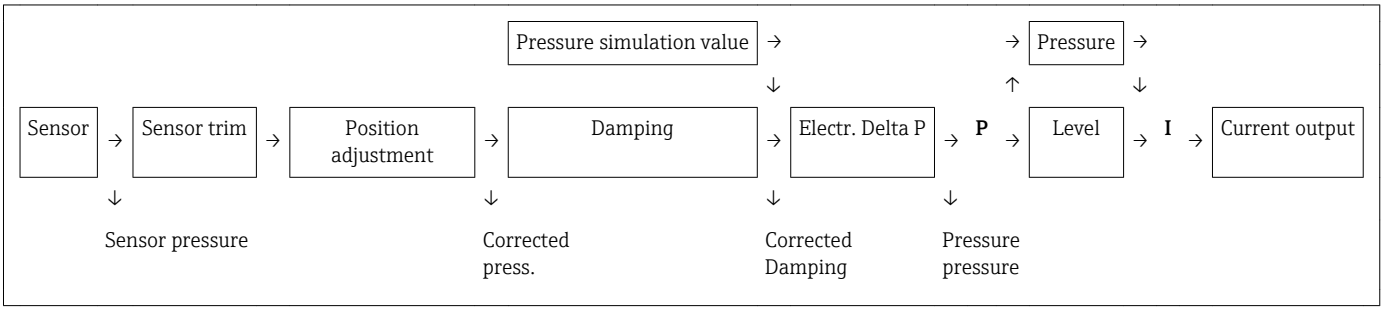
Description Set the pressure value, level or content for the upper current value (20 mA).

Factory setting
- 100.0 % in Level measuring mode
- URL Sensor or according to ordering information in Pressure measuring mode

Meas. pressure

Write permission No write permissions. Parameter is read only.

Description Displays the measured pressure after sensor trim, position adjustment and damping.



Sensor pressure

Write permission No write permissions. Parameter is read only.

Description Displays the measured pressure before the sensor trim.

Corrected press.

Write permission No write permissions. Parameter is read only.

Description Displays the measured pressure after sensor trim and position adjustment.

Pressure af.damp

Write permission No write permissions. Parameter is read only.

Description Displays the measured pressure after sensor trim, position adjustment and damping.

14.7 Expert → Measurement → Level

Level selection

Write permission Operators/Service engineers/Expert

Description Select the method for calculating the level

Options
- In pressure
  If this option is selected, specify two pressure/level value pairs. The level value is displayed directly in the unit that you select via the "Output unit" parameter.
- In height
  If this option is selected, specify two height/level value pairs. From the measured pressure, the device first calculates the height using the density. This information is then used to calculate the level in the "Output unit" selected using the two value pairs specified.

Factory setting In pressure

Output unit

Description Select the unit for the measured value display for the level before linearization.

Note The selected unit is used only to describe the measured value i.e. when a new output unit is selected, the measured value is not converted.

Example
- Current measured value: 0.3 ft
- New output unit: m
- New measured value: 0.3 m

Options
- %
- mm, cm, dm, m
- ft, inch
- m^3, in^3
- l, hl
- ft^3
- gal, Igal
- kg, t
- lb

Factory setting %

Height unit

Write permission Operators/Service engineers/Expert

Description Select the height unit. The measured pressure is converted to the selected height unit using the "Adjust Density" parameter.

Prerequisite "Level selection" = "In height"

Options
- mm
- m
- in
- ft

Factory setting m

Calibration mode

Write permission Operators/Service engineers/Expert

Description Select the calibration mode.

Options
- Wet
  Wet calibration takes place by filling and emptying the vessel. In the case of two different levels, the level, volume, mass or percentage value entered is assigned to the pressure measured at this point in time ("Empty calib." and "Full calib." parameters).
- Dry
  Dry calibration is a theoretical calibration. For this calibration, you specify two pressure-level value pairs or height-level value pairs via the following parameters: "Empty calib.", "Empty pressure", "Empty height", "Full calib.", "Full pressure", "Full height".

Factory setting Wet

Empty calib.

Write permission Operators/Service engineers/Expert

Description Enter the output value for the lower calibration point (vessel is empty). The unit defined in "Output unit" must be used.

Note
- In the case of wet calibration, the level (e.g. vessel empty or partially filled) must actually be available. The associated pressure is then automatically recorded by the device.
- In the case of dry calibration, the level (vessel empty) does not have to be available. For the "In pressure" level selection, the associated pressure must be entered in the "Empty pressure" parameter. The associated height must be entered in the "Empty height" parameter for the "In height" level selection.

Factory setting 0.0

Empty pressure

Write permission Operators/Service engineers/Expert

Description Enter the pressure value for the lower calibration point (vessel empty). See also "Empty calib.".

Prerequisite
- "Level selection" = In pressure
- "Calibration mode" = Dry -> entry
- "Calibration mode" = Wet -> display

Factory setting 0.0

Empty height

Write permission Operators/Service engineers/Expert

Description Enter the height value for the lower calibration point (vessel empty). The unit is selected via the "Height unit" parameter.

Prerequisite
- "Level selection" = "In height"
- "Calibration mode" = Dry -> entry
- "Calibration mode" = Wet -> display

Factory setting 0.0

Full calib.

Write permission Operators/Service engineers/Expert

Description Enter the output value for the upper calibration point (vessel full). The unit defined in "Output unit" must be used.

Note
- In the case of wet calibration, the level (e.g. vessel full or partially filled) must actually be available. The associated pressure is then automatically recorded by the device.
- In the case of dry calibration, the level (vessel full) does not have to be available. For the "In pressure" level selection, the associated pressure must be entered in the "Full pressure" parameter. The associated height has to be entered in the "Full height" parameter for the "In height" level selection.

Factory setting 100.0

Full pressure

Write permission Operators/Service engineers/Expert

Description Enter the pressure value for the upper calibration point (vessel full). See also "Full calib.".

Prerequisite
- "Level selection" = In pressure
- "Calibration mode" = Dry -> entry
- "Calibration mode" = Wet -> display

Factory setting URL of the sensor module

Full height

Write permission Operators/Service engineers/Expert

Description Enter the height value for the upper calibration point (vessel full). The unit is selected via the "Height unit" parameter.

Prerequisite
- "Level selection" = "In height"
- "Calibration mode" = Dry -> entry
- "Calibration mode" = Wet -> display

Factory setting URL is converted to a level unit

Density unit

Write permission Service engineers/Expert

Description Displays the density unit. The measured pressure is converted to a height using the "Height unit", "Adjust density" and "Process density" parameters.

Options
- g/cm^3
- kg/m^3
- kg/dm^3
- lb/in^3
- lb/ft^3

Factory setting g/cm^3

Adjust density

Write permission Operators/Service engineers/Expert

Description Enter the density of the medium used to perform the calibration. The measured pressure is converted to a height using the "Height unit" and "Adjust density" parameters.
Input: Auto dens. corr. = Off
Display: Auto dens. corr. ≠ Off

Factory setting 1.0

Process density

Write permission Operators/Service engineers/Expert

Description Enter a new density value for density correction. The calibration was carried out with the medium water, for example. Now the vessel is to be used for another medium with another density. The calibration is corrected appropriately by entering the new density value in the "Process Density" parameter.
Input: Auto dens. corr. = Off
Display: Auto dens. corr. ≠ Off

Note If, after completing a wet calibration, you change to dry calibration using the "Calibration mode" parameter, the density for the "Adjust density" and "Process density" parameters must be entered correctly before changing the calibration mode.

Factory setting 1.0

Level before lin.

Write permission No write permissions. Parameter is read only.

Description Displays the level value prior to linearization.

14.8 Expert → Measurement → Linearization

Lin. mode

Write permission Operators/Service engineers/Expert

Description Select the linearization mode.

Options
- Linear
  The level is output without being converted beforehand. "Level before lin" is output.
- Erase table
  The existing linearization table is deleted.
- Manual entry (sets the table to edit mode, an alarm is output):
  The value pairs of the table (X-value and Y-value) are entered manually.
- Semi-automatic entry (sets the table to edit mode, an alarm is output):
  The vessel is emptied or filled in stages in this entry mode. The device automatically records the level value (X-value). The associated volume, mass or % value is entered manually (Y-value).
- Activate table
  The table entered is activated and checked with this option. The device shows the level after linearization.

Factory setting Linear

Unit after lin.

Write permission Operators/Service engineers/Expert

Description Select volume unit, mass, height or % (unit of the Y-value).

Options
- %
- cm, dm, m, mm
- hl
- in^3, ft^3, m^3,
- l
- in, ft
- kg, t
- lb
- gal
- Igal

Factory setting %

Line-numb

Write permission Operators/Service engineers/Expert

Description Enter the number of the current point in the table. Subsequent entries in "X-val" and "Y-val" relate to this point.

Input range 1...32

X-val

Write permission Operators/Service engineers/Expert

Description Enter the X-value (level before linearization) for the specific point in the table and confirm.

Note
- If "Lin. mode" = "Manual", the level value must be entered.
- If "Lin. mode" = "Semiautomatic", the level value is displayed and must be confirmed by entering the paired Y-value.

Y-value

Write permission Operators/Service engineers/Expert

Description Enter the Y-value (value after linearization) for the specific point in the table. The unit is determined by "Unit after lin.".

Note The linearization table must be monotonic (increasing or decreasing).

Edit table

Write permission Operators/Service engineers/Expert

Description Select the function for entering the table.

Options
- Next point: Enter the next point.
- Current point: stay on the current point to correct a mistake for example.
- Last input point: skip back to previous point to correct a mistake for example.
- Insert point: Insert an additional point (see example below).
- Delete point: Delete the current point (see example below).

Example

Add point, in this case between the 4th and 5th point for example
- Select point 5 via the "Line-numb" parameter.
- Select the "Insert point" option via the "Edit table" parameter.
- Point 5 is displayed for the "Line-numb" parameter. Enter new values for the "X-val" and "Y-val" parameters.

Delete point, in this case the 5th point for example
- Select point 5 via the "Line-numb" parameter.
- Select the "Delete point" option via the "Edit table" parameter.
- The 5th point is deleted. All of the following points are pushed up one number i.e. following deletion, the 6th point becomes Point 5.

Factory setting Current point

Tank description

Write permission Operators/Service engineers/Expert

Description Enter the tank description (max. 32 alphanumeric characters)

Tank content

Write permission No write permissions. Parameter is read only.

Description Displays the level value after linearization.

14.9 Expert → Measurement → Sensor limits

LRL sensor

Write permission No write permissions. Parameter is read only.

Description Displays the lower-range limit of the sensor.

URL sensor

Write permission No write permissions. Parameter is read only.

Description Displays the upper-range limit of the sensor.

14.10 Expert → Measurement → Sensor trim

Lo trim measured

Write permission Parameter is read only. Only Endress+Hauser Service has write permission.

Description Displays the reference pressure present to be accepted for the lower calibration point.

Hi trim measured

Write permission Parameter is read only. Only Endress+Hauser Service has write permission.

Description Displays the reference pressure present to be accepted for the upper calibration point.

Lo trim sensor

Write permission No write permissions. Parameter is read only.

Description Sensor module recalibration by entering a target pressure while simultaneously and automatically accepting a reference pressure present for the lower calibration point.

Hi trim sensor

Write permission No write permissions. Parameter is read only.

Description Sensor module recalibration by entering a target pressure while simultaneously and automatically accepting a reference pressure present for the upper calibration point.

14.11 Expert → Output → Current output

Output current

Write permission Operators/Service engineers/Expert

Description Displays the current current value.

Alarm behav. P

Write permission Operators/Service engineers/Expert

Description Configure the response of the current output if sensor module limits are overshot or undershot.

Options
- Warning
  The device continues to measure. An error message is displayed.
- Alarm
  The output signal assumes a value that can be specified by the "Output fail mode" function.

Factory setting Warning

Output fail mode

Write permission Operators/Service engineers/Expert

Description Select Output fail mode. In the event of an alarm, the current assumes the current value specified with this parameter.

Options
- Max: can be set from 21 to 23 mA, see also "High alarm curr."
- Hold: last measured value is held.
- Min: 3.6 mA

Factory setting Max (22 mA)

Max. alarm curr.

Write permission Operators/Service engineers/Expert

Description Enter the current value for maximum alarm current. See also "Output fail mode".

Input range 21 to 23 mA

Factory setting 22 mA

Set min. current

Write permission Operators/Service engineers/Expert

Description Enter lower current limit.
Some switching units accept no current smaller than 4.0 mA.

Options
- 3.8 mA
- 4.0 mA

Factory setting 3.8 mA

Get LRV

Write permission Operators/Service engineers/Expert

Description Set the lower-range value – reference pressure is present at the device. The pressure for the lower current value (4 mA) is present at the device. Use the "Confirm" option to assign the lower current value to the applied pressure value.

Prerequisite: Pressure measuring mode

Options
- Cancel
- Confirm

Factory setting Cancel

Set LRV

Write permission Operators/Service engineers/Expert

Description Set the pressure value, level or content for the lower current value (4 mA).

Factory setting
- 0.0 % in Level measuring mode
- 0.0 mbar/bar or in accordance with ordering information in Pressure measuring mode

Get URV (pressure measuring mode)

Write permission Operators/Service engineers/Expert

Description Set the upper-range value – reference pressure is present at the device. The pressure for the upper current value (20 mA) is present at the device. Use the "Confirm" option to assign the applied pressure value to the upper current value.

Prerequisite: Pressure measuring mode

Options
- Cancel
- Confirm

Factory setting Cancel

Set URV

Write permission Operators/Service engineers/Expert

Description Set the pressure value, level or content for the upper current value (20 mA).

Factory setting
- 100.0 % in Level measuring mode
- URL Sensor or according to ordering information in Pressure measuring mode

Startcurrent

Write permission Service engineers/Expert

Description Entry of the start current. This setting also applies in the HART Multidrop mode.

Options
- 12 mA
- Max alarm (22 mA, cannot be set)

Factory setting 12 mA

Curr. trim 4mA

Write permission Service engineers/Expert

Description Enter the pressure value for the lower point (4 mA) of the current partial regression lines. Using this parameter and "Curr. trim 20 mA", you can adapt the current output to the transmission conditions.

Options Carry out the current trim for the lower point as follows.
- Select the "Current" option in the "Simulation mode" parameter.
- In the "Sim current" parameter, configure the "4 mA value".
- Enter the current value measured using the switching unit in the "Curr. trim 4mA" parameter.

Input range Measured current ±0.2 mA

Factory setting 4 mA

Curr. trim 20mA

Write permission Service engineers/Expert

Description Enter the pressure value for the upper point (20 mA) of the current partial regression lines. Using this parameter and "Curr. Trim 4 mA", you can adapt the current output to the transmission conditions.

Options Carry out the current trim for the upper point as follows:
- Select the "Current" option in the "Simulation mode" parameter.
- In the "Sim current" parameter, configure the value "20 mA".
- Enter the current value measured using the switching unit in the "Curr. trim 20mA" parameter.

Input range Measured current ±1 mA

Factory setting 20 mA

Offset trim 4mA

Write permission Service engineers/Expert

Description Display/enter the difference between 4 mA and the value entered for the parameter "Curr. trim 4mA".

Factory setting 0

Offset trim 20mA

Write permission Service engineers/Expert

Description Display/enter the difference between 20 mA and the value entered for the parameter "Curr. trim 20mA".

Factory setting 0

14.12 Expert→ Communication → HART config.

Burst mode

Write permission Service engineers/Expert

Description Switching burst mode on and off.

Options
- On
- Off

Factory setting Off

Burst option

Write permission Service engineers/Expert

Description You can use this parameter to define which command is sent to the master.

Options
- 1 (HART command 1)
- 2 (HART command 2)
- 3 (HART command 3)
- 9 (HART command 9)
- 33 (HART command 33)

Factory setting 1 (HART command 1)

Current mode

Write permission Service engineers/Expert

Description Configure current mode for HART communication.

Options
- Signaling
  Measured value transmission by the current value
- Fixed
  Fixed current 4.0 mA (Multidrop mode)
  (Measured value transmission via HART digital communication only)

Factory setting Signaling

Bus address

Write permission Service engineers/Expert

Description Use this function to enter the address via which a data exchange is to take place via HART protocol. (HART 5.0 master: Range 0 to 15, where address = 0 calls up the "Signaling" setting; HART 6.0 master: Range 0 to 63)

Factory setting 0

Preamble number

Write permission Service engineers/Expert

Description Use this function to enter the number of preambles in the HART protocol. (Synchronization of the modem components along a transmission path, each modem component could "swallow" one byte, at least 2 bytes must be the preamble.)

Input range 2...20

Factory setting 5

14.13 Expert→ Communication → HART info

Device type code

Write permission No write permissions. Parameter is read only.

Description Display of the numerical ID of the device
Waterpilot FMX21: 36

Device revision

Write permission No write permissions. Parameter is read only.

Description Display of Device Revision (e.g. 1)

Manufacturer ID

Write permission No write permissions. Parameter is read only.

Description Displays the HART manufacturer ID in a decimal digit format.
Here: 17 (Endress+Hauser)

HART version

Write permission No write permissions. Parameter is read only.

Description Displays HART version .
Waterpilot FMX21: 6

Description

Write permission Service engineers/Expert

Description Enter the tag description (max. 16 alphanumeric characters)

HART message

Write permission Service engineers/Expert

Description Enter the message (max. 32 alphanumeric characters) Upon request from the master, this message is sent via the HART protocol.

HART date

Write permission Service engineers/Expert

Description Enter the date of the last configuration change.

Factory setting DD/MM/YY (date of the final test)

14.14 Expert→ Communication → HART output

Primary value is

Write permission No write permissions. Parameter is read only.

Description Indicates which measured value is transmitted via the HART protocol as the primary process value.

Factory setting Depending on the selected measuring mode, the following measured values can be displayed:
- "Pressure" measuring mode: "Meas. pressure"
- "Level" measuring mode, Lin. mode "Linear": "Level before Lin"
- "Level" measuring mode, Lin. mode "Activate table": "Tank content"

Primary value

Write permission No write permissions. Parameter is read only.

Description The primary value is displayed.

Secondary val.is

Write permission No write permissions. Parameter is read only.

Description Indicates which measured value is transmitted via the HART protocol as the secondary process value. The process value is configured via HART command 51.

Factory setting
- "Pressure" measuring mode: "Corrected press."
- "Level" measuring mode, "Linear" lin. mode: "Meas. pressure"
- "Level" measuring mode, Lin. mode "Activate table": "Level before linearization"

Display Depending on the selected measuring mode, the following measured values can be displayed:
- "Meas. pressure"
- "Sensor pressure"
- "Corrected press."
- "Pressure af.damp"
- "Sensor temp."
- "Level before Lin"
- "Tank content"
- "Process density" (corrected)

Secondary value

Write permission No write permissions. Parameter is read only.

Description The secondary value is displayed.

Third value is

Write permission No write permissions. Parameter is read only.

Description Indicates which measured value is transmitted via the HART protocol as the third process value. The process value is configured via HART command 51.

Factory setting
- "Pressure" measuring mode: "Sensor pressure"
- "Level" measuring mode, "Linear" lin. mode: "Corrected press."
- "Level" measuring mode, "Activate table" lin. mode: "Meas. pressure"

Display Depending on the selected measuring mode, the following measured values can be displayed:
- "Meas. pressure"
- "Sensor pressure"
- "Corrected press."
- "Pressure af.damp"
- "Sensor temp."
- "Level before Lin"
- "Tank content"
- "Process density" (corrected)

Third value is

Write permission No write permissions. Parameter is read only.

Description The third value is displayed.

4th value is

Write permission No write permissions. Parameter is read only.

Description Indicates which measured value is transmitted via the HART protocol as the fourth process value. The process value is configured via HART command 51.

Factory setting
- "Pressure" measuring mode: "Sensor temp"
- "Level" measuring mode, "Linear" lin. mode: "Sensor temp."
- "Level" measuring mode, "Activate table" lin. mode: "Sensor temp."

Display Depending on the selected measuring mode, the following measured values can be displayed:

- "Meas. pressure"
- "Sensor pressure"
- "Corrected press."
- "Pressure af.damp"
- "Sensor temp."
- "Level before Lin"
- "Tank content"
- "Process density" (corrected)

4th value

Write permission No write permissions. Parameter is read only.

Description The fourth value is displayed.

14.15 Expert→ Communication → HART input

HART input value

Write permission No write permissions. Parameter is read only.

Description Display of the HART input value

HART input stat.

Write permission No write permissions. Parameter is read only.

Description Display of the HART input status
Bad / Uncertain / Good

HART input unit

Write permission No write permissions. Parameter is read only.

Description Display of the unit for the HART input value.

Display
- Unknown
- mbar, bar
- mmH2O, ftH2O, inH2O
- Pa, hPa, kPa, MPa
- psi
- mmHg, inHg
- Torr
- g/cm^2, kg/cm^2
- lb/ft^2
- atm
- ˚C, ˚F, K, R

Factory setting Unknown

HART input form.

Write permission Operators/Service engineers/Expert

Description Number of decimal places of the displayed input value.

Options

- x.x
- x.xx
- x.xxx
- x.xxxx
- x.xxxxx

Factory setting

x.x

14.16 Expert → Application

Electr. Delta P

Write permission Operators/Service engineers/Expert

Description For switching the Electr. Delta P application off or on with an external or constant value.

Options
- Off
- External value
- Constant

Factory setting Off

Fixed ext. value

Write permission Operators/Service engineers/Expert

Description Use this function to enter the constant value. The value refers to "HART input unit"

Factory setting 0.0

Auto dens. corr.

Write permission Operators/Service engineers/Expert

Description For switching the auto dens. corr. application off or on with an external or internal temperature value.
Before performing a calibration (dry or wet), auto-density compensation must be switched on if this function is to be used. As soon as "Auto dens. corr." is switched on, the field for entering the "Process density" and "Adjust density" is disabled.
The calibration density remains the last value until it is overwritten by a calibration. The process density remains the last value until it is overwritten when the system recalculates the value.
Automatic density compensation is performed for the 0 to 70 °C (32 to 158 °F) temperature range. The density values for water are used for this density compensation.

Prerequisite Level mode

Options
- Off
- Sensor temperature
- External value (only if Off or Constant is selected for Electr. Delta P)

Factory setting
- Off
- On (if the option "IC" was selected in the "Service" order code when ordering)

14.17 Expert → Diagnosis

Diagnostic code

Write permission No write permissions. Parameter is read only.

Description Displays the diagnostic message with the highest priority currently present.

Last diag. code

Write permission No write permissions. Parameter is read only.

Description Displays the last diagnostic message that occurred and was rectified.

Note
- Digital communication: the last message is displayed.
- Use the "Reset logbook" parameter to clear the messages listed in the parameter "Last diag. code".

Reset logbook

Write permission Service engineers/Expert

Description Use this parameter to reset all messages of the parameter "Last diag. code" and the event logbook "Last diag. 1" to "Last diag. 10".

Options
- Cancel
- Confirm

Factory setting Cancel

Min. meas. press.

Write permission No write permissions. Parameter is read only.

Description Displays the lowest pressure value measured (peakhold indicator). You can reset this indicator by means of the "Reset peakhold" parameter.

Max. meas. press.

Write permission No write permissions. Parameter is read only.

Description Displays the highest pressure value measured (peakhold indicator). You can reset this indicator by means of the "Reset peakhold" parameter.

Reset peakhold

Write permission Service engineers/Expert

Description You can reset the "Min. meas. press." and "Max. meas. press." indicators with this parameter.

Options
- Cancel
- Confirm

Factory setting Cancel

Operating hours

Write permission No write permissions. Parameter is read only.

Description Displays the hours of operation. This parameter cannot be reset.

Config. counter

Write permission Operators/Service engineers/Expert

Description Displays the configuration counter.
This counter is increased by one every time a parameter or group is changed. The counter counts up to 65535 and then starts again at zero.

14.18 Expert → Diagnosis → Diagnostic list

Diagnostic 1 (075)
Diagnostic 2 (076)
Diagnostic 3 (077)
Diagnostic 4 (078)
Diagnostic 5 (079)
Diagnostic 6 (080)
Diagnostic 7 (081)
Diagnostic 8 (082)
Diagnostic 9 (083)
Diagnostic 10 (084)

Write permission No write permissions. Parameter is read only.

Description This parameter contains up to ten diagnosis messages that are currently pending, arranged in order of priority.

14.19 Expert → Diagnosis→ Event logbook

Last diag. 1 (085)
Last diag. 2 (086)
Last diag. 3 (087)
Last diag. 4 (088)
Last diag. 5 (089)
Last diag. 6 (090)
Last diag. 7 (091)
Last diag. 8 (092)
Last diag. 9 (093)
Last diag. 10 (094)

Write permission
No write permissions. Parameter is read only.

Description
This parameter contains the last 10 diagnosis messages to occur and be rectified. They can be reset using the "Reset logbook" parameter.
Errors which have occurred multiple times are displayed once only.
Errors may also appear multiple times if another error has occurred in the meantime. The messages are displayed in chronological order.

14.20 Expert → Diagnosis → Simulation

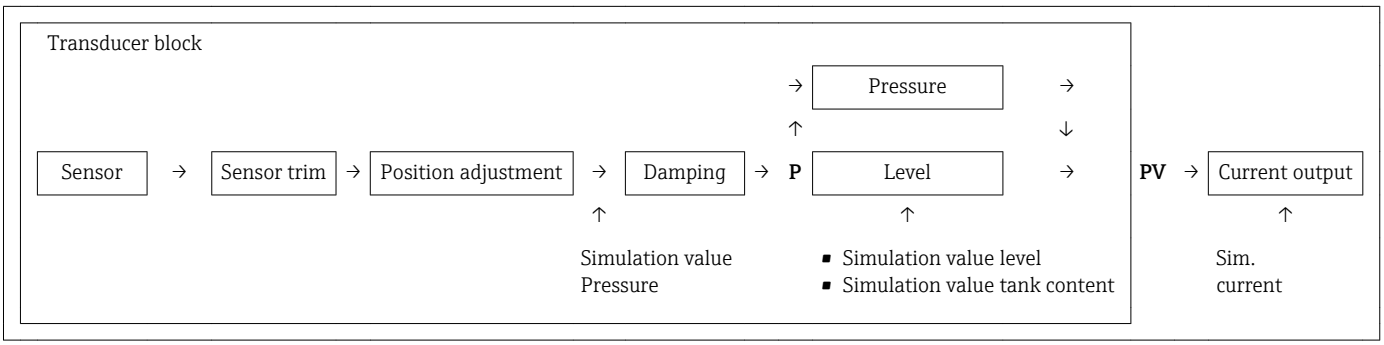
Simulation mode

Write permission Operators/Service engineers/Expert

Description Switch on simulation and select the simulation mode. When changing the measuring mode or the "Lin. mode" level type or when the device is restarted, any simulation that may be running is switched off.

Options
- None
- Pressure →see this table, "Sim. pressure" parameter
- Level, → see this table, "Sim. level" parameter
- Tank content, → see this table, "Sim. tank cont." parameter
- Current, → see this table, "Sim. current" parameter
- Alarm/warning, → see this table, "Sim. error no."

Factory setting None



Sim. pressure

Write permission Operators/Service engineers/Expert

Description Enter the simulation value. See also "Simulation mode".

Prerequisite "Simulation mode" = Pressure

Value at switch-on Current pressure measured value

Sim. level

Write permission Operators/Service engineers/Expert

Description Enter the simulation value. See also "Simulation mode".

Prerequisite "Measuring mode" = Level and "Simulation mode" = Level

Value at switch-on Current level measured value

Sim. tank cont.

Write permission Operators/Service engineers/Expert

Description Enter the simulation value. See also "Simulation mode".

Prerequisite "Measuring Mode" = level, Lin mode "Activate table" and "Simulation Mode" = Tank content

Value at switch-on Current tank content

Sim. current

Write permission Operators/Service engineers/Expert

Description Enter the simulation value. See also "Simulation mode".

Prerequisite "Simulation Mode" = Current value

Value at switch-on Current current value

Sim. alarm/warning

Write permission Operators/Service engineers/Expert

Description Enter the simulation value. See also "Simulation mode".

Prerequisite "Simulation Mode" = Alarm/Warning

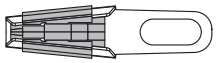
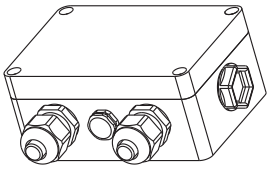
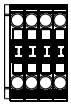
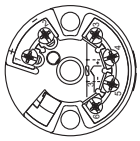
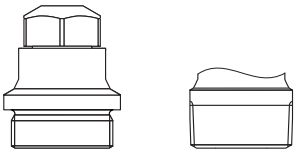
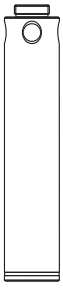
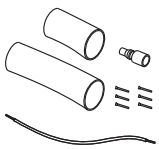
Factory setting: 484 (Simulation active)

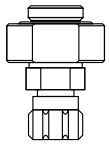
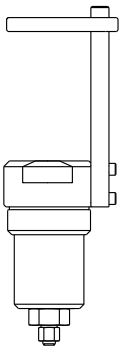
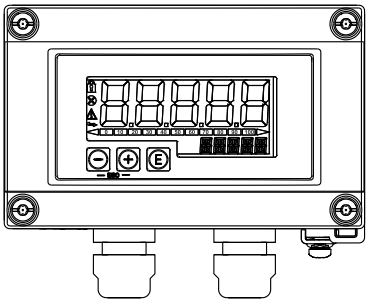
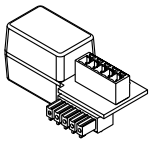
15 Accessories

⚠ CAUTION

Observe the additional information in the individual sections!

- For additional information, see the sections "Mechanical construction" (in Technical Information TI00431P), "Environment", → 134, "Process" → 136 and "Installation" → 18.

Designation	Diagram	Description	Order number / ordering information
Suspension clamp	 A0030950	For easy installation of the FMX21, Endress+Hauser offers a mounting clamp .	▪ 52006151 ▪ Product Configurator order code for "Accessory enclosed", option "PO"
Terminal box	 A0030967	Terminal box for terminal strip, temperature head transmitter and Pt100.	▪ 52006152 ▪ Product Configurator order code for "Accessories enclosed", option "PS"
4-terminal strip/terminals	 A0030951	4-terminal strip for wiring	52008938
TMT182 temperature head transmitter for FMX21 4 to 20 mA HART	 A0030952	PC-programmable (PCP) temperature head transmitter for the conversion of various input signals	▪ 51001023 ▪ Product Configurator order code for "Accessories enclosed", option "PT"
Cable mounting screws	A B  A0030953 *A G 1½" A* *B NPT 1½"*	Endress+Hauser offers a cable mounting screw for easy FMX21 mounting and to seal the measuring aperture.	▪ G 1½" A – 52008264 – Product Configurator order code for "Accessories enclosed", option "PQ" ▪ NPT 1½" – 52009311 – Product Configurator order code for "Accessories enclosed", option "PR"
Additional weight for FMX21 with outer diameter 22 mm (0.87 in) or 29 mm (1.14 in)	 A0030954	Endress+Hauser offers additional weights to prevent sideways movement that results in measuring errors, or to make it easier to lower the device in a guide tube.	▪ 52006153 ▪ Product Configurator order code for "Accessories enclosed", option "PU"
Cable shortening kit	 A0030948	The cable shortening kit is used to shorten a cable easily and professionally.	▪ 71222671 ▪ Product Configurator order code for "Accessories enclosed", option "PW"

Designation	Diagram	Description	Order number / ordering information
Testing adapter for FMX21 with outer diameter 22 mm (0.87 in) or 29 mm (1.14 in)	 A0030956	Endress+Hauser offers a testing adapter to ease function-testing of the level probes.	▪ 52011868 ▪ Product Configurator order code for "Accessories enclosed", option "PV"
Testing adapter for FMX21 with outer diameter 42 mm (1.65 in)	 A0030957	Endress+Hauser offers a testing adapter to ease function-testing of the level probes. ▪ Observe the maximum pressure for compressed air hose and maximum overload for level probe ▪ Maximum pressure for the quick coupling piece provided: 10 bar (145 psi)	71110310
RIA15 in the field housing	 A0036164	Remote display RIA15 non-hazardous	Product structure, feature 620 "Accessory enclosed", option R4 "Remote display RIA15 non-hazardous area, field housing"
		Remote display RIA15 hazardous	Product structure, feature 620 "Accessory enclosed", option R5 "Remote display RIA15 Ex= explosion protection approval, field housing"
HART communication resistor	 A0036165	HART communication resistor, hazardous / non-hazardous area, for use with RIA15	Product structure, feature 620 "Accessory enclosed", option R6 "HART communication resistor hazardous / non-hazardous area"

15.1 Service-specific accessories

Accessories	Description
DeviceCare SFE100	Configuration tool for HART, PROFIBUS and FOUNDATION Fieldbus field devices Technical Information TI01134S DeviceCare is available for download at www.software-products.endress.com. You need to register in the Endress+Hauser software portal to download the application.
FieldCare SFE500	FDT-based plant asset management tool FieldCare can configure all smart field units in your plant and helps you manage them. By using the status information, FieldCare is also a simple but effective way of checking the status and condition of the field devices. Technical Information TI00028S

16 Technical data

16.1 Input

16.1.1 Measured variable

FMX21 + Pt100 (optional)

- Hydrostatic pressure of a liquid
- Pt100: Temperature

TMT182 temperature head transmitter (optional) for FMX21 4 to 20 mA HART

Temperature

16.1.2 Measuring range

- Customer-specific measuring ranges or calibration that has been preset in the factory
- Temperature measurement of −10 to +70 °C (+14 to +158 °F) with Pt100 (optional)

Relative pressure

Sensor measuring range [bar (psi)]	Lowest calibratable span [1] [bar (psi)]	Vacuum resistance [bar_{abs} (psi_{abs})]	Option [2]
0.1 (1.5)	0.01 (0.15)	0.3 (4.5)	1C
0.2 (3.0)	0.02 (0.3)	0.3 (4.5)	1D
0.4 (6.0)	0.04 (1.0)	0	1F
0.6 (9.0)	0.06 (1.0)	0	1G
1.0 (15.0)	0.1 (1.5)	0	1H
2.0 (30.0)	0.2 (3.0)	0	1K
4.0 (60.0)	0.4 (6.0)	0	1M
10.0 (150) [3]	1.0 (15)	0	1P
20.0 (300) [3]	2.0 (30)	0	1Q

1) Largest turn down that can be configured at the factory: 10:1, higher turn down can be configured on request or in the device (for FMX21 4 to 20 mA HART).
2) Product Configurator order code for "Sensor range"
3) These measuring ranges are not available for the special version with plastic insulation, external diameter of 29 mm (1.14 in).

Absolute pressure

Sensor measuring range [bar (psi)]	Lowest calibratable span [1] [bar (psi)]	Vacuum resistance [bar_{abs} (psi_{abs})]	Option [2]
2.0 (30.0)	0.2 (3.0)	0	2K
4.0 (60.0)	0.4 (6.0)	0	2M

Sensor measuring range [bar (psi)]	Lowest calibratable span [1] [bar (psi)]	Vacuum resistance [bar_{abs} (psi_{abs})]	Option [2]
10.0 (150) [3]	1.0 (15)	0	2P
20.0 (300) [3]	2.0 (30)	0	2Q

1) Largest turn down that can be configured at the factory: 10:1, higher turn down can be configured on request or in the device (for FMX21 4 to 20 mA HART).
2) Product Configurator order code for "Sensor range"
3) These measuring ranges are not available for the special version with plastic insulation, external diameter of 29 mm (1.14 in).

16.1.3 Input signal

FMX21 + Pt100 (optional)

- Change in capacitance
- Pt100: Change in resistance

TMT182 temperature head transmitter (optional) for FMX21 4 to 20 mA HART

Pt100 resistance signal, 4 wire

16.2 Output

16.2.1 Output signal

FMX21 + Pt100 (optional)

- 4 to 20 mA HART with superimposed digital communication protocol HART 6.0, 2-wire for hydrostatic pressure measured value.
  Ordering information: Product Configurator order code for "Output", option "2"
  Options:
  – Max. alarm (factory setting 22mA): can be set from 21 to 23 mA
  – Hold measured value: last measured value is held
  – Min. alarm: 3.6 mA
- Pt100: temperature-dependent resistance value

TMT182 temperature head transmitter (optional) for FMX21 4 to 20 mA HART

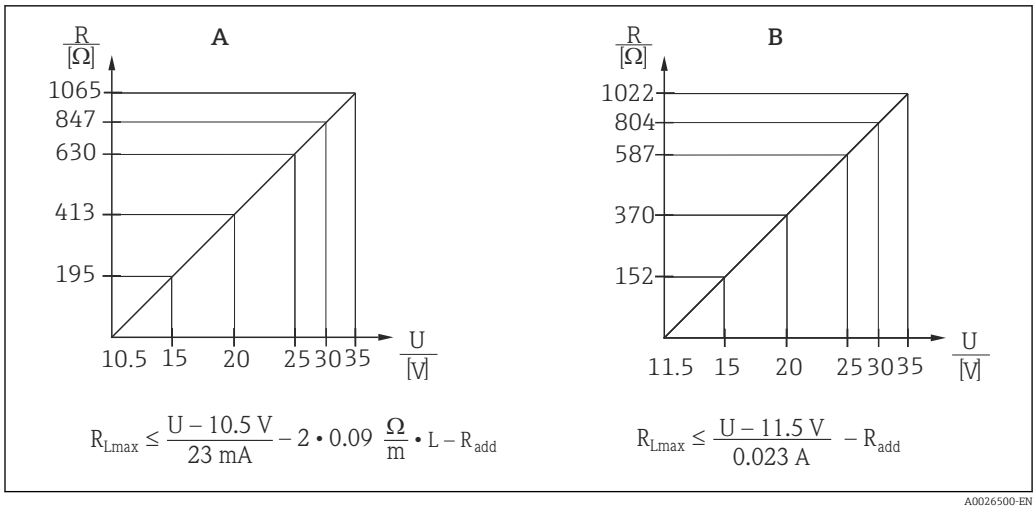
4 to 20 mA HART with superimposed digital communication protocol HART 5.0 for temperature measured value, 2-wire

16.2.2 Signal range

3.8 mA to 20.5 mA

16.2.3 Maximum load for FMX21 4 to 20 mA HART

The maximum load resistance depends on the supply voltage (U) and must be determined individually for each current loop, see formula and diagrams for FMX21 and temperature head transmitter. The total resistance resulting from the resistances of the connected devices, the connecting cable and, where applicable, the resistance of the extension cable may not exceed the load resistance value.



A FMX21 4 to 20 mA HART load chart for estimating the load resistance. Additional resistances, such as the resistance of the extension cable, have to be subtracted from the value calculated as shown in the equation.

B Load diagram for TMT182 temperature head transmitter for estimating the load resistance. Additional resistances must be subtracted from the value calculated as shown in the equation

R_{Lmax} *Max. load resistance [Ω]*

R_{add} *Additional resistances such as resistance of evaluating device and/or display unit, cable resistance [Ω]*

U Supply voltage [V]

L Basic length of extension cable [m] (cable resistance per wire 0.09 Ω/m)

- When using the measuring device in hazardous areas, installation must comply with the corresponding national standards and regulations and the Safety Instructions or Installation or Control Drawings (XA).
- When operating via a handheld terminal or via a PC with an operating program, a minimum communication resistance of 250 Ω must be taken into account.

16.2.4 Protocol-specific data for FMX21 4 to 20 mA HART

Manufacturer ID	17 (11 hex)
Device type code	25 (19 hex)
Device revision	01 (01 hex) - SW version 01.00.zz
HART specification	6
DD revision	01
Device description files (DTM, DD)	Information and files under: ▪ www.endress.com ▪ www.fieldcommgroup.org
HART load	Min. 250 Ω
HART device variables	The dynamic variables SV, TV and QV may be assigned to any device variable: **Standard process values for SV, TV (second and third device variable) are dependent on the measuring mode:** ▪ Pressure ▪ Level **Standard process value for QV (fourth device variable) is the sensor temperature:** Temperature **Measured values for PV (first device variable) are dependent on the measuring mode:** ▪ Pressure ▪ Level ▪ Tank content
Supported functions	▪ Burst mode ▪ Additional transmitter status ▪ Device locking ▪ Alternative measuring modes ▪ Catch variable ▪ Long tag

16.3 Performance characteristics

16.3.1 Reference operating conditions

FMX21 + Pt100 (optional)

- As per IEC 60770
- Ambient temperature T_U = constant, in the range of +21 to +33 °C (+70 to +91 °F)
- Humidity φ = constant, in the range of 20 to 80 % rH
- Ambient pressure p_U = constant, in the range of 860 to 1060 mbar (12.47 to 15.37 psi)
- Position of measuring cell constant, vertical in the range of ±1°
- Input of LOW SENSOR TRIM and HIGH SENSOR TRIM for lower range value and upper range value (only for HART)
- Supply voltage constant: 21 V DC to 27 V DC
- Load with HART: 250 Ω
- Pt100: DIN EN 60770, T_U = +25 °C (+77 °F)

TMT182 temperature head transmitter (optional) for FMX21 4 to 20 mA HART

Calibration temperature +25 °C (+77 °F) ±5 K

16.3.2 Reference accuracy

FMX21 + Pt100 (optional)

The reference accuracy comprises the non-linearity after limit point configuration, hysteresis and non-reproducibility in accordance IEC 60770.

Standard version [2]:
Setting ±0.2 %
– to TD 5:1: < 0.2 % of set span
– from TD 5:1 to TD 20:1 ±(0.02 x TD+0.1)

Platinum version [3]:
- Setting ±0.1 % (optional)
  – to TD 5:1: < 0.1 % of set span
  – from TD 5:1 to TD 20:1 ±(0.02 x TD)
- Class B as per DIN EN 60751
  Pt100: max. ±1 K

TMT182 temperature head transmitter (optional) for FMX21 4 to 20 mA HART

- ±0.2 K
- With Pt100: max. ±0.9 K

16.3.3 Resolution

Current output: 1 µA

Reading cycle

HART commands: on average 2 to 3 per second

2) Ordering information: Product Configurator order code for "Reference accuracy", option "G"
3) Ordering information: Product Configurator order code for "Reference accuracy", option "D"

16.3.4 Long-term stability

FMX21 + Pt100 (optional)

- ≤ 0.1 % of URL/year
- ≤ 0.25 % of URL/5 years

TMT182 temperature head transmitter (optional) for FMX21 4 to 20 mA HART

≤ 0.1 K per year

16.3.5 Influence of medium temperature

- Thermal change in the zero output and the output span:
  0 to +30 °C (+32 to +86 °F): < (0.15 + 0.15 x TD)% of set span
  −10 to +70 °C (+14 to +158 °F): < (0.4 + 0.4 x TD)% of set span
- Temperature coefficient (T_K) of the zero output and the output span
  −10 to +70 °C (+14 to +158 °F): 0.1 % / 10 K of URL

16.3.6 Warm-up period

FMX21 + Pt100 (optional)

- FMX21: < 6 s
- Pt100: 300 s

TMT182 temperature head transmitter (optional) for FMX21 4 to 20 mA HART

4 s

16.3.7 Response time

FMX21 + Pt100 (optional)

- FMX21: 400 ms (T90 time), 500 ms (T99 time)
- Pt100: 160 s (T90 time), 300 s (T99 time)

16.4 Environment

16.4.1 Ambient temperature range

FMX21 + Pt100 (optional)

- With external diameter of 22 mm (0.87 in) and 42 mm (1.65 in):
  −10 to +70 °C (+14 to +158 °F) (= medium temperature)
- With external diameter of29 mm (1.14 in):
  0 to +50 °C (+32 to +122 °F) (= medium temperature)

Cable

(when mounted in a fixed position)
- With PE: −30 to +70 °C (−22 to +158 °F)
- With FEP: −40 to +70 °C (−40 to +158 °F)
- With PUR: −40 to +70 °C (−40 to +158 °F)

Terminal box

−40 to +80 °C (−40 to +176 °F)

TMT182 temperature head transmitter (optional) for FMX21 4 to 20 mA HART

−40 to +85 °C (−40 to +185 °F)

Temperature head transmitter 2-wire, configured for a measuring range of −20 to +80 °C (−4 to +176 °F). This configuration offers a temperature range of 100 K which can be easily mapped. Please note that the Pt100 resistance temperature detector is suitable for a temperature range of −10 to +70 °C (14 to +158 °F)

The TMT182 temperature head transmitter is not designed for use in hazardous areas incl. CSA GP.

16.4.2 Storage temperature range

FMX21 + Pt100 (optional)

−40 to +80 °C (−40 to +176 °F)

Cable

(when mounted in a fixed position)
- With PE: −30 to +70 °C (−22 to +158 °F)
- With FEP: −30 to +80 °C (−22 to +176 °F)
- With PUR: −40 to +80 °C (−40 to +176 °F)

Terminal box

−40 to +80 °C (−40 to +176 °F)

TMT182 temperature head transmitter (optional) for FMX21 4 to 20 mA HART

−40 to +100 °C (−40 to +212 °F)

16.4.3 Degree of protection

FMX21 + Pt100 (optional)

IP68, permanently hermetically sealed at 20 bar (290 psi) (~200 m H_2O)

Terminal box (optional)

IP66, IP67

TMT182 temperature head transmitter (optional) for FMX21 4 to 20 mA HART

IP00, condensation permitted

16.4.4 Electromagnetic compatibility (EMC)

FMX21 + Pt100 (optional)

- EMC in accordance with all relevant requirements of EN 61326 series. For details, refer to the Declaration of Conformity.
- Maximum deviation: < 0.5 % of span.

TMT182 temperature head transmitter (optional) for FMX21 4 to 20 mA HART

EMC in accordance with all relevant requirements of EN 61326 series. For details, refer to the Declaration of Conformity.

16.4.5 Overvoltage protection

FMX21 + Pt100 (optional)

- Integrated overvoltage protection as per EN 61000-4-5 (500 V symmetrical/1000 V asymmetrical)
- Overvoltage protection ≥ 1.0 kV, external if necessary

TMT182 temperature head transmitter (optional) for FMX21 4 to 20 mA HART

Provide overvoltage protection, externally if necessary (see Technical Information).

16.5 Process

16.5.1 Medium temperature range

FMX21 + Pt100 (optional)

- With external diameter of 22 mm (0.87 in) and 42 mm (1.65 in):
  −10 to +70 °C (+14 to +158 °F)
- With external diameter of 29 mm (1.14 in):
  0 to +50 °C (+32 to +122 °F)

TMT181 temperature head transmitter (optional) for FMX21 4 to 20 mA HART

−40 to +85 °C (−40 to +185 °F)

(= ambient temperature), install temperature head transmitter outside the medium.

Temperature head transmitter 2-wire, configured for a measuring range of −20 to +80 °C (−4 to +176 °F). This configuration offers a temperature range of 100 K which can be easily mapped. Please note that the Pt100 resistance temperature detector is suitable for a temperature range of −10 to +70 °C (14 to +158 °F)

The TMT182 temperature head transmitter is not designed for use in hazardous areas incl. CSA GP.

16.5.2 Medium temperature limit

FMX21 + Pt100 (optional)

With external diameter of 22 mm (0.87 in) and 42 mm (1.65 in):
−20 to +70 °C (−4 to +158 °F)

In hazardous areas incl. CSA GP, the medium temperature limit is −10 to +70 °C (+14 to +158 °F).

With external diameter of29 mm (1.14 in): 0 to +50 °C (+32 to +122 °F)

The FMX21 may be operated in this temperature range. The specification values, such as accuracy, may be exceeded.

16.5.3 Pressure specifications

⚠ WARNING

The maximum pressure for the measuring device depends on the lowest-rated element with regard to pressure.

- For pressure specifications, see the "Measuring range" section and the "Mechanical construction" section.
- The measuring device must be operated only within the specified limits!
- The Pressure Equipment Directive (2014/68/EU) uses the abbreviation "PS". The abbreviation "PS" corresponds to the MWP (maximum working pressure) of the measuring device.
- MWP (maximum working pressure): The MWP (maximum working pressure) is specified on the nameplate. This value refers to a reference temperature of +20 °C (+68 °F) and may be applied to the device for an unlimited time. Observe temperature dependency of the MWP.
- OPL (Over Pressure Limit = sensor overload limit): The test pressure corresponds to the over pressure limit of the sensor and may only be applied for a limited time period to ensure measurement within specification and in order to avoid permanent damage. In the case of sensor range and process connections where the over pressure limit (OPL) of the process connection is smaller than the nominal value of the sensor, the device is set at the factory, at the very maximum, to the OPL value of the process connection. If you want to use the entire sensor range, select a process connection with a higher OPL value.
- avoid steam hammering! Steam hammering can cause zero point drifts. Recommendation: Residue (such as condensation or drops of water) can remain on the process isolating diaphragm after CIP cleaning and lead to local steam hammering if steam cleaning is performed again. In practice, drying the process isolating diaphragm (e.g. by blowing) has proved to prevent steam hammering.

16.6 Additional technical data

See Technical Information TI00431P.

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